

A Data-Driven Extrapolation Technique for the DUNE-PRISM Oscillation Analysis

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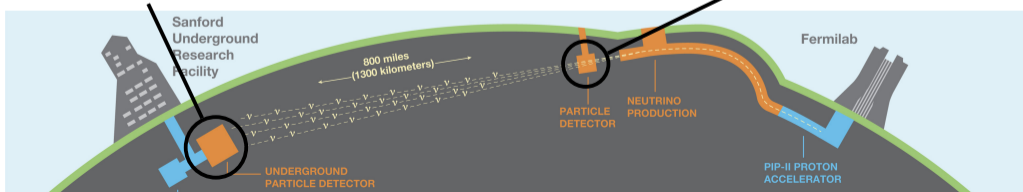
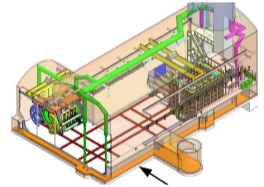
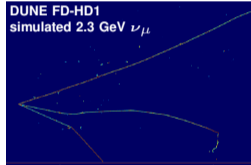
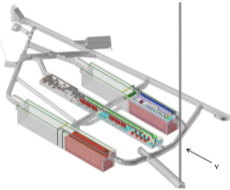
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DUNE Oscillation Analysis

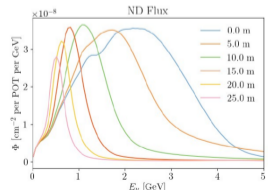
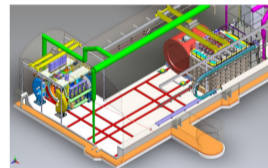
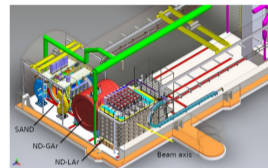
$$N_\nu(E_{rec}) = \int dE_\nu \underbrace{P_{osc}(E_\nu, L; \theta)}_{\text{Far Detector fits for oscillation probability}} \times \underbrace{\Phi(E_\nu) \times \sigma_{\nu\text{-Ar}}(E_\nu)}_{\text{Near Detector constrains flux \& cross section model params}} \times \mathbf{D}(E_\nu, E_{rec})$$

Far Detector fits for oscillation probability

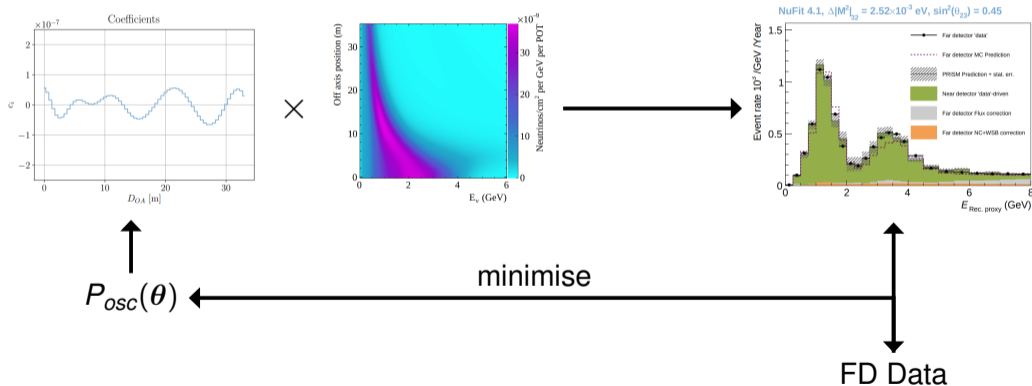
Near Detector constrains flux & cross section model params



- ▶ Constraining neutrino-nucleus interaction model parameters using ND can introduce bias if the model is not correct
 - Reconstructed energy depends on the final state of the ν -Ar interaction, so model needs to be correct for exclusive cross sections too - really hard!
- ▶ The Precision Reaction Independent Spectrum Measurement (PRISM) technique can help
 - The ND moves perpendicular to the neutrino beam ("off-axis") up to 30m
 - Beam energy spectrum changes with off-axis position
- ▶ Sampling many energy spectra provides strong verification on the cross section model adjustments used to make ND MC match data
 - Harder to introduce bias with a bad model correction

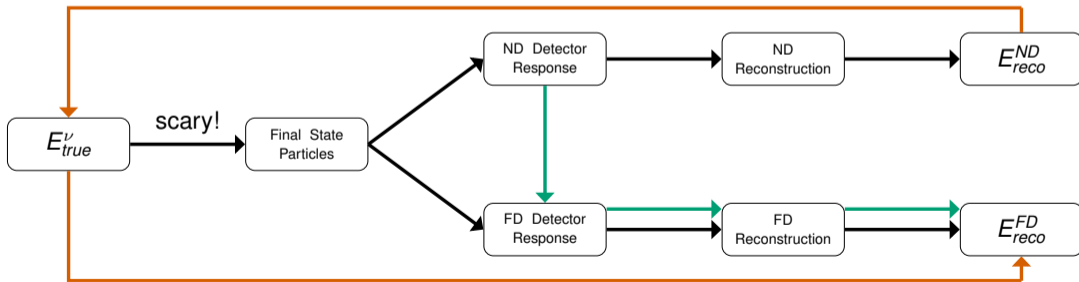


- ▶ PRISM enables an oscillation analysis that compares ND data to FD data directly through linear combination of off-axis fluxes
- Any unknown cross section effects get directly incorporated into a FD spectrum prediction



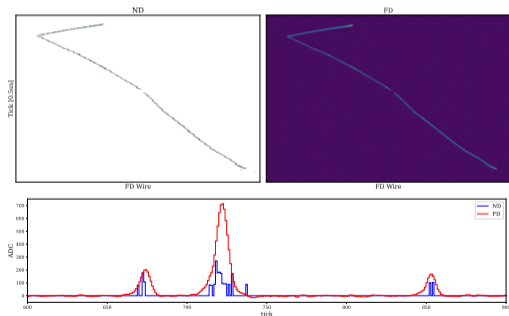
Near to Far Detector Extrapolation

- ▶ Completing the extrapolation of off-axis ND measurements to the FD requires correcting different detector effects
 - Using MC response matrices to **unfold and smear** introduces interaction model dependence
 - Directly **translating detector response** from ND to FD would be much better

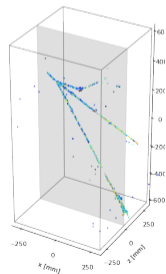


Translating from Near to Far Detector

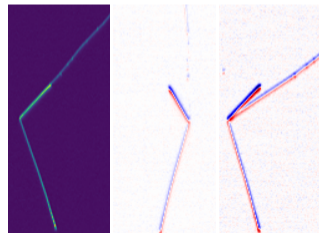
- ▶ Apply machine learning to translate ND response to the equivalent FD response
- ▶ Focus on the primary difference between detectors — charge readout
 - Single 3d view from self-triggering pixel planes vs multiple 2d views from wire planes
- ▶ Generate a paired dataset by simulating the same charge depositions at both detectors



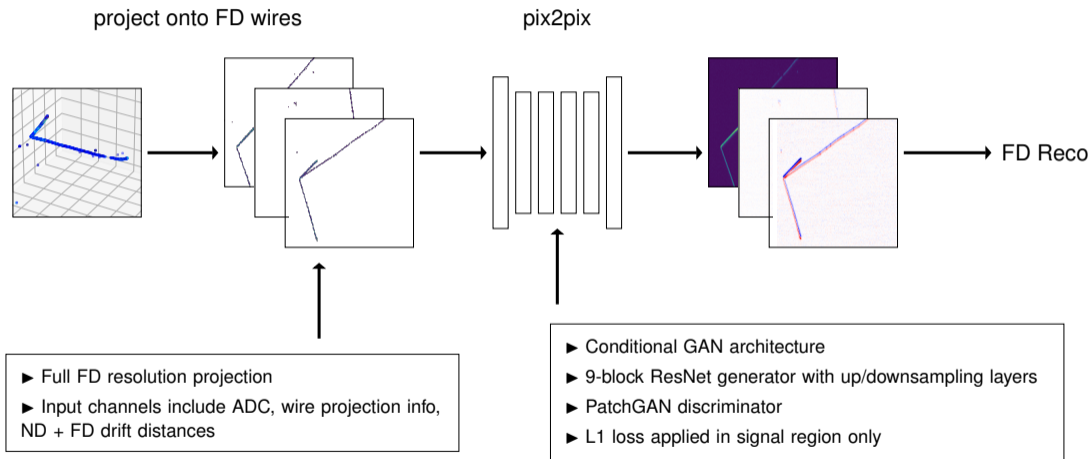
Near Detector



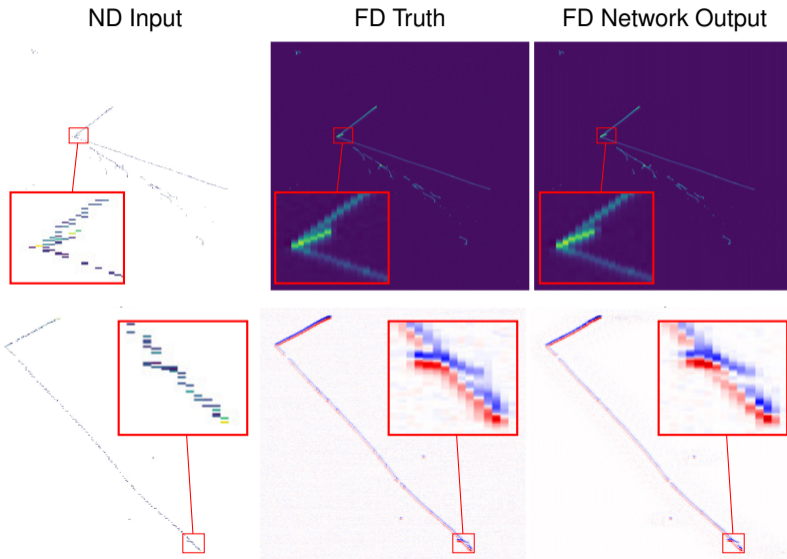
Far Detector



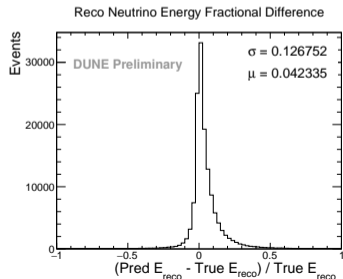
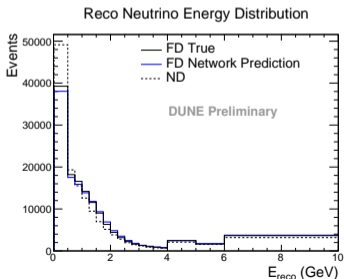
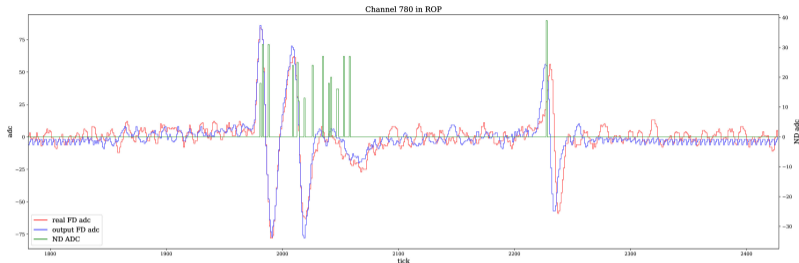
Translation with pix2pix



Results - Image Translation



Results - Wire Trace and Reco



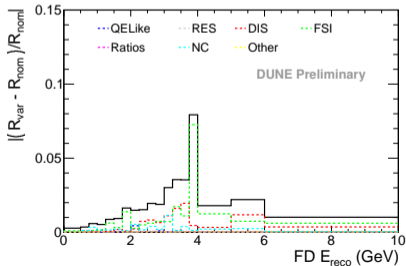
Cross Section Systematics

- ▶ Study interaction model dependence of extrapolation method using cross section systematic event reweights
- ▶ Look at the ratio of predicted FD spectrum with true FD spectrum under reweights
→ No change in ratio after reweight means no interaction model dependence is introduced by extrapolation

ML Translation



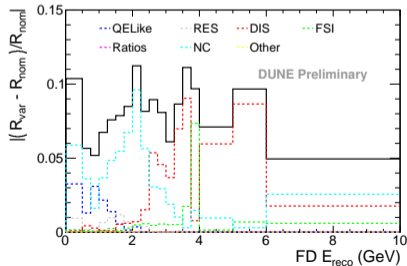
Network Pred+Smear/True variation from all xsec dials (2σ)



Unfold + Smear



Unfold+Smear/True variation from all xsec dials (2σ)

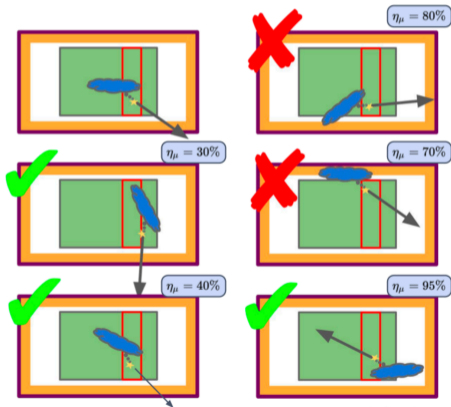


- ▶ PRISM capability of near detector enables an oscillation analysis that is largely independent of cross section modelling by making FD predictions directly from ND data
 - Detector effects correction can compromise this
- ▶ Machine learning is applied to correct for detector effects by translating detector response
 - Accurate prediction of FD response
 - Robust to mismodelling of cross sections
- ▶ Working on extending model to correct for all ND-FD differences
 - Different detector dead regions
 - Muon spectrometer ND component

Backup

Geometric Efficiency Correction

- ▶ Correct each event by combining leptonic and hadronic efficiency factors for each throw and averaging over all throws

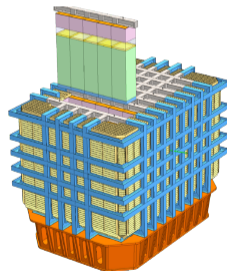
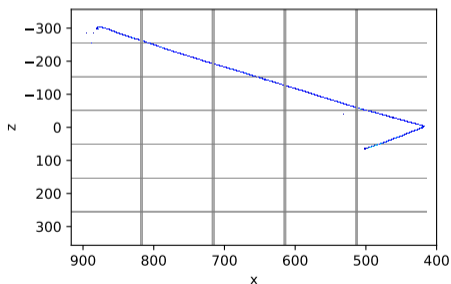


L. Pickering

$$\eta = \frac{0 \times 0.8 + 1 \times 0.3 + 0 \times 0.7 + 1 \times 0.4 + 1 \times 0.95}{5} = 0.33$$

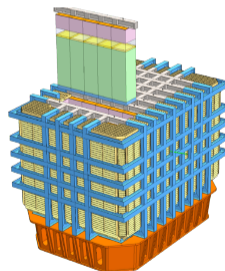
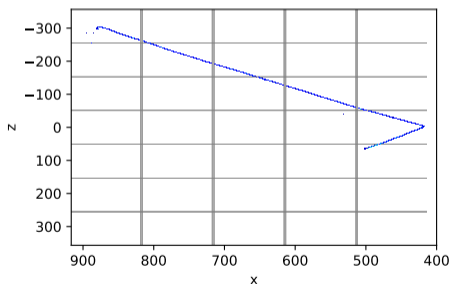
→ reweight event by $\frac{1}{0.33}$

- ▶ Need to predict FD detector response in the non-active ND regions between drift modules to correctly translate
- ▶ Difficult to do this after wire projections since positions of gaps are not well defined in this projection
- ▶ Attempt to infill gaps between drift modules at the 3D pixel response level



Dead Region Infill

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Dead Region Infill

