The LCG Software and the ROOT Framework

LCG seminar

CERN- 7 November

René Brun

`ftp://root.cern.ch/root/lcgtalk.ppt`

Plan of talk

- General considerations
- ROOT status & plans
  - what we presented at the Blueprint RTAG
  - required developments
  - modularity issues
- Relations with LCG
  - Where we agree
  - Possible problems
  - Scenario 1, 2, 3

General Considerations

Some time-invariant messages

The perfect program is a rock.
There are no inputs.
There are no outputs.
There are no errors!

Some basic rules (1)

When starting a new project, many unexpected obstacles. Must explore many ways before building the final path.

Some basic rules (2)

The development model is crucial.

A "well-designed" system that looks pretty on paper, but not validated early enough by users may end up into a very fat and unusable system.

Some basic rules (3)

Cooperation between projects is difficult.

Different development styles, Team experience.

One more reason for rapid prototyping. Do not wait the end to see the product. Develop the product with users.

Some basic rules (4)

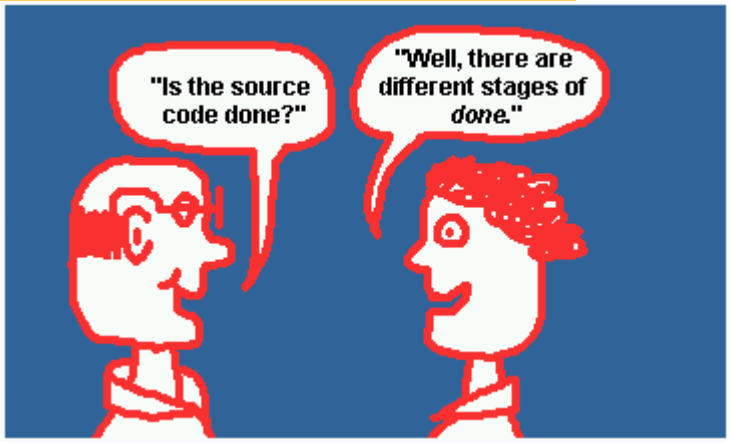
If you have more than pi^2 years experience in managing software projects, multiply by pi your estimation to complete your next project

else multiply by pi^2 R.Brun

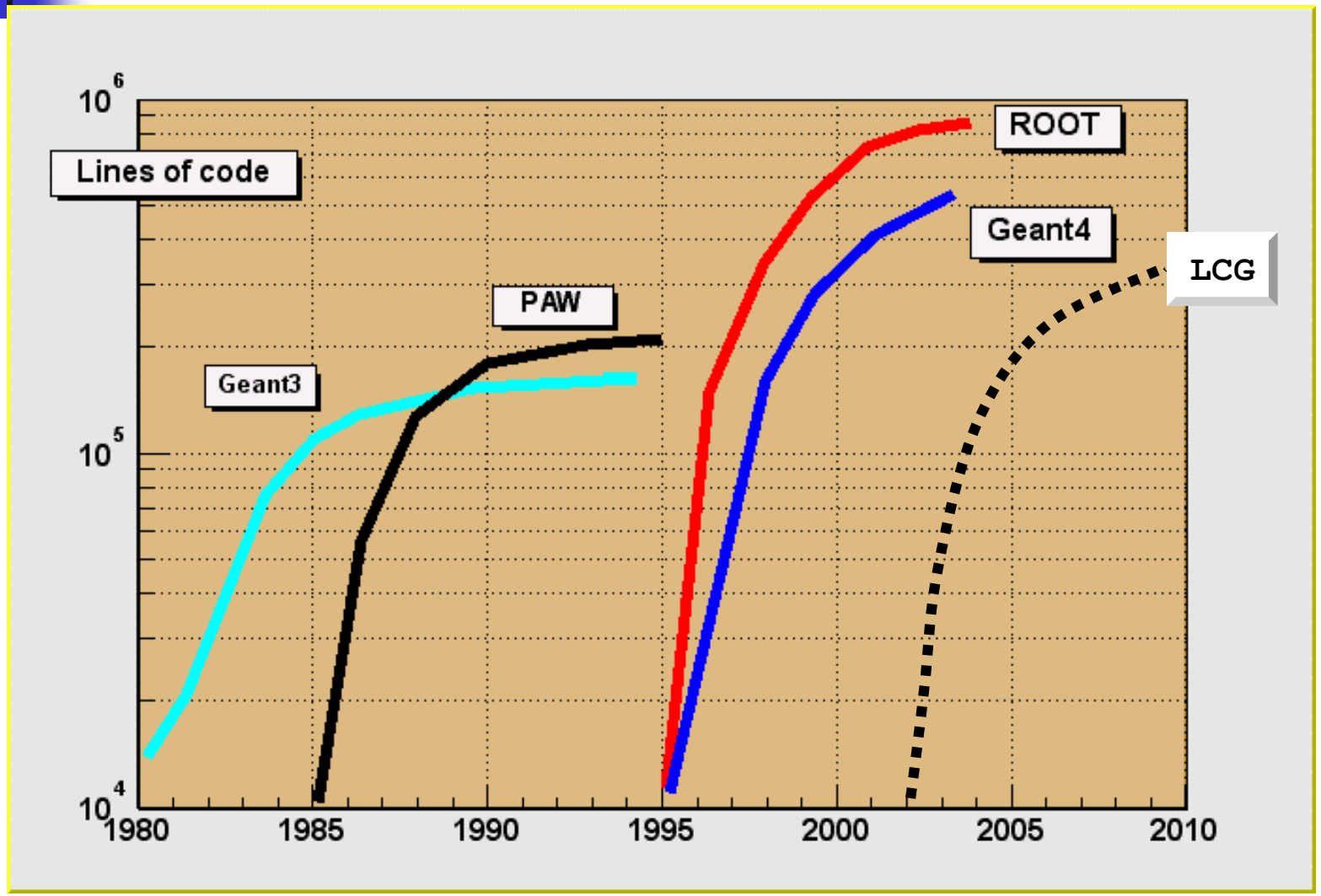
Nine women working together have never made a baby in one month.

If T is the time to implement a system and N the number of participants $T = a/N - b*N^2$

Ideal team size 3 to 6 people



Time to develop



ROOT status/plans

The team

Measuring success

The main components

The development plans

Project History

8 years !!

- Jan 95: Thinking/writing/rewriting/???
- November 95: Public seminar, show Root 0.5
- Spring 96: decision to use CINT
- Jan 97: Root version 1.0
- Jan 98: Root version 2.0
- Mar 99: Root version 2.21/08 (1st Root workshop FNAL)
- Feb 00: Root version 2.23/12 (2nd Root workshop CERN)
- Mar 01: Root version 3.00/06
- Jun 01: Root version 3.01/05 (3rd Root workshop FNAL)
- Jan 02: Root version 3.02/07 (LCG project starts: RTAGs)
- Oct 02: Root version 3.03/09 (4th Root workshop CERN)

ROOT Project basic principles

- Born with minimal CERN staff (by constraint)
- Try to involve as many developers as possible from outside CERN ==>Open Source project
- Try to get as many users asap to validate the ideas. We knew many PAW users.
- Release early, Release often principle
- Target maximum portability (OS & compilers)
- Target maximum functionality and simplicity
- Roottalk newsgroup: vital importance

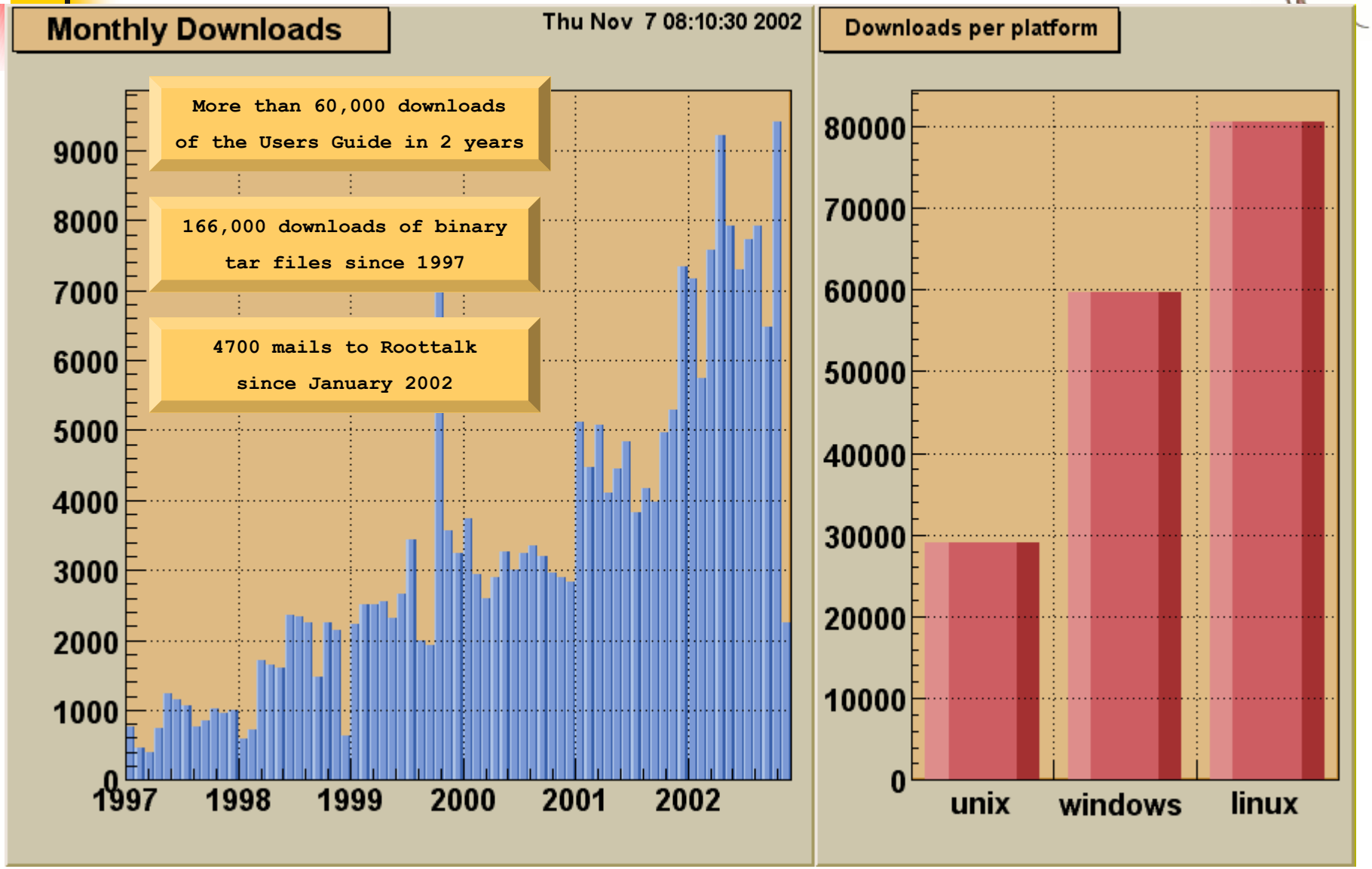
ROOT Team & Associates

- ROOT Team:
  - Ilka Antcheva (LCG staff) (since 1st Aug 2002)
  - Rene Brun: new SFT group and Alice part time
  - Philippe Canal (FNAL/CD) (since 1998)
  - Olivier Couet CERN/IT/API (from PAW) (since 1st Jun 2002)
  - Gerardo Ganis (LCG/EP/SFT) starting just now
  - Masa Goto (Agilent technologies/Japan)
  - Valeriy Onuchin (LCG project associate) (since 1st Feb 2002)
  - Fons Rademakers: Alice and new SFT group
- External Associates
  - Bertrand Bellenot (Alcan) Win32gdk (since June 2000)
  - Maarten Ballintijn (MIT) PROOF (since Sep 2001)
  - Andrei Gheata: (Alice) Geometry package (since Sep 2001)

ROOT Team & Associates (2)

- Now in the LCG
  - Valery Fine (BNL/Atlas) TVirtualX/Qt
  - Victor Perevoztchikov (BNL/Atlas) STL, foreign classes
- More than 50 important contributions from people spending a substantial fraction of their time on the project. See **$ROOTSYS/README/CREDITS**
- Special thanks to Suzanne Panacek who did a great job with the ROOT Users Guide, tutorials, lectures.
  - **Printed copies of the Users Guide in my office**.
- Many thanks to FNAL computing Division for the continuous support of the project since 1998.

ROOT ftp Downloads



Source & Binary distributions

- Intel x86 Linux for Redhat 7.2 and gcc 3.2, version 3.03/09 (10.9 MB). NEW
- Intel x86 Linux for Redhat 7.2 and gcc 2.96, version 3.03/09 (11.2 MB). NEW
- Intel x86 Linux for Redhat 7.2 and gcc 2.95.3, version 3.03/09 (11.5 MB). NEW
- Intel x86 Linux for Redhat 7.2 and Intels icc 6, version 3.03/07 (16.2 MB). NEW
- Intel x86 Linux for Redhat 6.1 (glibc 2.1) and gcc2.95.2, version 3.03/09 (12.9 MB). NEW
- Intel x86 Linux for Redhat 6.1 (glibc 2.1) and egcs1.1.2, version 3.03/09 (11.2 MB). NEW
- Intel x86 Linux for Redhat 5.0/5.1/5.2 (glibc) and egcs 1.1.1, version 3.03/09 (10.9 MB). NEW
- Intel Itanium Linux for Redhat 7.1 (glibc 2.2) and gcc 2.96, version 3.02/06 (9.0 MB). NEW
- HP PA-RISC HP-UX 10.20 with aCC (v1.18), version 3.03/09 (16.8 MB). NEW
- HP Itanium HP-UX 11.20 with aCC, version 3.03/07 (16.8 MB). NEW
- Compaq Alpha OSF1 with cxx 6.2, version 3.03/09 (12.1 MB). NEW
- Compaq Alpha OSF1 with egcs 1.1.2, version 3.03/09 (14.2 MB). NEW
- Compaq Alpha Linux with egcs 1.1.2, version 3.02/06 (11.0 MB).
- Compaq iPAQ PocketPC Linux with gcc 2.95, version 3.02/06 (7.0 MB).
  For more on Linux on iPAQ see www.handhelds.org.
- IBM AIX 4.5 with xlC version 5, version 3.03/09 (13.0 MB, works only on AIX 4.5). NEW
- Sun SPARC Solaris 5.6 with CC4.2, version 3.02/06 (8.7 MB). It cannot be used with Solaris 5.7 or 5.8 even using the same compiler version. You must recompile from the source on these two systems.
- Sun SPARC Solaris 5.7 with CC5.2, version 3.03/09 (13.9 MB). NEW
  It cannot be used with Solaris 5.6 or 5.8 even using the same compiler version. You must recompile from the source on these two systems.
- Sun SPARC Solaris 5.8 with CC5.2, version 3.03/09 (13.6 MB). NEW
  It cannot be used with Solaris 5.6 or 5.7 even using the same compiler version. You must recompile from the source on these two systems.
- SGI IRIX 6.5 with CC, version 3.03/09 (compiled with -n32) (12.8 MB). NEW
- SGI IRIX 6.5 with g++ 2.95.2, version 3.03/09 (14.5 MB). NEW
- SGI IRIX 6.5 with KCC, version 3.03/09 (13.3 MB). NEW
- LinuxPPC(Suse7.3) gcc 2.95.3, version 3.03/07 (10.5 MB). NEW
  Thanks to Damir Buskulic (buskulic@lapp.in2p3.fr) for building this version.
- MacOS X 10.1, for more info see these pages from Keisuke Fujii.
- Windows/NT/w2000 with VC++ 6.0, version 3.03/08 (good old tar file) **WIN32GDK** (12.9 MB). NEW
  This version is compiled and linked with the GDK driver implemented by Bertrand Bellenot. This is still an experimental version:
  - Advantages: Same GUI and look&feel as on Unix
  - Disadvantages: cannot use MSDOS shell: slower
- Windows/NT/w2000 with VC++ 6.0, version 3.03/09 (good old tar file) (12.6 MB). NEW
- Windows/NT/w2000 with VC++ 6.0,compiled with debug info, version 3.03/09 (good old tar file) (22.1 MB). NEW
- Windows/NT/w2000 with VC++ 6.0, version 3.03/09 (built with InstallShield) (12.6 MB). NEW

26 binary tar files + all possible combinations of OS/Compiler in the Makefile

Unix(es)

Linux

Windows

MacosX

Cost to develop

Estimated Value of the main software packages using the SlocCount tool (CoCoMo method) see: http://www.dwheeler.com/sloccount/

	Lines of code	Person Years	Number Years	Number Developers	Total cost $ millions
Minuit	5913	1.29	0.59	2.19	0.174
Hbook	33415	7.96	1.18	6.76	1.075
CLHEP	34932	8.34	1.21	6.96	1.127
Zebra	35058	8.38	1.21	6.97	1.135
Geant3	129727	33.09	2.02	16.34	4.471
PAW	284277	75.42	2.77	27.24	10.187
Geant4	339085	90.75	2.97	30.55	12.259
AliRoot	669419	185.38	3.91	47.57	25.039
ROOT	849859	238.15	4.29	55.56	32.171

ROOT : Powerful & Light-weight

- Tar ball < 15 Mbytes
- Source < 7 Mbytes
- Install from binary file : 1 minute
- No external dependencies
- Fast start-up (1 second)
- Low memory occupancy (< 15 Mbytes)
- Highly optimized algorithms for histograming, fitting, I/O, Tree queries, etc.
- and yet runs everywhere

The main software areas

GRID middleware

DAQ Online

Event Models Folders

ETC...

Event Generators

RDBMS run/file catalogs

Object persistency

Object Dictionary

Event Display

Detector Simulation

System services

Histograming Fitting

2-d, 3-d graphics

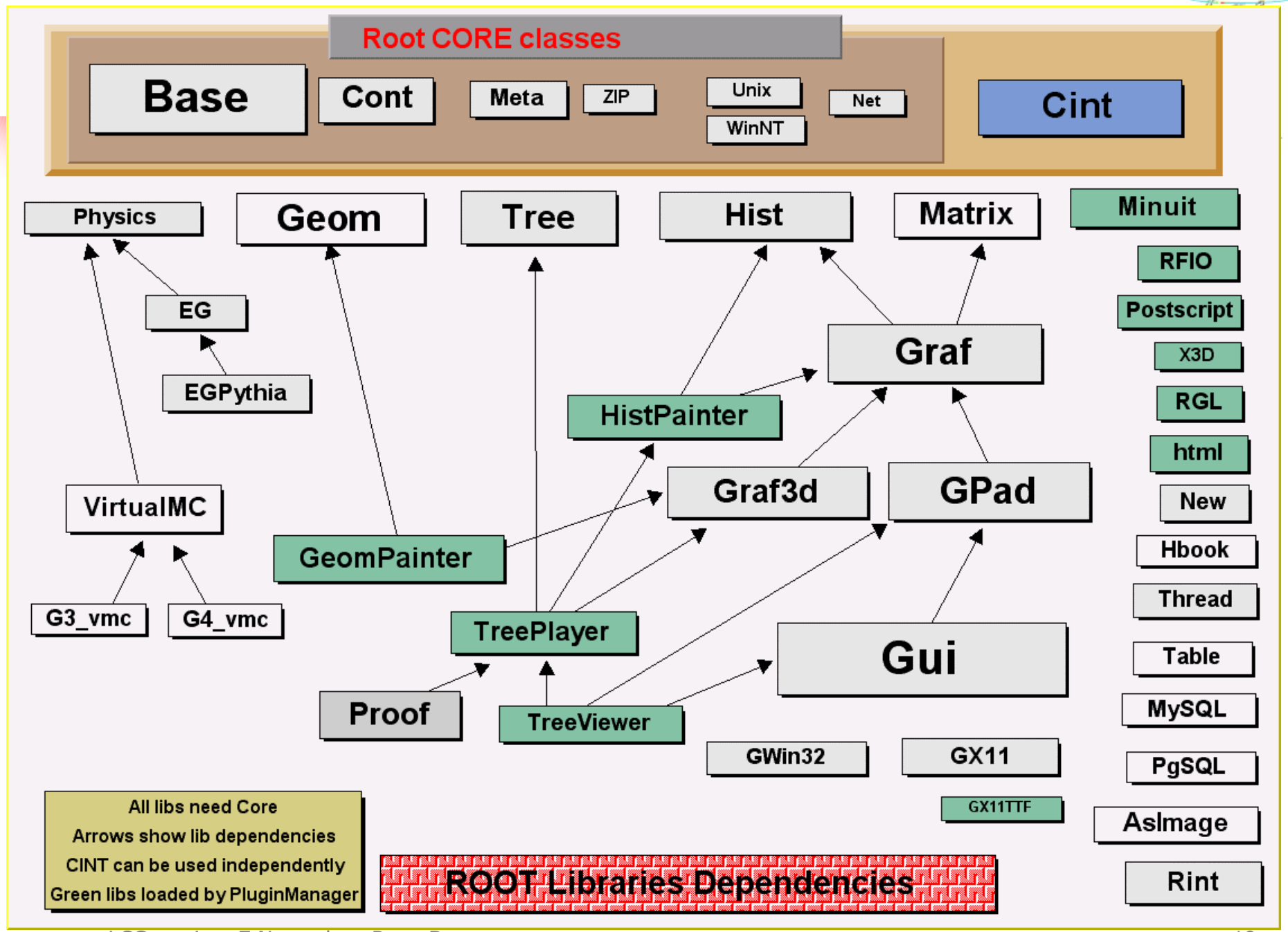
Ntuple analysis

Detector Geometry

Math Libs Statistics

Interpreters

GUI Toolkits


Root CORE classes
Base
Cont
Meta
ZIP
Unix
WinNT
Net
Cint
Physics
Geom
Tree
Hist
Matrix
Minuit
RFIO
Postscript
X3D
RGL
html
New
Hbook
Thread
Table
MySQL
PgSQL
AsImage
Rint
EG
EGPythia
Graf
HistPainter
Graf3d
GPad
VirtualMC
GeomPainter
G3_vmc
G4_vmc
TreePlayer
Gui
Proof
TreeViewer
GWin32
GX11
GX11TTF
All libs need Core
Arrows show lib dependencies
CINT can be used independently
Green libs loaded by PluginManager
ROOT Libraries Dependencies

ROOT libs

R O O T

`ls -l $ROOTSYS/lib`

```
203856  libASImage.so
1273308  libCint.so
5658143  libCore.so
 419481  libEG.so
 152912  libEGPythia.so
 160874  libEGPythia6.so
 162181  libEGVenus.so
 326000  libGX11.so
 183065  libGX11TTF.so
2306421  libGeom.so
 158895  libGeomPainter.so
1019977  libGpad.so
1602106  libGraf.so
1028762  libGraf3d.so
3669409  libGui.so
1605344  libHbook.so
1940222  libHist.so
 332268  libHistPainter.so
 114970  libHtml.so
 167670  libMC.so
 580851  libMatrix.so
 319945  libMinuit.so
 268321  libMySQL.so
  21981  libNew.so
  88438  libPgSQL.so
 336736  libPhysics.so
 196318  libPostscript.so
 576691  libProof.so
 681086  libRFIO.so
2017467  libRGL.so
 177657  libRint.so
  35410  libSRPAuth.so
1120731  libTable.so
 312785  libThread.so
1067715  libTree.so
 356186  libTreePlayer.so
 409350  libTreeViewer.so
 155664  libX3d.so
```

TOTAL = 30.7 MBytes

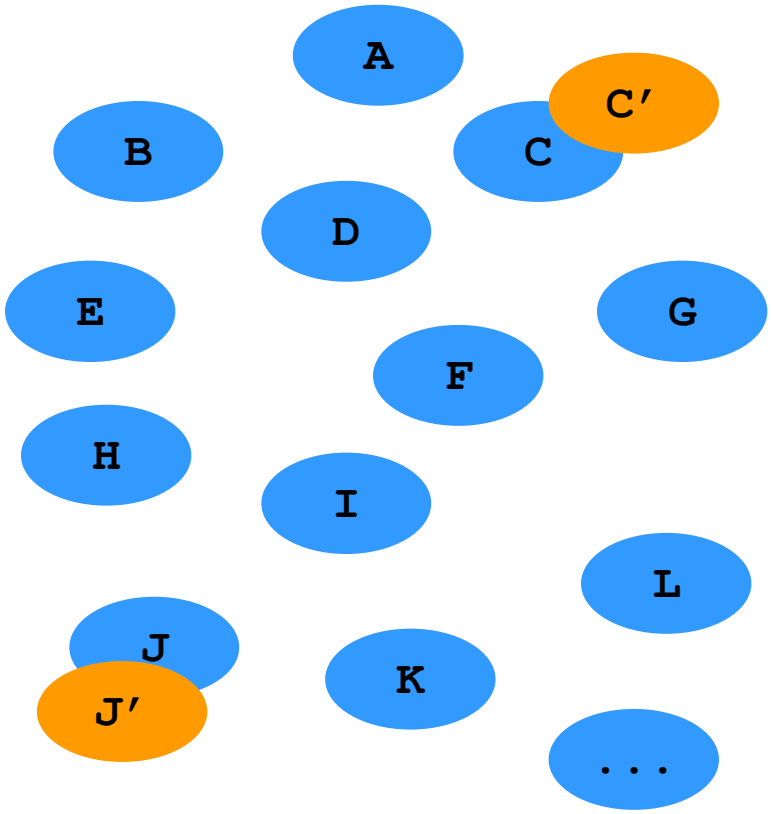
CERNLIB

`ls -l /cern/pro/lib`

```
1434404  libgrafX11.a
1046944  libgraflib.a
4981896  libkernlib.a
2002460  libmathlib.a
11849762  libpacklib.a
4350440  libpawlib.a
```

TOTAL = 25.2 MBytes

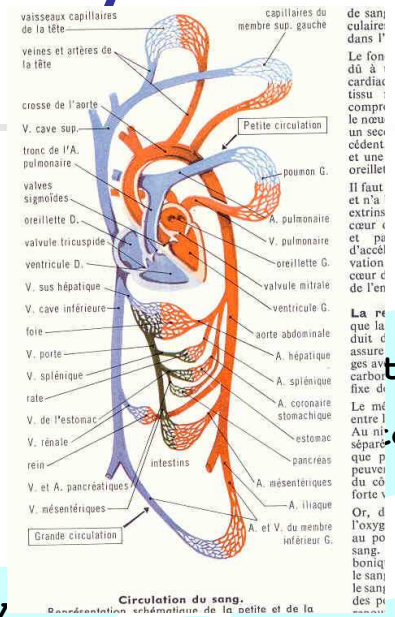
The naive component model



PROs: In principle easy to add or replace a component because of weak coupling

In reality, you simply postpone the integration problem if the number of components N is big eg N> 50

Any box connected to many boxes



Circulation du sang.

GRID middleware

DAQ Online

Event Models Folders

RDBMS run/file catalogs

Object persistency

Event Display

System services

Dectector Simulation

Histograming Fitting

2-d, 3-d graphics

Ntuple analysis

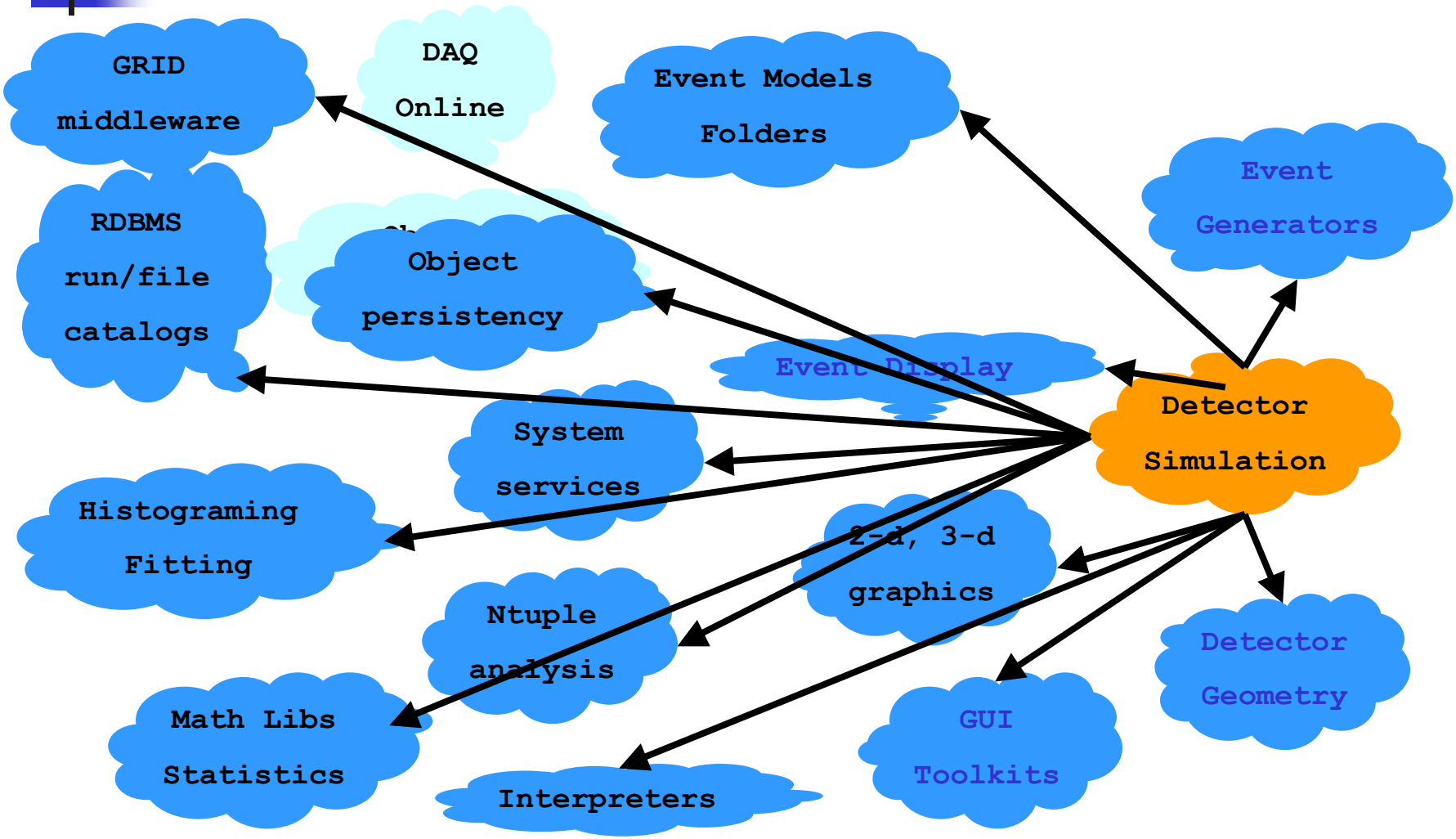
Detector Geometry

Math Libs Statistics

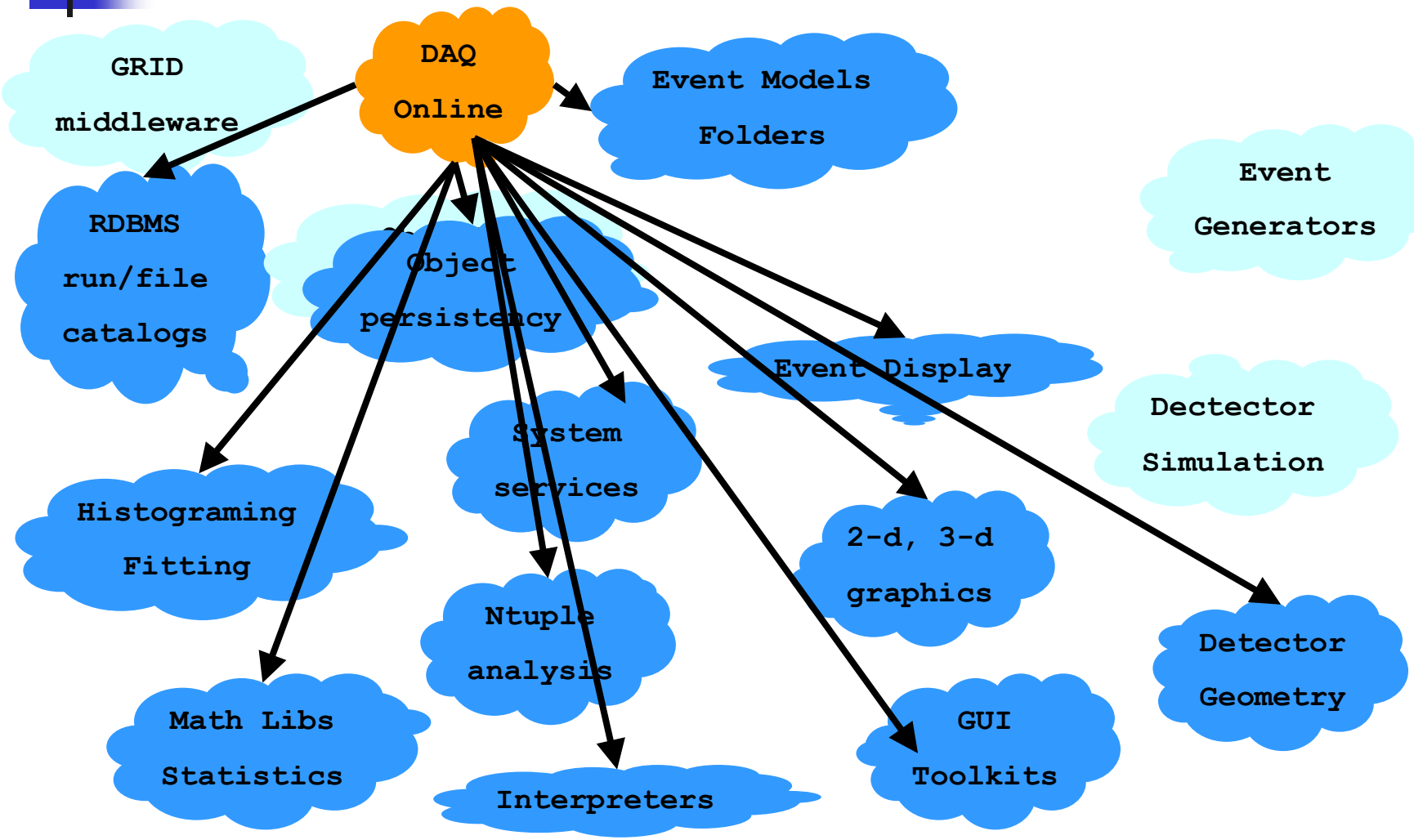
GUI Toolkits

Interpreters

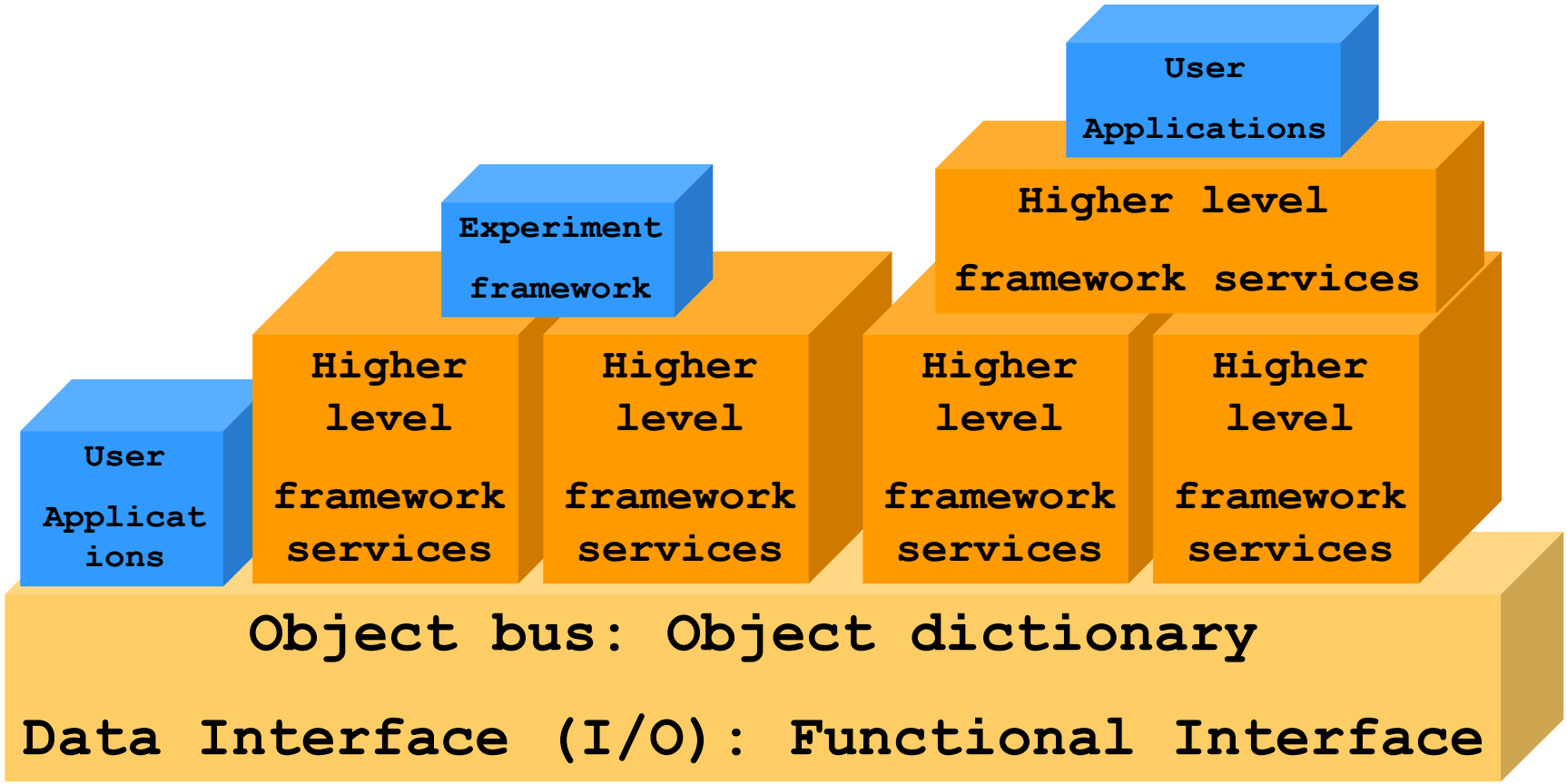
Any box connected to many boxes



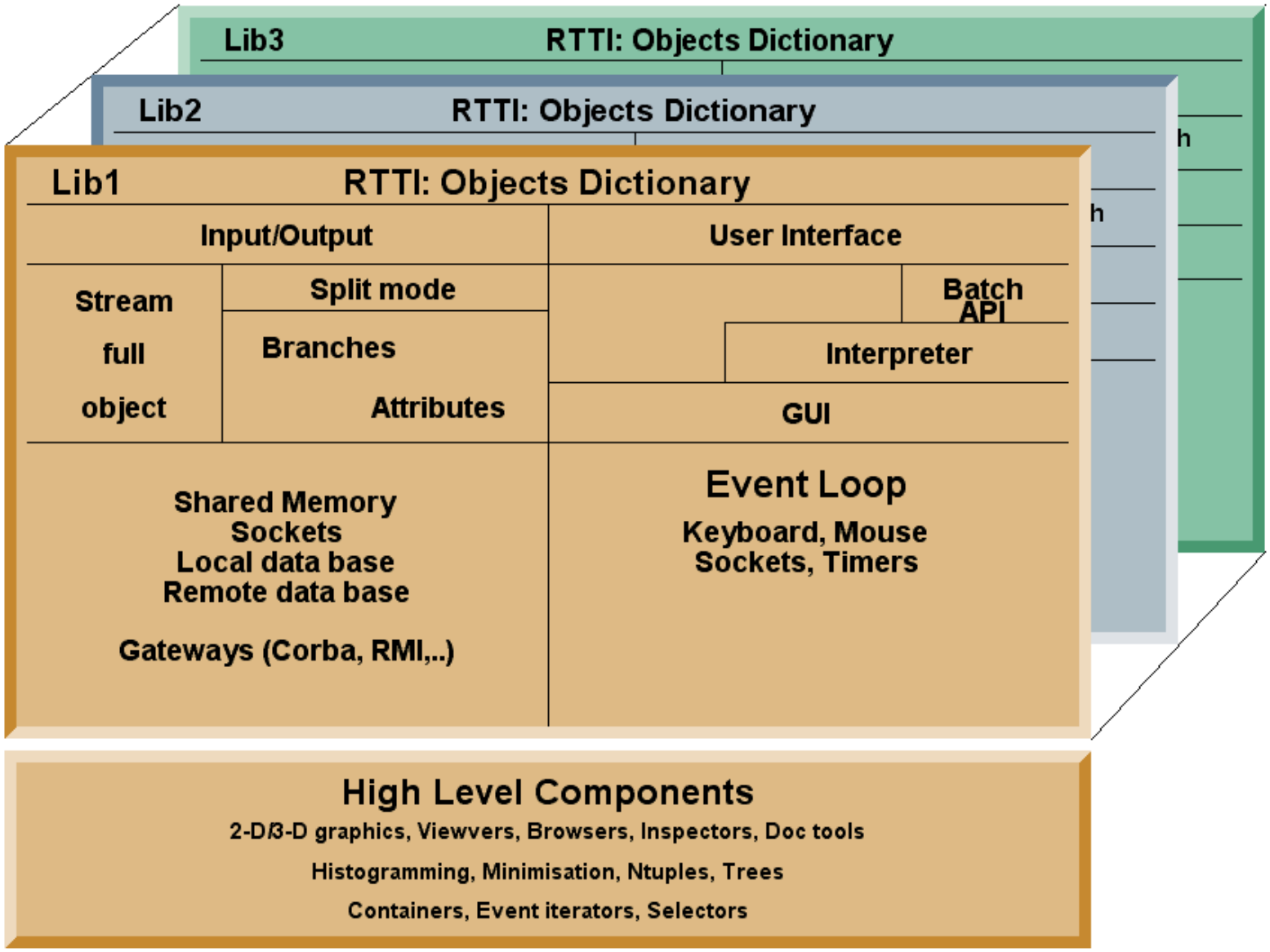
Any box connected to many boxes



Framework with Object bus



Framework: Basic components



Object Persistency (in a nutshell)

- Two I/O modes supported (Key and Trees).
- Key access: simple object streaming mode.
  - A ROOT file is like a Unix directory tree
  - Very convenient for objects like histograms, geometries, mag.field, calibrations
- Trees
  - A generalization of ntuples to objects
  - Designed for storing events
  - split and no split modes
  - query processor
- Chains: Collections of files containing Trees
- ROOT files are self-describing
- Interfaces with RDBMS also available
- Access to remote files (RFIO, DCACHE, GRID)

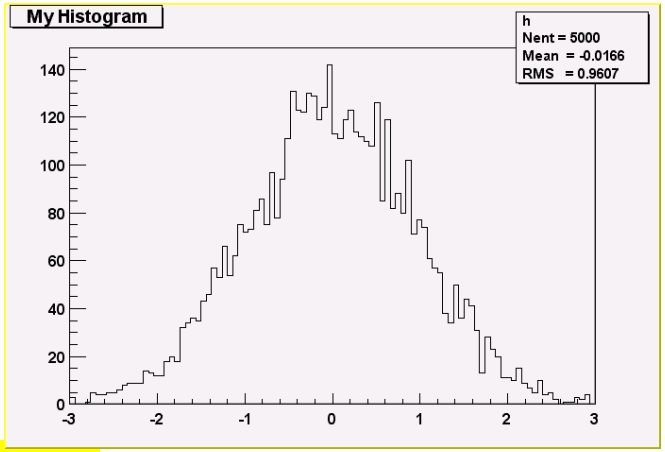
ROOT I/O : An Example

Program Writing

```
TFile f("example.root","new");
TH1F h("h","My histogram",100,-3,3);
h.FillRandom("gaus",5000);
h.Write();
```

Program Reading

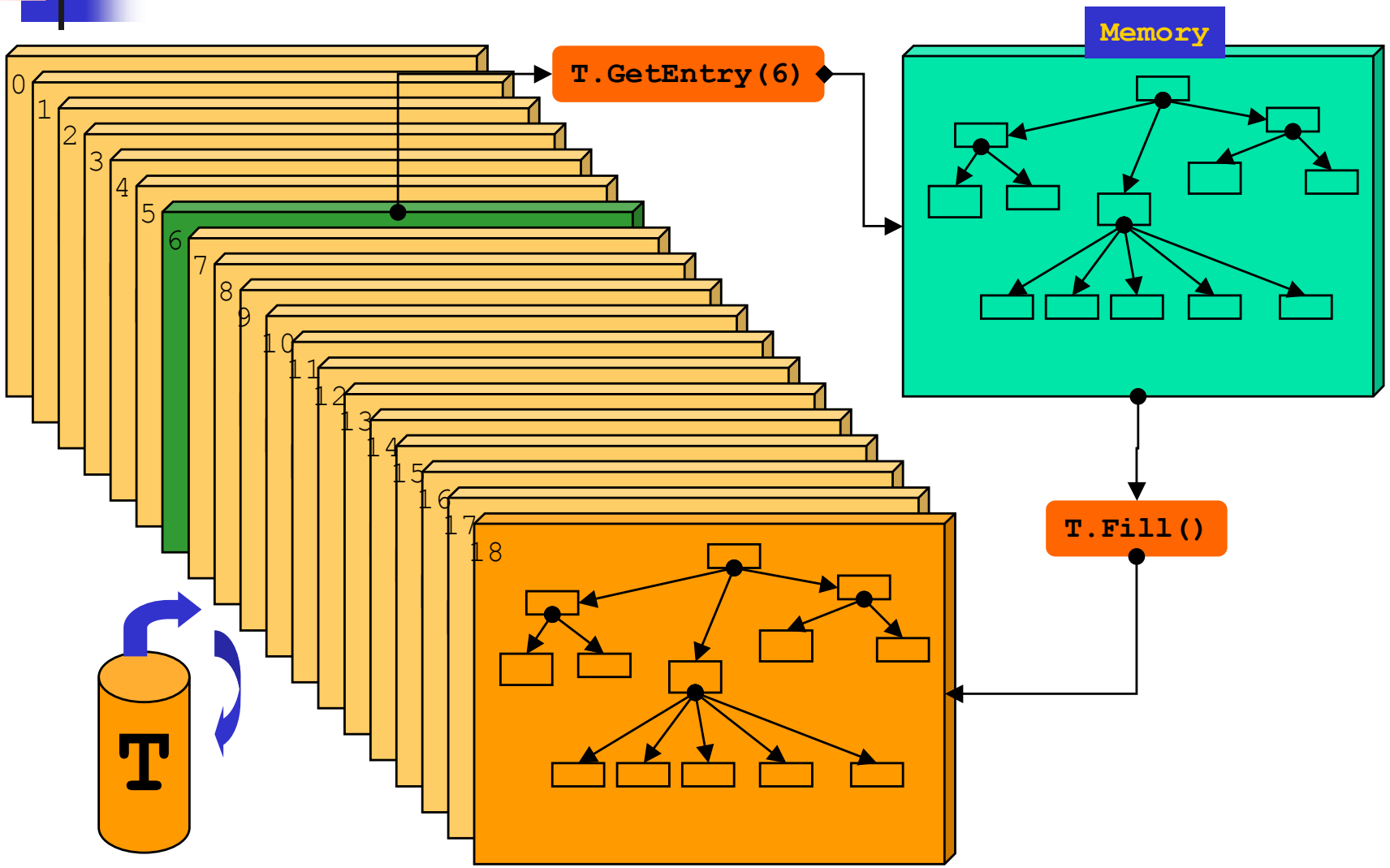
```
TFile f("example.root");
TH1F *h = (TH1F*)f.Get("h");
h->Draw();
f.Map();
```



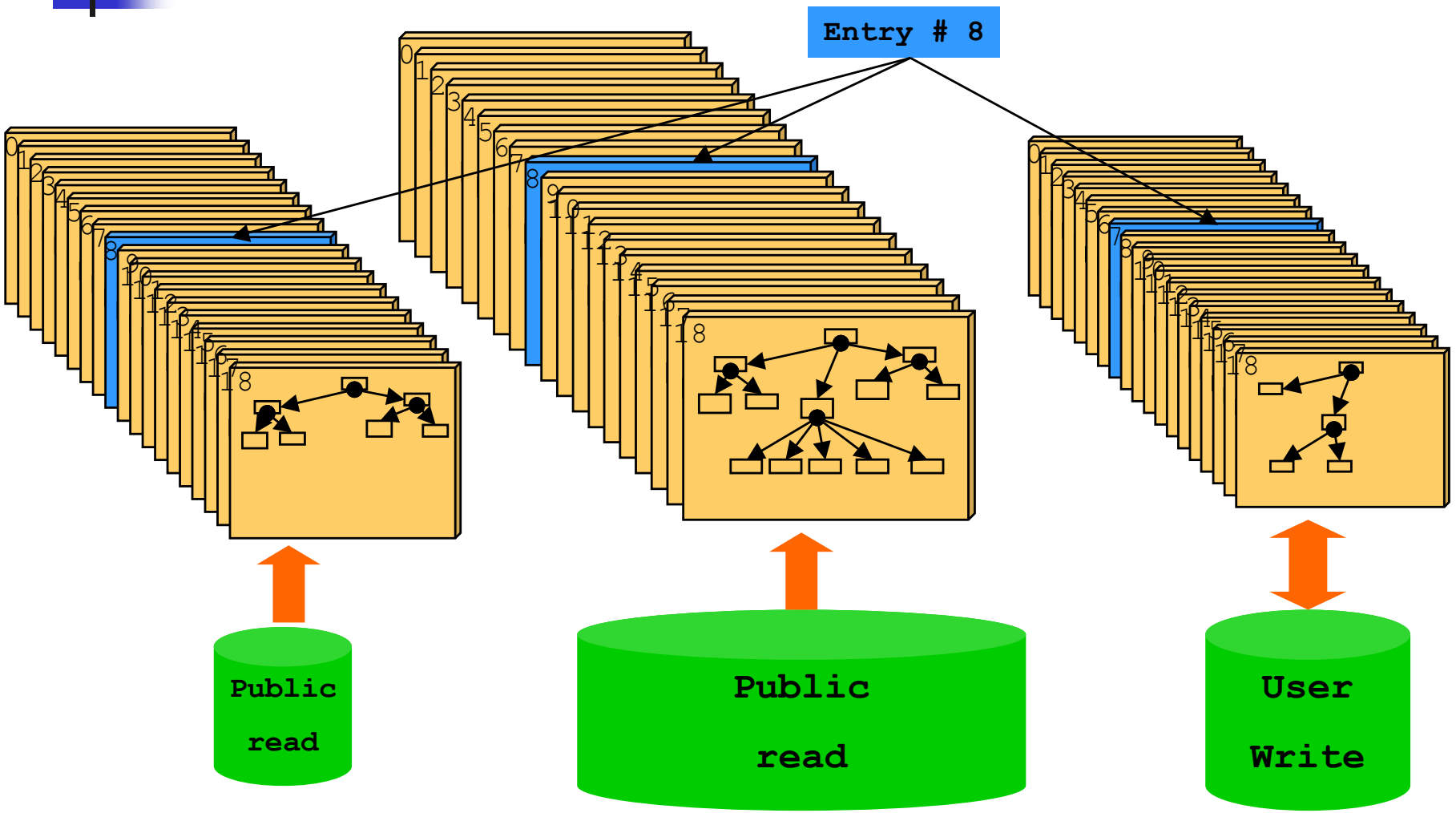

```
20010831/171903  At:64      N=90      TFile
20010831/171941  At:154     N=453     TH1F          CX =  2.09
20010831/171946  At:607     N=2364    StreamerInfo  CX =  3.25
20010831/171946  At:2971    N=96      KeysList
20010831/171946  At:3067    N=56      FreeSegments
20010831/171946  At:3123    N=1       END
```

Memory <--> Tree

Each Node is a branch in the Tree



Tree Friends



Object Persistency

Collaboration with FNAL and BNL

GRID middleware

Online

Event

RDBMS run/file catalogs

Object persistency

Collaboration with LCG ???

Fitting

Ntuple

Collaboration with BNL

Math

Statistics

Interpret

Continue current developments in ROOT I/O

- Foreign classes
- Support for STL

Improved Trees

- TLongRefs
- Interface to Catalogs

Large files > 2 Gbytes

Implement in TStreamerInfo

- in interpreted mode
- what is currently generated by Rootcint
- for STL containers

GRIDS Run/file catalogs

GRID middleware

RDBMS run/file catalogs

DAQ Online

Object persistency

Histograming

Interpreters

Interface with Grid middleware

Interface with Globus

Interface with Alien

PROOF (GRID oriented)

Interfaces with RDBMS

Oracle, MySQL, Postgres, etc

TSQL, TSQLResult

Expecting close relationship with LCG

DAQ Online

GRID middleware

DAQ Online

Event

Fo

RDBMS

ors

Electronic logbook at FNAL

well integrated with ROOT

System

JavaRoot interface

possibly interesting

analysis

Math Libs

Statistics

Interpret

Multi-Threading support

Shared memory

Sockets/Monitors

Client/Server

Network classes

System interface/Signals

Interpreter

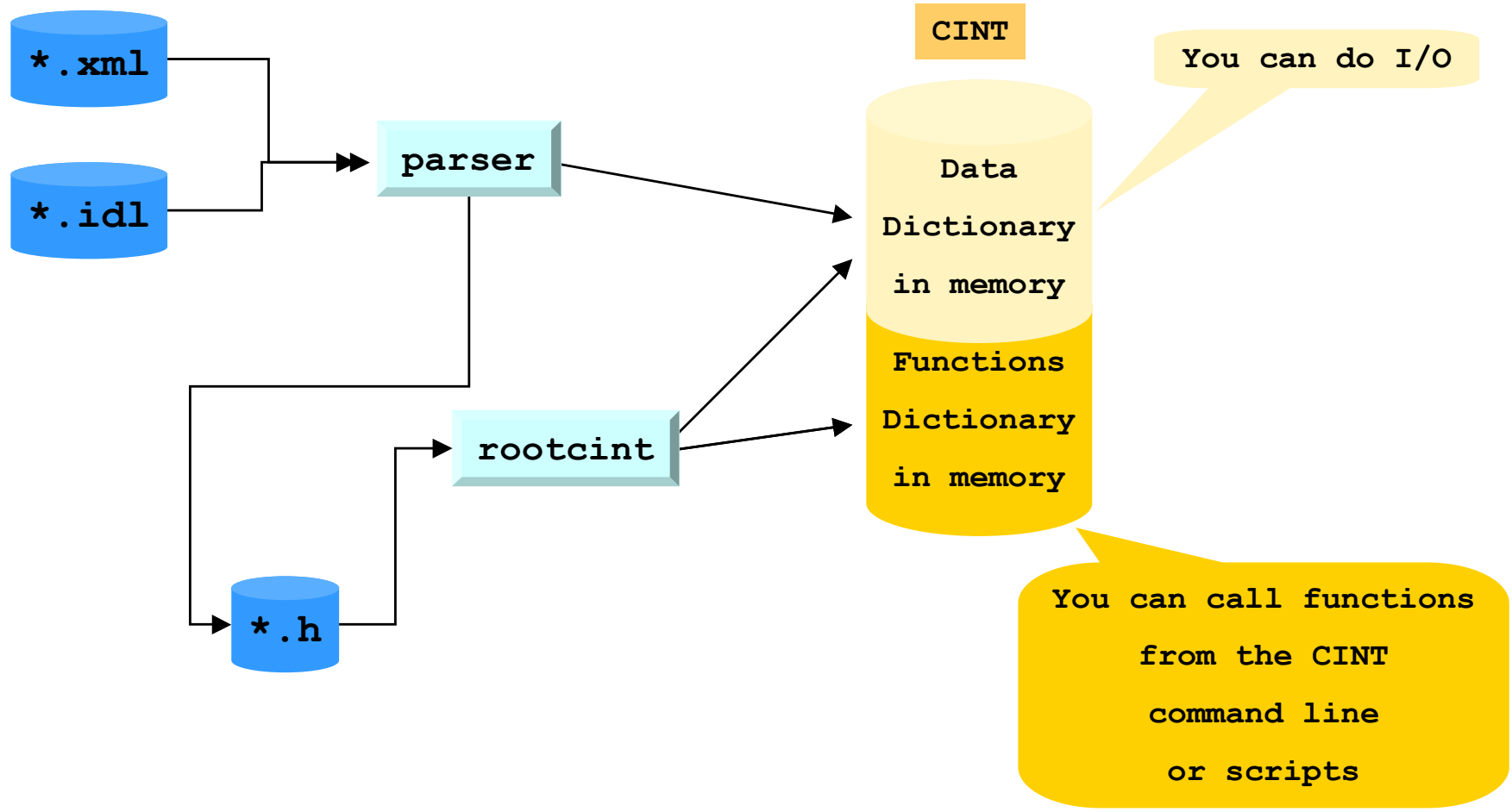
Histograming

Event Display

Browsers/Inspectors

Persistency

Object Dictionary(ies)



Object Dictionary

- Follow the new C++ standard XTI proposal in the area of introspection (eXtended Type Information)
- Too much emphasis so far on the transient class dictionary. (may be we can have one in common!!)
- The real difficulty is the support for automatic schema evolution (persistent views and relationship with current transient classes).
- We did not discuss enough this essential area.
- Remove as much as possible automatic generated code in favor of dynamic interpretation. Reading files without the original classes.

Interpreters

- It was surprising to see that 3 of the 4 architects did not express any interest in the CINT command line. I may have a distorted perception of the user requirements. Please speak now on this important subject.
- Python (like Perl) is a nice scripting language, but is inferior to CINT for what we want to do! A scripting language that can be compiled by a native compiler is essential.
  - In PAW it was not possible to compile a 5000 lines kumac.
- It will happen to Python what we have seen with Iris Explorer a few years ago. It can eat a lot of manpower and users silently ignoring it.
- RootPython is an interesting tool to extend ROOT to services already interfaced with Python.
- JavaRoot could be very interesting for Java-based projects that need an interface to ROOT services.

CINT, Python, Java, C#

GRID middleware

RDBMS run/file catalogs

Histograming Fitting

Math Libs Statistics

Interpreters

GUI Toolkits

CINT: Smooth transition from interpreted code to compiled code dynamically unlinked/linked :

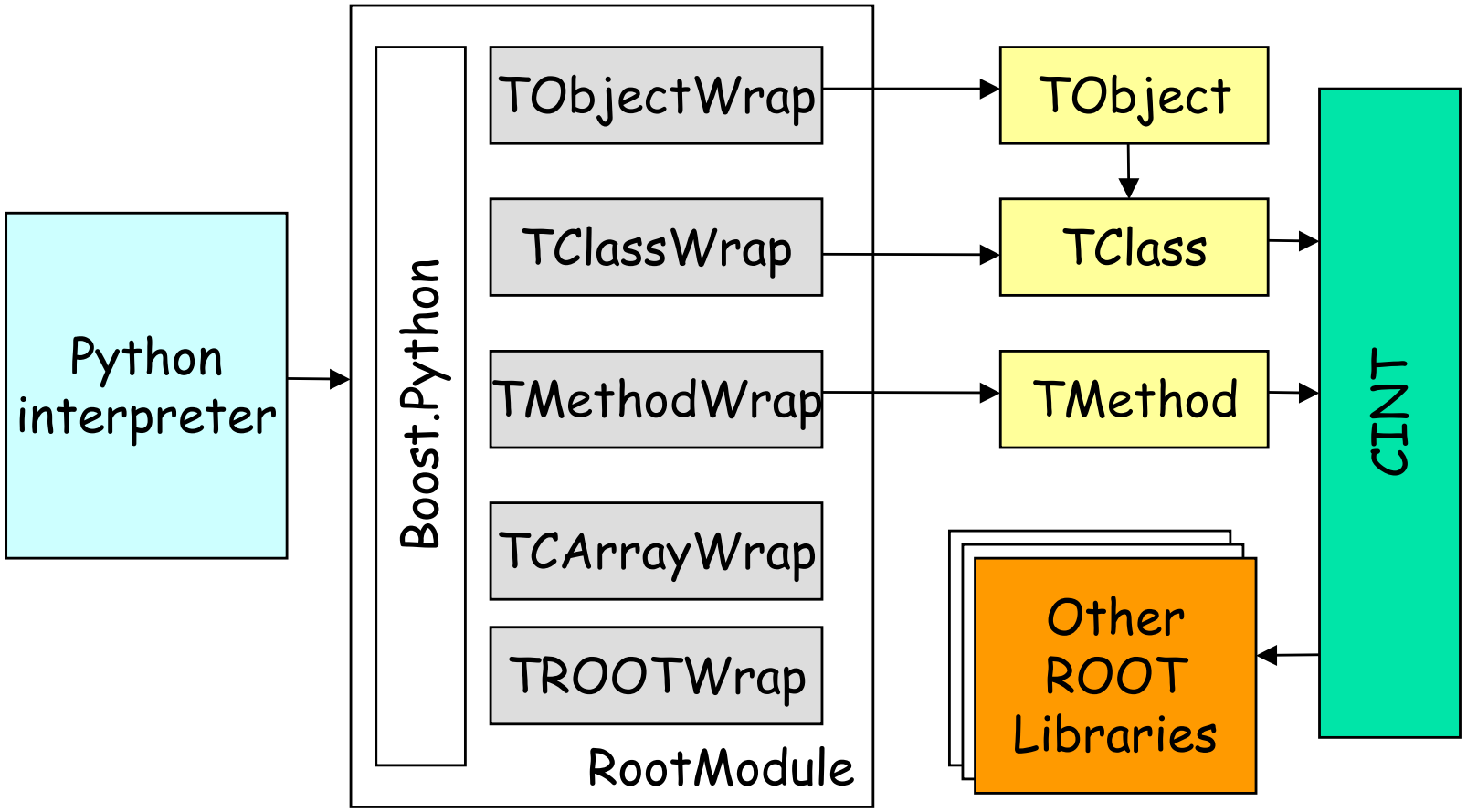
```
root > .x script.C (interpreted)
root > .x script.C++  (compiled)
```

Facilitate automatic interfaces to Python and Java

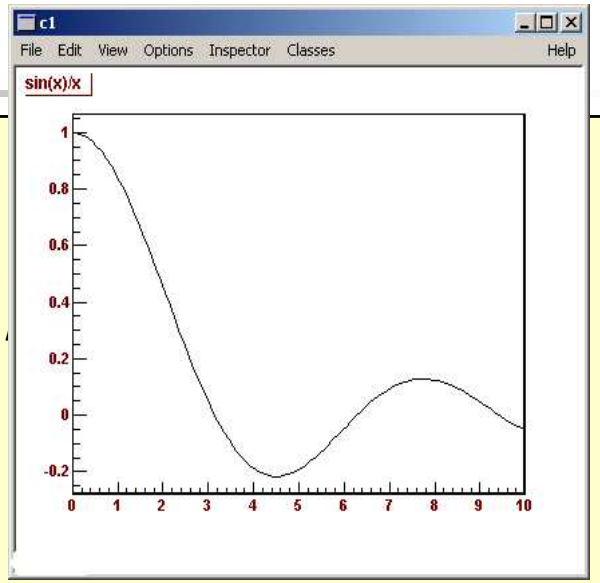
Current implementations are slow

Root dictionary could be better exploited to improve run time.

RootPython (Pere Mato)



Example



Python

```
C:\> python
...
>>> from rootmodule import *
>>> f1 = TF1('func1','sin(x)/x',0,
>>> f1.Eval(3)
0.047040002686622402
>>> f1.Derivative(3)
-0.34567505667199266
>>> f1.Integral(0,3)
1.8486525279994681
>>> f1.Draw()
<TCanvas::MakeDefCanvas>: created default TCanvas with name c1
```

- No much difference between CINT and Python ! P.Mato

CINT

```
TF1 f1("func1","sin(x)/x",0,10)
f1.Eval(3)
f1.Derivative(3)
f1.Integral(0,3)
f1.Draw()
```

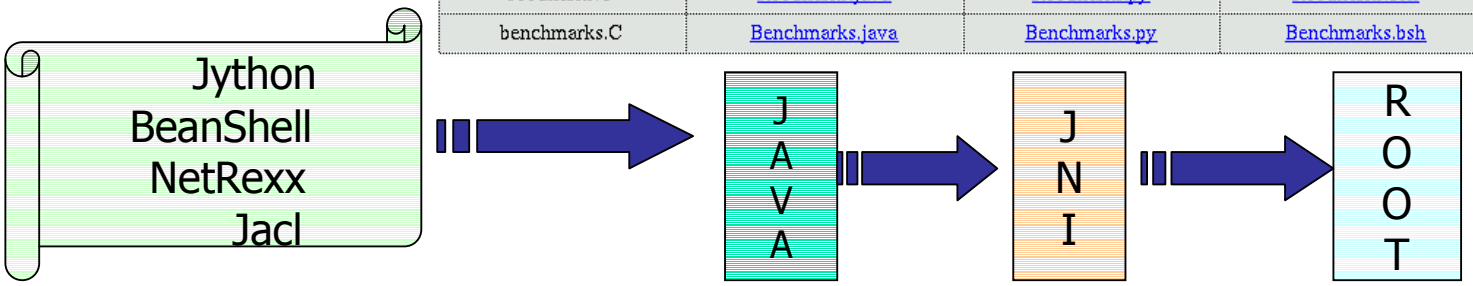
JavaRoot

http://sarkar.home.cern.ch/sarkar/jroot/main.html

Extend Java with Root libraries

- Java gets a matured Histograming API, Fitting and Physics analysis classes, a HEP specific Socket programming API
- Root reaches an even wider audience, finds a number of interpreter and scripting environments that are (re)implemented in Java (Jython, BeanShell etc.)

CINT	Java	Jython	BeanShell
gaxis.C	AxisTest.java	AxisTest.py	AxisTest.bsh
eldmanCousins.C	FeldmanCousins.java	FeldmanCousins.py	FeldmanCousins.bsh
feynman.C	FeynmanTest.java	FeynmanTest.py	FeynmanTest.bsh
file.C	FileTest.java	FileTest.py	FileTest.bsh
fillrandom.C	FillRandom.java	FillRandom.py	FillRandom.bsh
fit.C	FitTest.java	FitTest.py	FitTest.bsh
formula.C	FormulaTest.java	FormulaTest.py	FormulaTest.bsh
framework.C	Framework.java	Framework.py	Framework.bsh
gerrors.C	GerrorsTest.java	GerrorsTest.py	GerrorsTest.bsh
graph.C	GraphTest.java	GraphTest.py	GraphTest.bsh
h1draw.C	H1drawTest.java	H1drawTest.py	H1drawTest.bsh
hsimple.C	HsimpleTest.java	HsimpleTest.py	HsimpleTest.bsh
hsum.C	HsumTest.java	HsumTest.py	HsumTest.bsh
na49view.C	NA49view.java	NA49view.py	NA49view.bsh
ntuple1.C	NtupleTest.java	NtupleTest.py	NtupleTest.bsh
zdemo.C	Runzdemo.java	Runzdemo.py	Runzdemo.bsh
shapes.C	Shapes.java	Shapes.py	Shapes.bsh
surfaces.C	SurfacesTest.java	SurfacesTest.py	SurfacesTest.bsh
tornado.C	Tornado.java	Tornado.py	Tornado.bsh
twoscales.C	TwoscalesTest.java	TwoscalesTest.py	TwoscalesTest.bsh
rootmarks.C	Rootmarks.java	Rootmarks.py	Rootmarks.bsh
benchmarks.C	Benchmarks.java	Benchmarks.py	Benchmarks.bsh



CINT vs Java/Python/Jython

CINT

```
{
   gROOT->Reset();
   c1 = new TCanvas("c1","A Graph with error bars",
           200,10,700,500);

   c1->SetFillColor(42);
   c1->SetGrid();
   c1->GetFrame()->SetFillColor(21);
   c1->GetFrame()->SetBorderSize(12);

   Int_t n = 10;
   Float_t x[n]  = {-0.22, 0.05, 0.25, 0.35, 0.5,
                    0.61, 0.7,  0.85, 0.89, 0.95};
   Float_t y[n]  = {1.0, 2.9, 5.6, 7.4, 9.0,
                    9.6, 8.7, 6.3, 4.5, 1.0};
   Float_t ex[n] = {.05, .10, .07, .07, .04,
                    .05, .06, .07, .08, .05};
   Float_t ey[n] = {.8, .7, .6, .5, .4,
                    .4, .5, .6, .7, .8};
   gr = new TGraphErrors(n,x,y,ex,ey);
   gr->SetTitle("TGraphErrors Example");
   gr->SetMarkerColor(4);
   gr->SetMarkerStyle(21);
   gr->Draw("ALP");

   c1->Update();
}
```

Jython

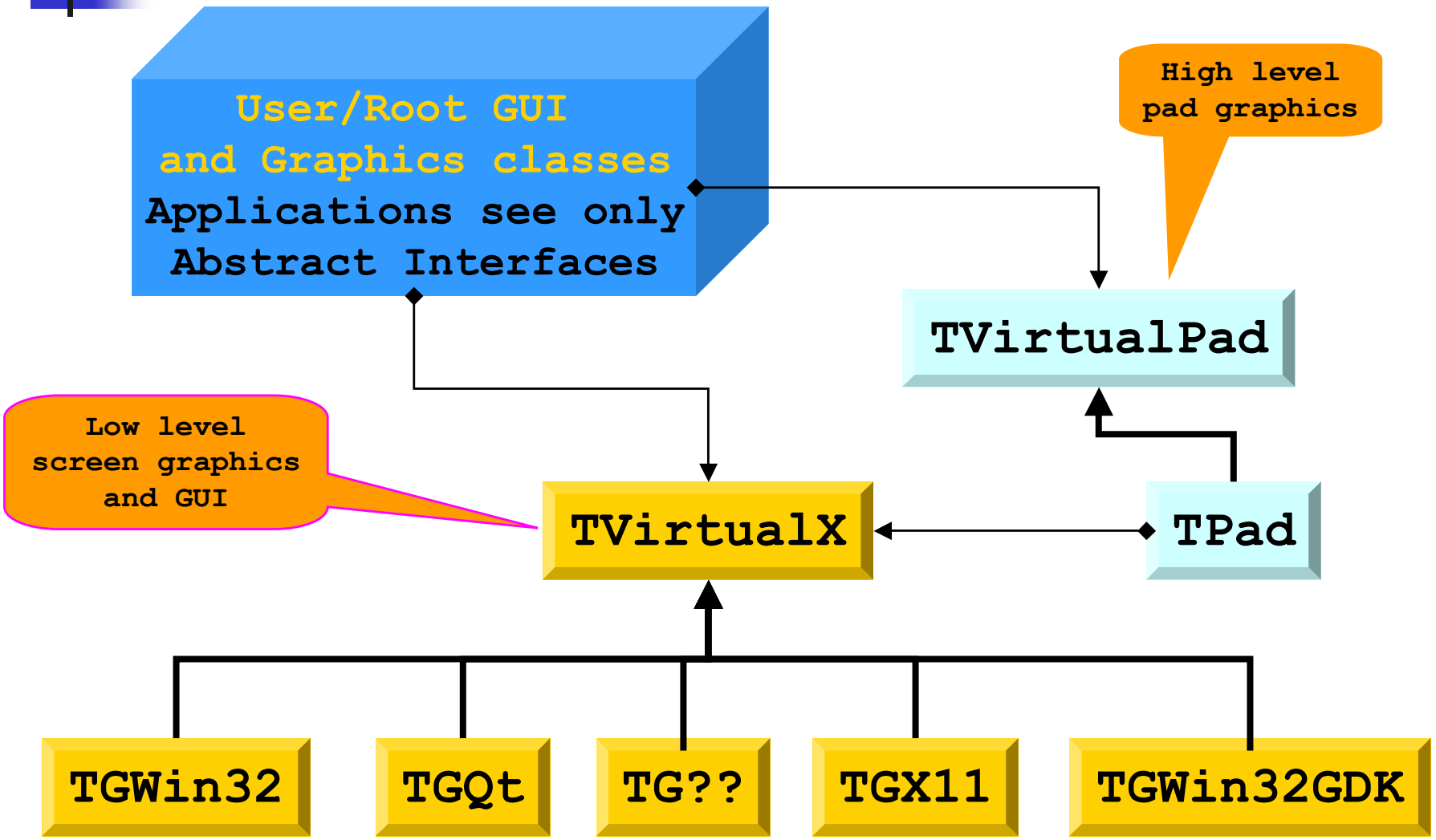
```
class GerrorsTest:
  def __init__(self):
    c1 = gpad.TCanvas("c1",
         "A Graph with error bars",
         200,10,700,500)
    c1.SetFillColor(42)
    c1.SetGrid()
    c1.GetFrame().SetFillColor(21)
    c1.GetFrame().SetBorderSize(12)

    n = 10
    x  = [-0.22, 0.05, 0.25, 0.35, 0.5,
           0.61, 0.7,  0.85, 0.89, 0.95]
    y  = [1.0, 2.9, 5.6, 7.4, 9.0,
          9.6, 8.7, 6.3, 4.5, 1.0]
    ex = [.05, .10, .07, .07, .04,
          .05, .06, .07, .08, .05]
    ey = [.8, .7, .6, .5, .4,
          .4, .5, .6, .7, .8]

    gr = graf.TGraphErrors(n, x, y, ex, ey)
    gr.SetTitle("TGraphErrors Example")
    gr.SetMarkerColor(4)
    gr.SetMarkerStyle(21)
    gr.Draw("ALP")

    c1.Update()
```

CINT: 280 Rootmarks

JAVA: 105 Rootmarks

JYTHON: 52 Rootmarks

Gui/Graphics strategy



GUI Toolkits

Consolidate the TVirtualX interface

Complete TVirtualX/Qt implementation

TVirtualX/Win32-GDK (free on Windows)

Export script from a running GUI

Build GUI from a given script

GUI editor/builder

The ROOT event loop has proven to work with all known graphics systems: X11, Xt, Motif, Qt, Open Inventor, etc

DAQ

Online

Object

persis

Event Display

System services

Histograming

Fitting

TVirtualX

TGX11

TQt

TGWin32

TGWin32gdk

tuple

analysis

Math Libs

Statistics

ors

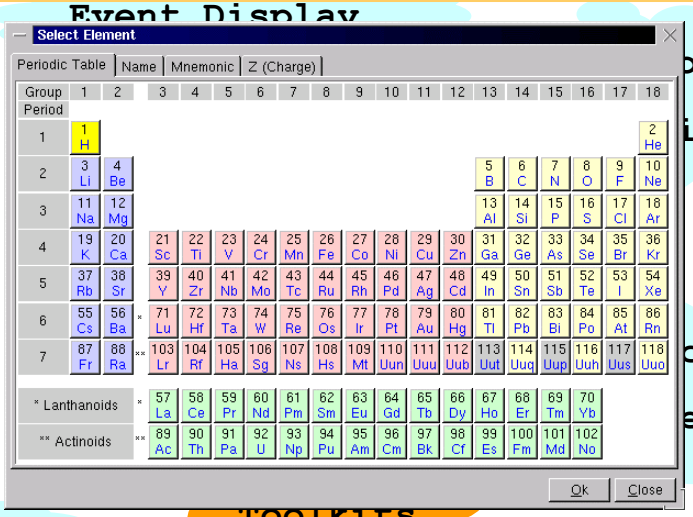
ion

ctor

etry

eters

Toolkits



Math Libs & Statistics

In ROOT today

TVector2,3

TLorentzRotation

TLorentzVector

TRandom,2,3

TMatrix

TMath

TFeldmanCousins

TPrincipal

TMultidimFit

TConfidenceLevel

TFractionFitter

Math Libs

Statistics

Can generate random numbers

from basic distributions; gaus, poisson, etc

from parametric analytic functions 1,2,3-d

from histograms, 1,2,3-d

Matrix package maintained by E. Offermann (Rentec)

A collection of many algorithms

CERNLIB, Numerical Recipes in C/C++

Many algorithms classes

developed by a huge user community

See recent FNAL meeting

and effort organized within ACAT

Would like to see an interface

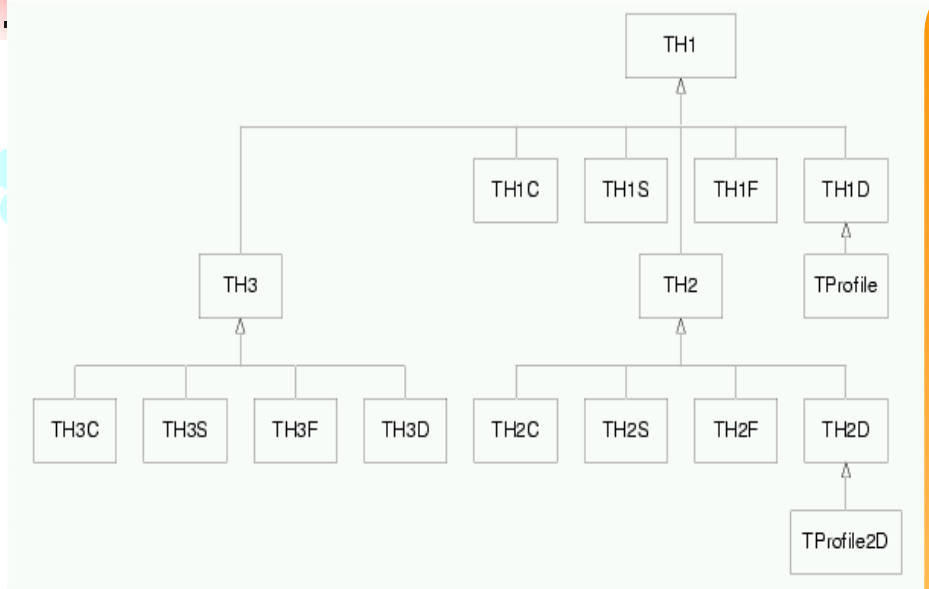
to GSL

to Numerical Recipes in C++

Collaboration with

Fred James, Louis Lyons, Sherry Towers

Histograming & Fitting



Much more than HBOOK/PAW

Fix & var bin size for 1-d, 2-d 3-D

Profile 1, 2 & 3D

All kinds of projections, slices

Errors for all dims

Filling with strings (auto sort)

time axis

associated fitting

Random n. generation

+ auto binning

+ auto addition

support for parallelism

Histograming

Fitting

services

Fairly complete

no requests

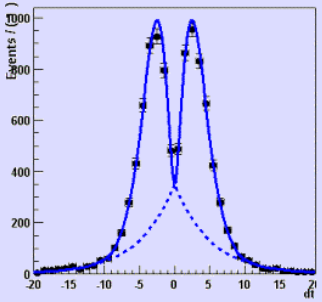
for extensions

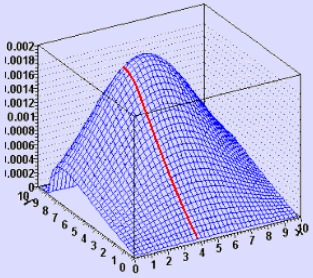
Fitting

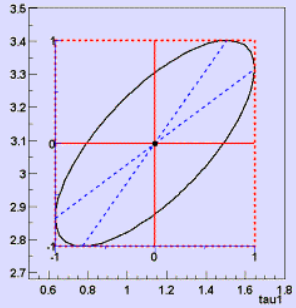
new ideas

collaborators

Interpreters







RooFit
A general purpose tool kit for data modeling

Wouter Verkerke (UC Santa Barbara)

David Kirkby (UC Irvine)

`ftp://root.cern.ch/root/R2002/verkerke.ppt`

Development and Use of RooFit in BaBar

- Development
  - RooFit started as RooFitTools (presented at ROOT2001) in late 1999
    - Original design was rapidly stretched to its limits
  - Started comprehensive redesign early 2001
    - New design was released to BaBar users in Oct 2001 as RooFit
    - Extensive testing & tuning of user interface in the past year
  - RooFit released on SourceForge in Sep 2002
- Current use
  - Almost all BaBar analysis requiring a non-trivial fit now use RooFit or are in the process of switching to RooFit, e.g.
    - CP violation and mixing in hadronic decays ('sin2β')
    - B-Mixing in di-lepton events, $D^{*}\ell\nu$ events
    - Measurement of $\sin 2\alpha_{(eff)}$ from $B \rightarrow \rho\,\pi$, $B \rightarrow \pi\,\pi$
    - Searches for rare decays ($B \rightarrow \phi\, K_S$, $\eta'\, K_S$, ...)
  - **Typical fit complexity**
    - **30 – 70 floating parameters**
    - **4-8 dimensions**
    - **PDF consists of 1000-10000 objects**
    - **Dataset of 500-100000 events**

Ntuples & Trees analysis

PAW-like queries on attributes

tree.Draw("varx","sqrt(x*y) <z")

tree.Draw("event.tracks.GetPt()")

+

Tree browser and viewer

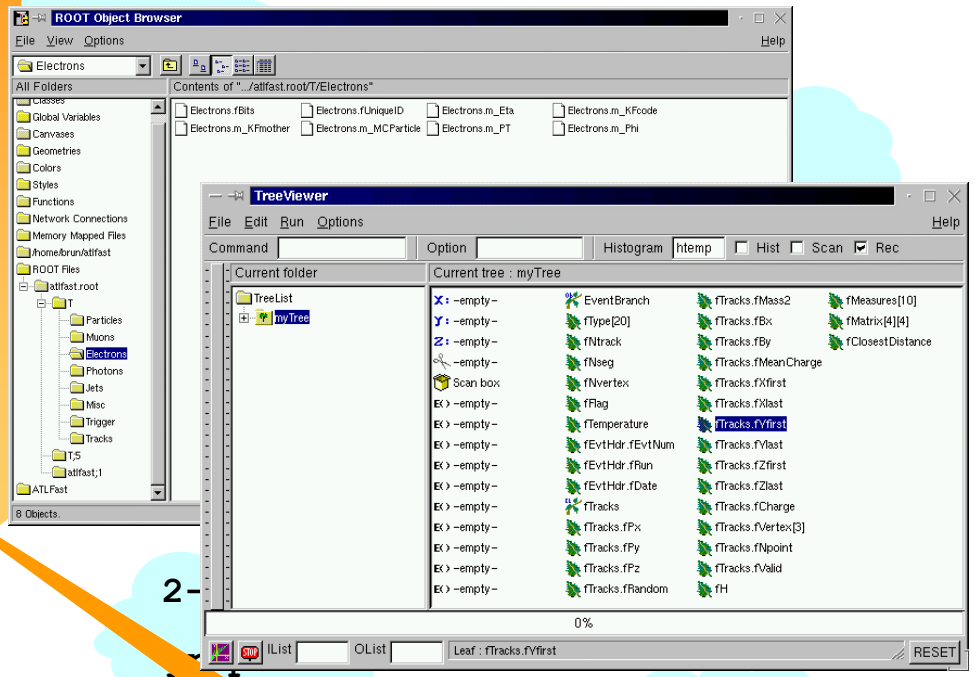
+MakeClass

(generation of skeleton analysis code)

+MakeSelector

same as MakeClass for PROOF

Collaboration with FNAL



Histograming

Fitting

Ntuple analysis

Math Libs

Statistics

Interpreters

Detector Geometry

Collaboration with MIT

Parallel ROOT Facility

- The PROOF system allows:
  - parallel analysis of trees in a set of files
  - parallel analysis of objects in a set of files
  - parallel execution of scripts

  on clusters of heterogeneous machines
- Its design goals are:
  - transparency, scalability, adaptability
- Prototype developed in 1997 as proof of concept, full version nearing completion now
- Collaboration between core ROOT group at CERN and MIT Heavy Ion Group

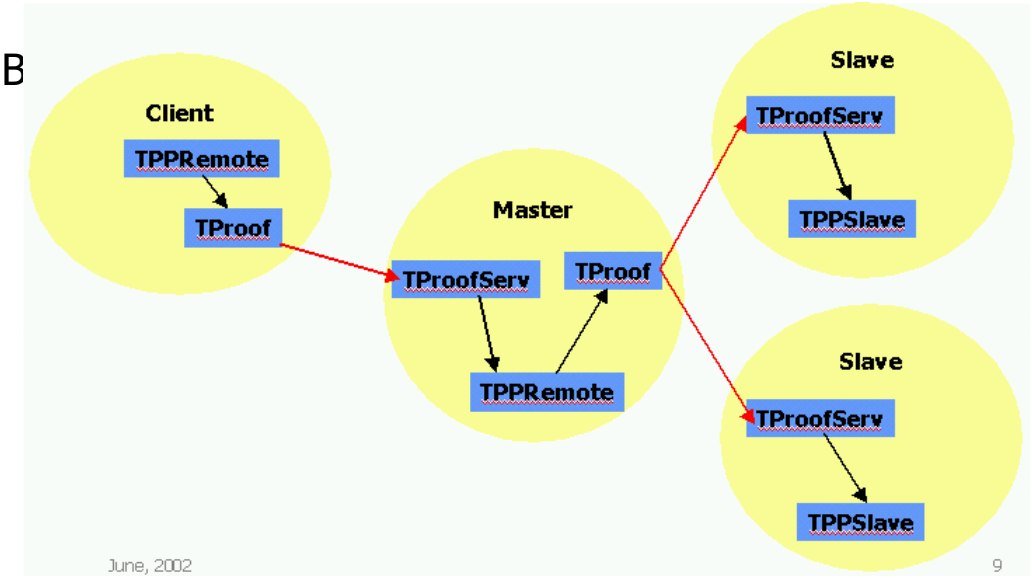
Running a PROOF Job

```
// Analyze TChains in parallel

gROOT->Proof();
TChain *chain = new TChain("AOD");
chain->Add("lfn://alien.cern.ch/alice/prod2002/P2001*");
. . .
chain->Process("myselector.C");
```

```
// Analyze generic data sets in parallel

gROOT->Proof();
TDSet *objset = new TDSet("MyEvent", "*", "/events");
objset->Add("lfn://alien.cern.ch/alice/prod2002/file1");
. . .
objset->Add(set2003);
objset->Process("myselector.C++");
```

PROOF Demo at ROOT workshop

- Client machine
  - PIII @ 1GHz / 512 MB
  - Standard IDE disk
- Cluster with 15 nodes at CERN
  - Dual PIII @ 800 MHz / 384 MB
  - Standard IDE disk
- Cluster with 4 nodes at MIT
  - Dual AthlonMP @ 1.4GHz / 1GB
  - Standard IDE disk



Detector geometry

A very important element

Request number 1 at ROOT FNAL workshop 2001

Work in progress with ALICE

Huge interest in many experiments

I have a complete talk on this

Modeling

Visualization

Interactivity

Where am I?

Distance to boundary

Closest boundary

Persistency

DAQ

Online

Object

ersistency

Event

Generators

Event Display

Detector

Simulation

Syst

servi

Simulation program
Geant3-based
Geant4-based
Fluka-based

-d, 3-d

raphics

Histogramming

C++ classes

Geometry package

le

sis

Math Libs

tics

MySQL

Interp

Reconstruction program

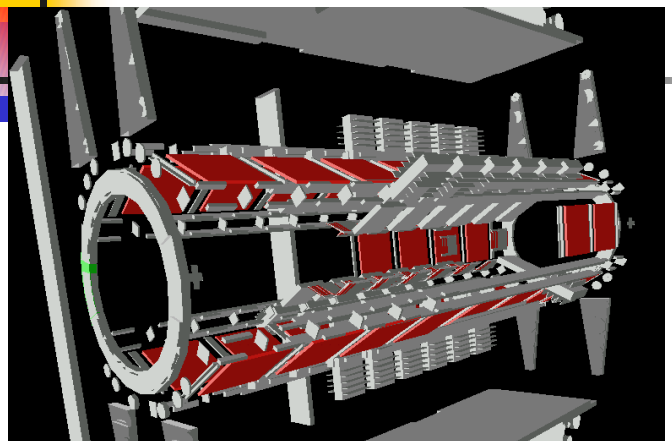
GUI

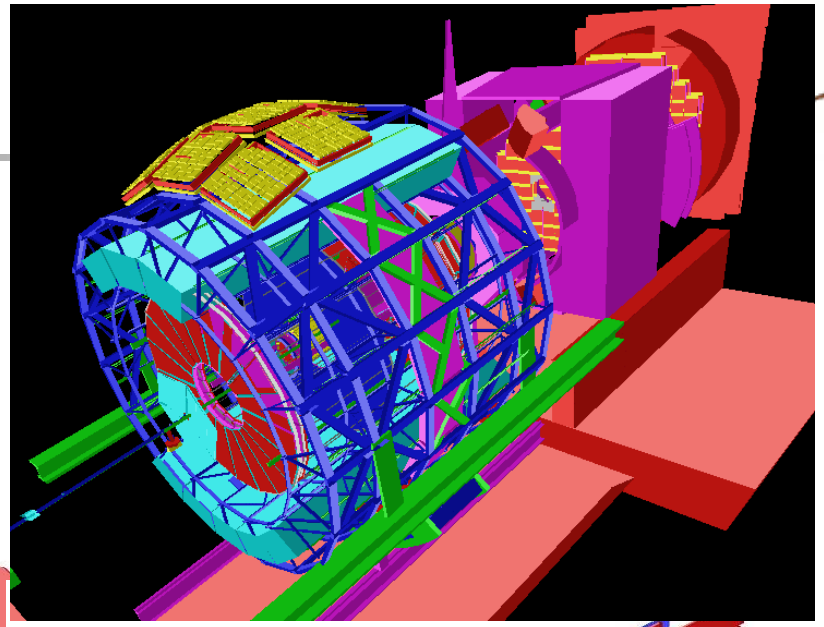
Toolkits

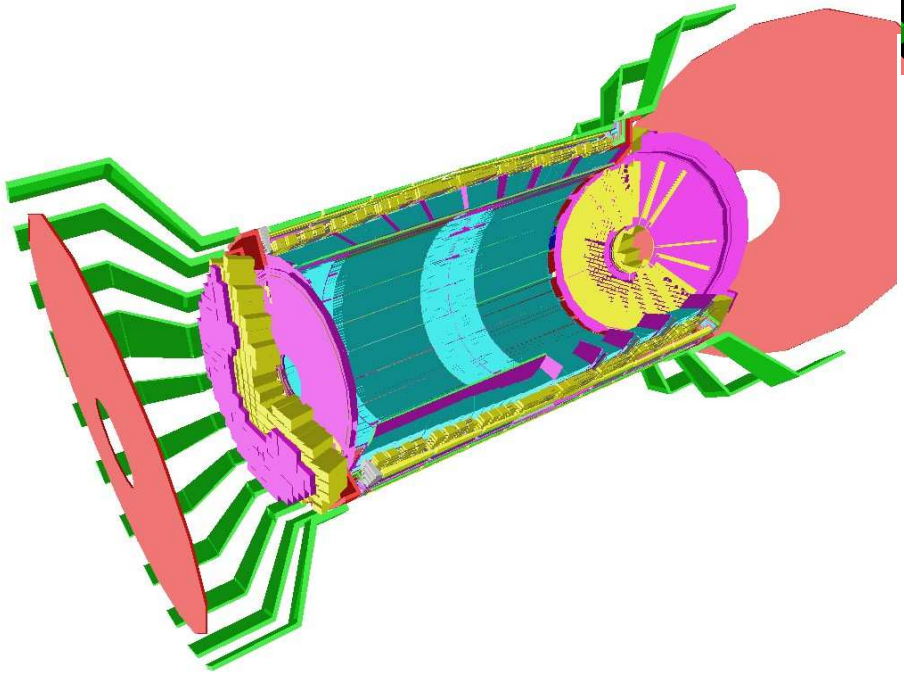
Detector

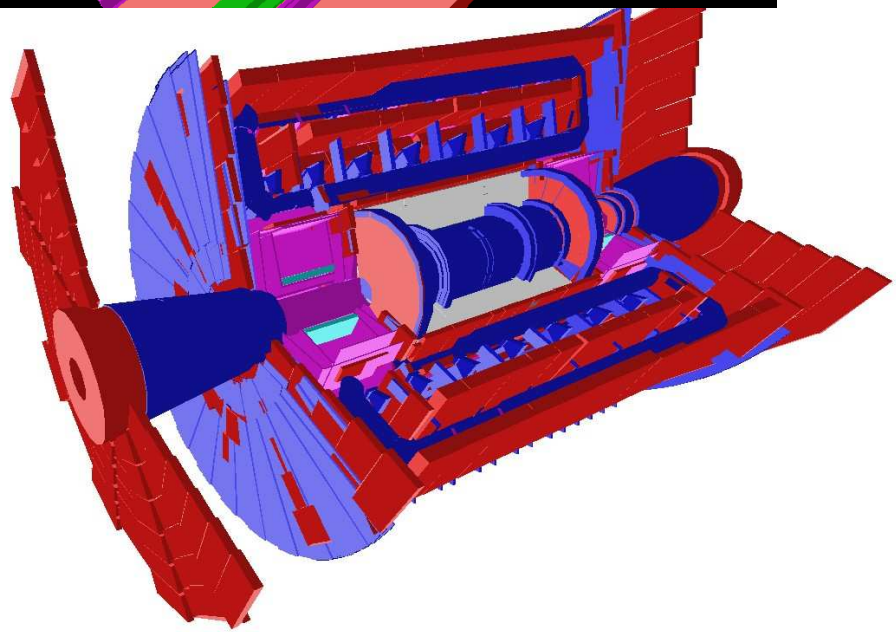
Geometry

Some detectors in ROOT geometry









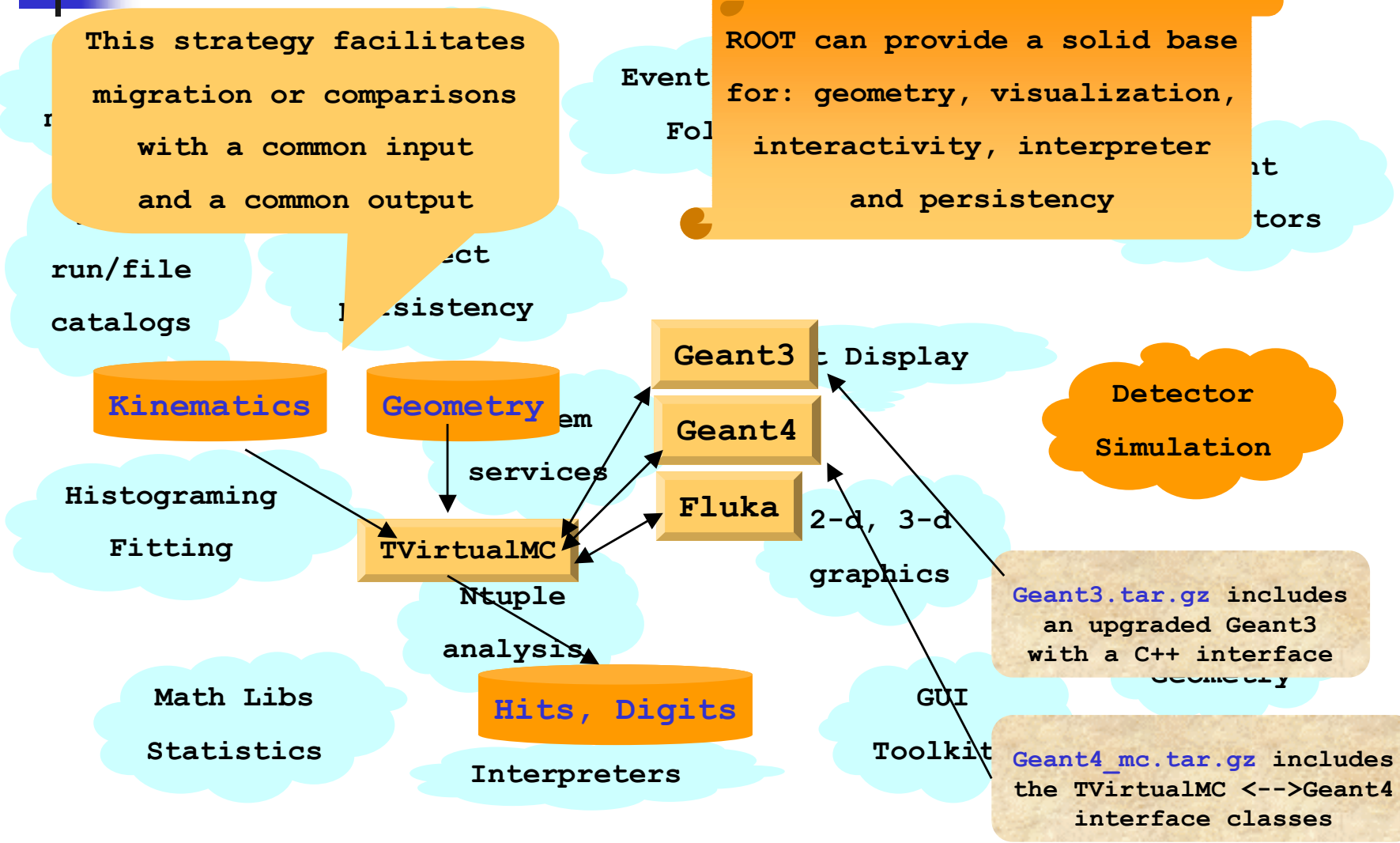
TGeo performance vs Geant3

	Number nodes	gtmedi physics	Root physics	Geant3/ Root	gtmedi random	Root random	Geant3/ Root
Gexam1	425	3.08	1.84	1.67	6.60	4.39	1.50
Gexam3	86	2.87	2.15	1.33	3.47	2.50	1.38
Gexam4	12781	2.51	2.20	1.14	12.09	11.18	1.08
Brahms	2649	5.82	3.04	1.91	4.17	1.93	2.16
Tesla	15370	6.56	5.58	1.17	12.95	7.15	1.81
CDF	24422	14.81	4.31	3.43	20.94	5.85	3.57
Minos_near	30988	30.93	20.99	1.47	21.57	13.70	1.57
BTeVEcal	52	1.57	1.08	1.45	1.78	0.73	2.43
BTeV	295310	45.27	25.88	1.75	197.06	26.83	7.34
CMSEcal	251713	5.60	1.81	3.09	5.69	1.74	3.27
CMS	1166310	33.57	8.76	3.83	39.09	24.98	1.56
LHCb	1533488	7.98	6.75	1.18	12.58	2.89	4.35
Alice	3080198	11.50	8.63	1.33	11.45	7.28	1.57
Atlas	29046966	8.90	9.94	0.89	32.48	23.39	1.38

Detector Simulation

This strategy facilitates migration or comparisons with a common input and a common output

ROOT can provide a solid base for: geometry, visualization, interactivity, interpreter and persistency



Modularity

Ignominy plots

Decoupling components

The Plug-in Manager

Package Metrics (Ignominy)

from Lassi Tuura

Project	Release	Packages	Average # of direct dependencies	Cycles (Packages Involved)	# of levels	ACD*	CCD*	NCCD*	Size
Anaphe	3.6.1	31	2.6	--	8	5.4	167	1.3	630/170k
ATLAS	1.3.2	230	6.3	2 (92)	96	70	16211	10	1350k
	1.3.7	236	7.0	2 (92)	97	77	18263	11	1350k
CMS/ORCA	4.6.0	199	7.4	7 (22)	35	24	4815	3.6	420k
	6.1.0	385	10.1	4 (9)	29	37	14286	4.9	580k
CMS/COBRA	5.2.0	87	6.7	4 (10)	19	15	1312	2.7	180k
	6.1.0	99	7.0	4 (8)	20	17	1646	2.9	200k
CMS/IGUANA	2.4.2	35	3.9	--	6	5.0	174	1.2	150/38k
	3.1.0	45	3.3	1 (2)	8	6.1	275	1.3	150/60k
Geant4	4.3.2	108	7.0	3 (12)	21	16	1765	2.8	680k
ROOT	2.25/05	30	6.4	1 (19)	22	19	580	4.7	660k

*) *John Lakos, Large-Scale C++ Programming*

- Size = total amount of source code (roughly—not normalised across projects!)
- ACD = average component dependency (~ libraries linked in)
- CCD = sum of single-package component dependencies over whole release: test cost
- **NCCD = Measure of CCD compared to a balanced binary tree**
  - < 1.0: structure is flatter than a binary tree (= independent packages)
  - > 1.0: structure is more strongly coupled (vertical or cyclic)
  - **Aim: Minimise NCCD for given software/functionality** (good toolkit: ~ 1.0)

Plug-in Manager

Extended in 3.03/09

- Where are plug-ins used?

```
TFile *rf = TFile::Open("rfio://castor.cern.ch/alice/aap.root")

TFile *df = TFile::Open("dcache://main.desy.de/h1/run2001.root")
```

- Previously dependent on "magic strings" in source, e.g. in TFile.cxx:
- Adding case or changing strings requires code change and recompilation. Not user customizable.
- Currently 29 plug-ins are defined for 20 different (abstract) base classes
- No magic strings in code anymore

The Plug-in Manager is expected to solve most problems reported by Lassi

Relations with LCG

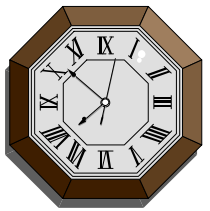
Where we agree

Possible problems

Wishes

The LCG Project

- Must be a success
- Because success is not guaranteed
  - we better start on solid grounds
  - time is very very very critical



- The LCG has an opportunity to capitalize on the success of ROOT.

- But, there is a potential danger to see
  - parallel developments and conflicts
  - software "balkanisation" and "saucissonage"
  - wrong balance in manpower between projects and experiments

Proposal to Blueprint RTAG in June

The existing set of ROOT libs is the starting core of the LCG software. Because the system is already widely distributed and used, it guarantees the initial acceptance of a wide community.

We invite architects and key developers to review the current organisation of libraries and to propose an evolution if it proves necessary.

This proposal was rejected at the level of the architects (3:1) In fact, it was never discussed on pure technical grounds.

Blueprint RTAG & ROOT

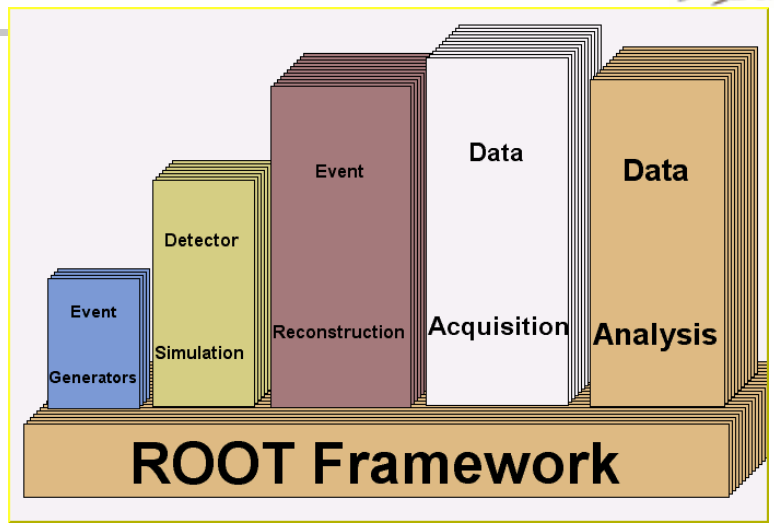
The ROOT data analysis framework is widely used in HENP and beyond, and is being heavily used by the LHC experiments and the LCG. We see the LCG software as a user of ROOT; a user with a very close relationship with the ROOT team. While the ROOT team is highly attuned and responsive to the needs of the LHC experiments, it also supports a large and diverse non-LHC community (including many major HENP experiments) with its own requirements, not least the stability of ROOT itself.
It is impractical for LCG software architecture and development to be tightly coupled to ROOT and vice versa. We expect the user-provider relationship to work much better. The ROOT team has an excellent record of responsiveness to users. So while ROOT will be used at the core of much LCG software for the foreseeable future, there will always be a 'line' with ROOT proper on one side and LCG software on the other.
ROOT itself will grow and change over time. Decisions on making use of ROOT in the implementation of LCG software components should be made on a case by case basis, driven by the circumstances. Despite the user-provider relationship, LCG software may nonetheless place architectural, organizational or other demands on ROOT. For example, the library organization and factorization of ROOT will impact component interdependencies in LCG software employing ROOT implementations and may drive changes in the organization and/or factorization.

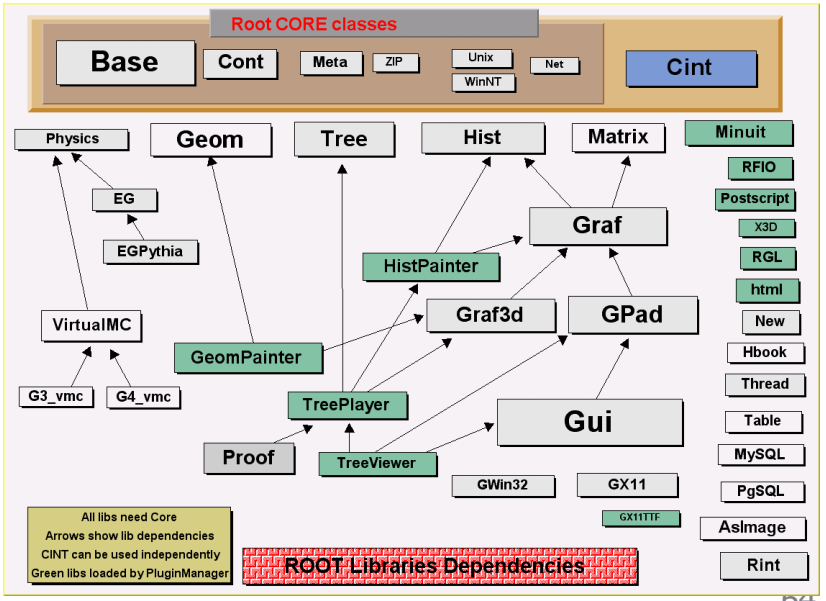
Blueprint RTAG impressions

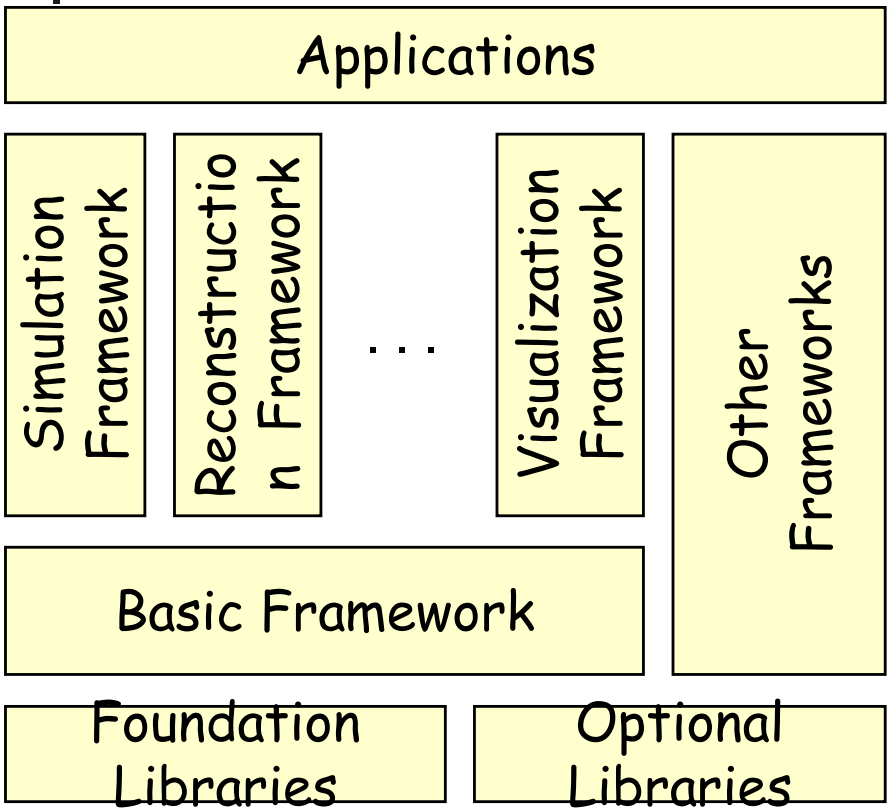
- We had useful meetings, sometime hot meetings.
- An opportunity to discuss many topics (first time since many years!). Dialog is better than wars.
- There is nothing wrong if there are some divergences. Uniformity is a bad sign.
- We had input from architects and some experts. I hope that we will get feedback now from end users.
- Torre, as application area coordinator, has done a great job in just a few months.
- There are a few but important points where I positively disagree with him (next slides).

Software Structure

Picture from 1995

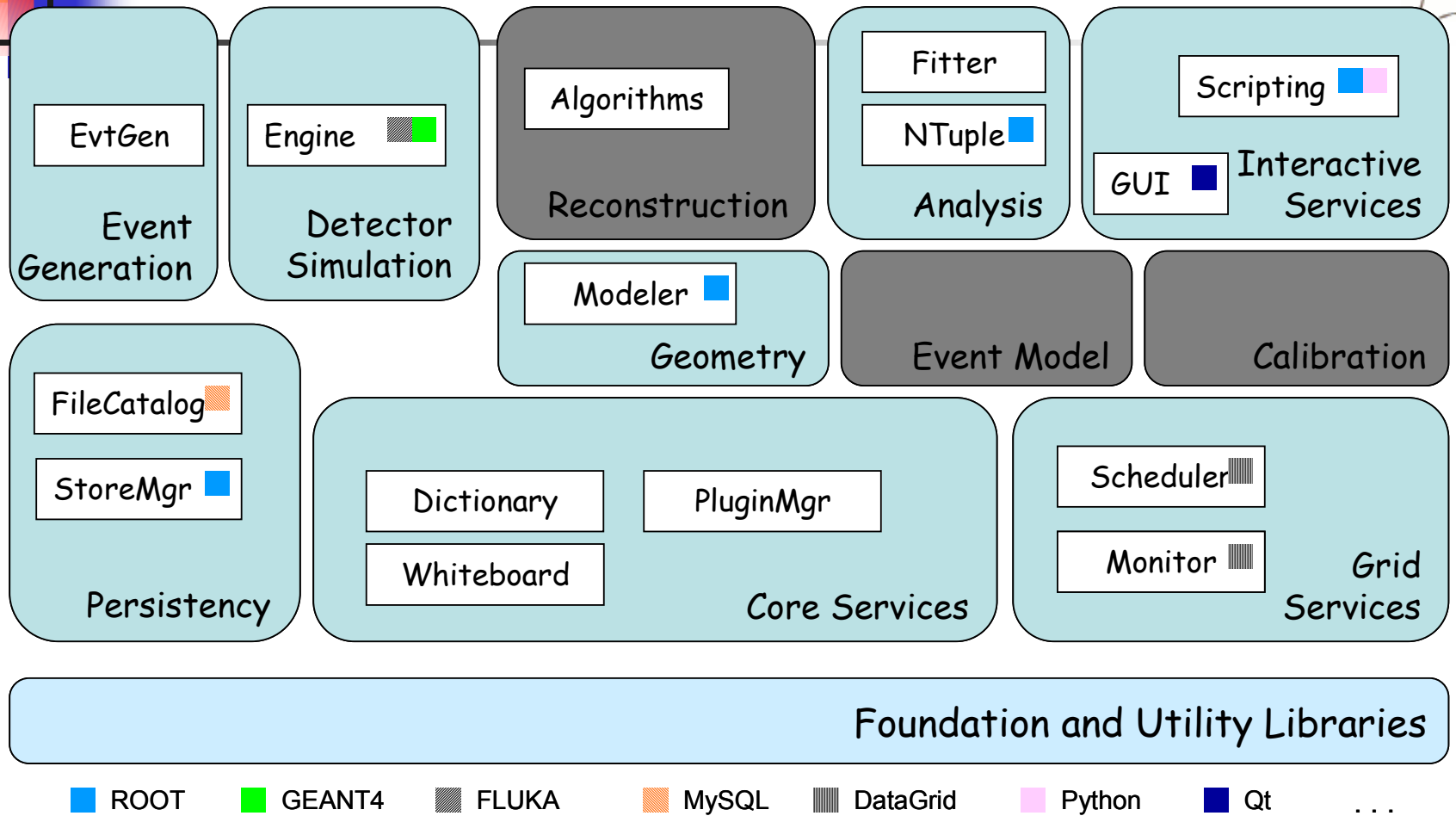






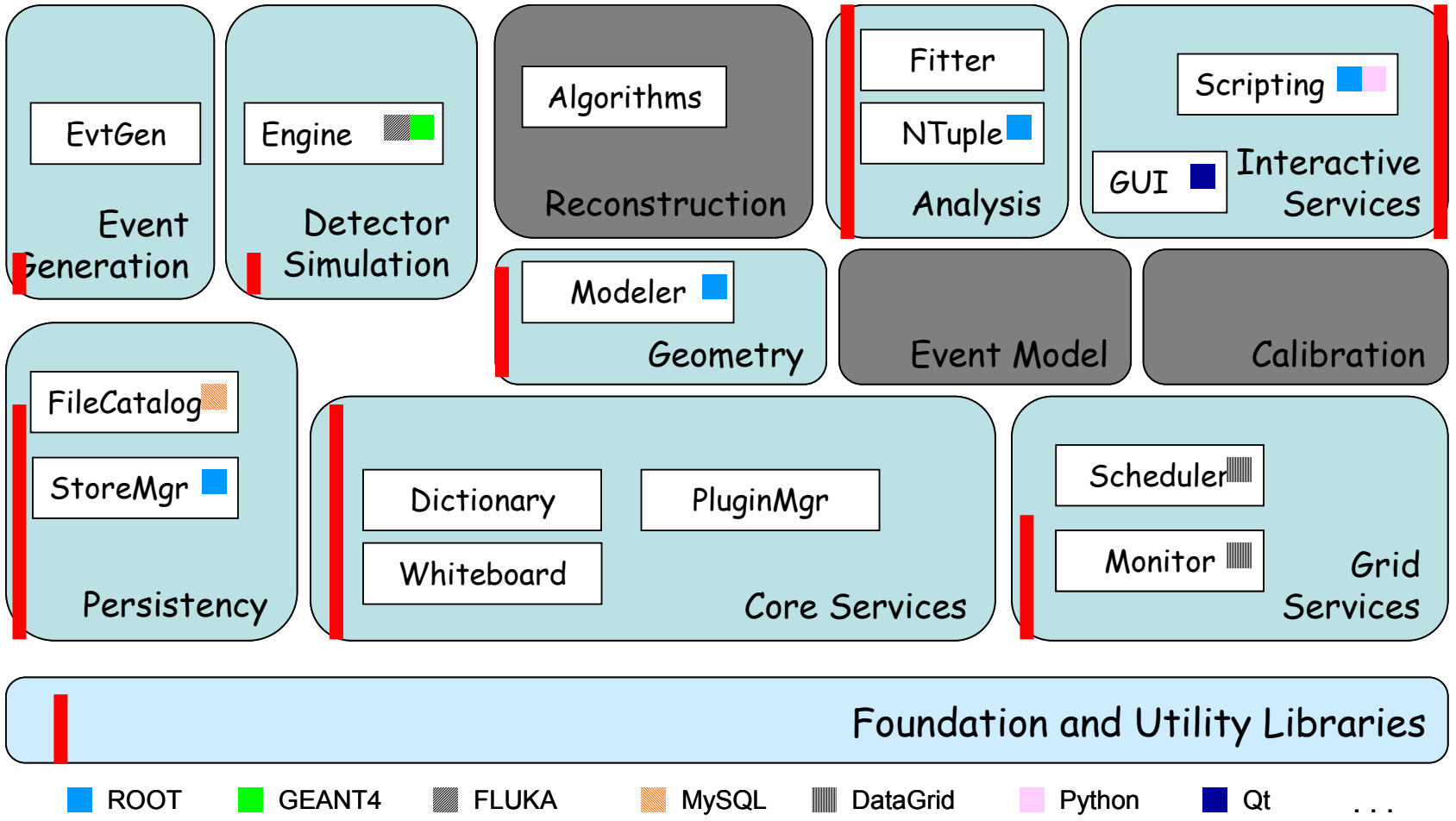
Blueprint RTAG 2002

Domain Decomposition

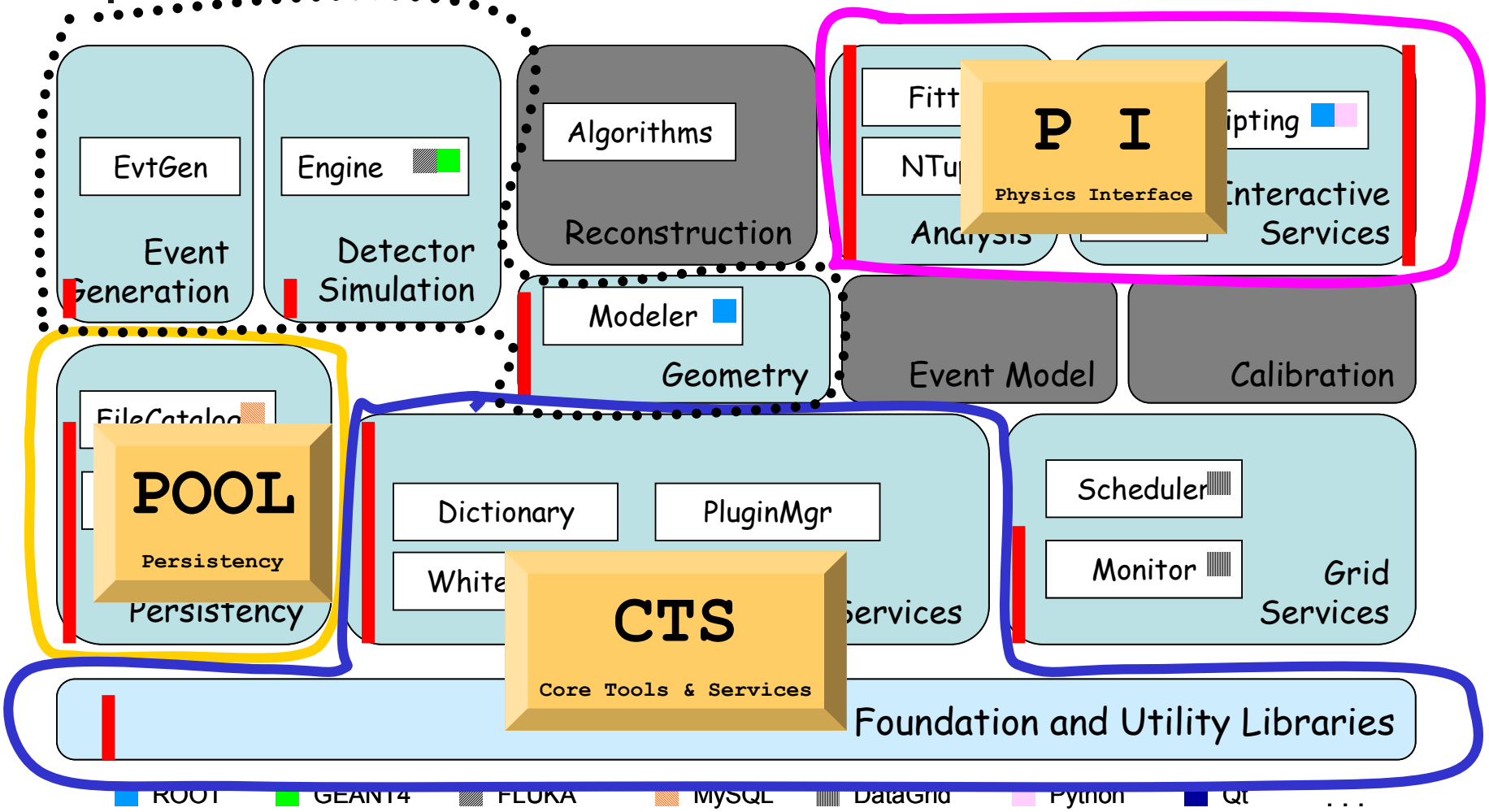


Products mentioned are examples; not a comprehensive list

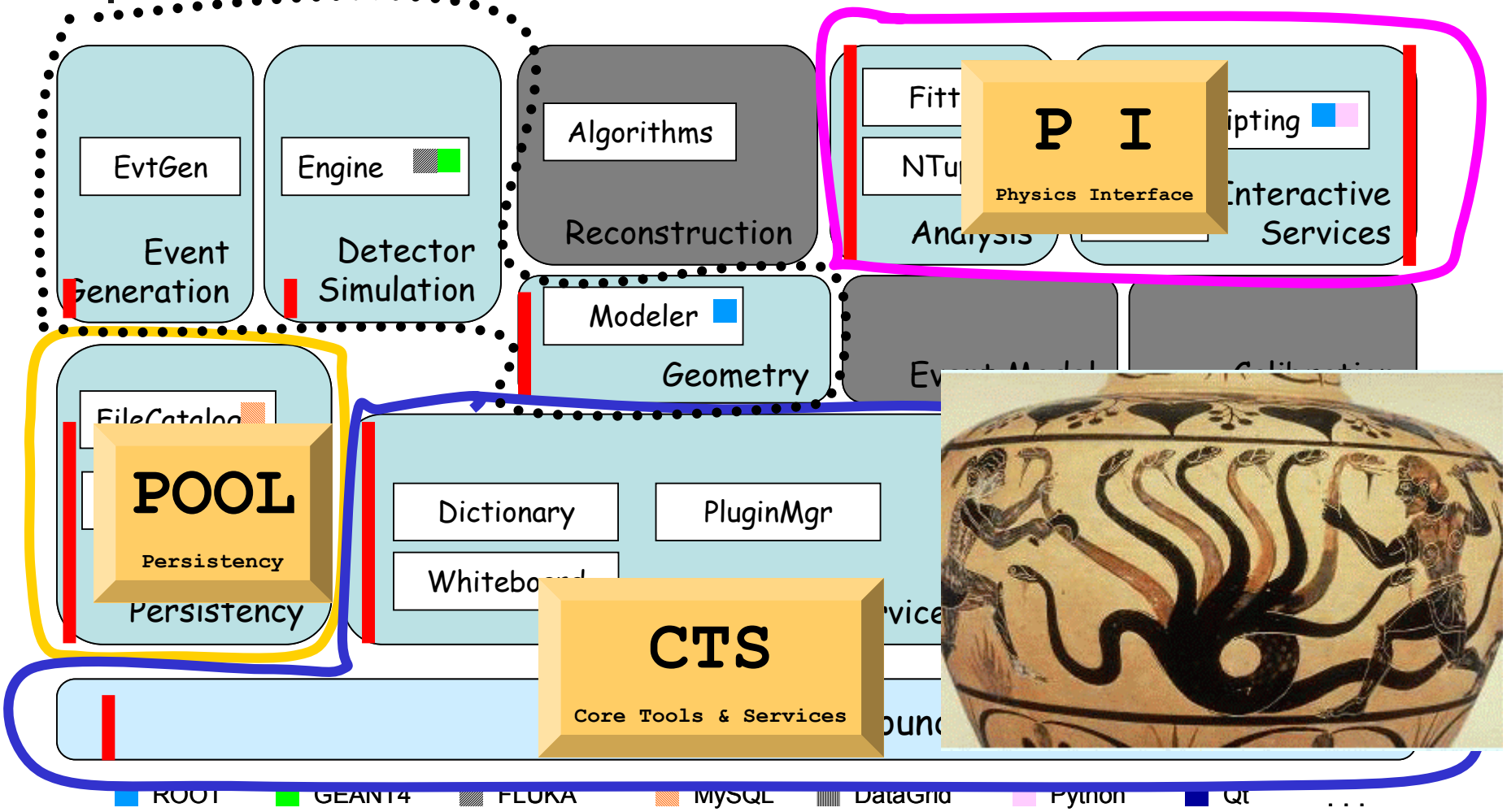
Domain Decomposition
What ROOT covers in red



Domain Decomposition
LCG proposed projects



Domain Decomposition
LCG proposed projects

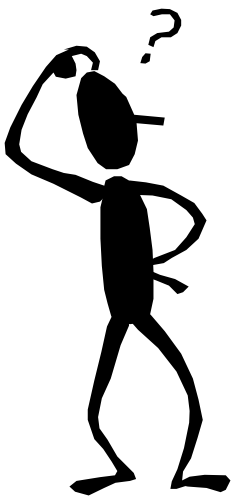


LCG proposed projects

- Scenario 1
- Scenario 2
- Scenario 3

Two extreme views on the LCG proposal

A simple alternative model



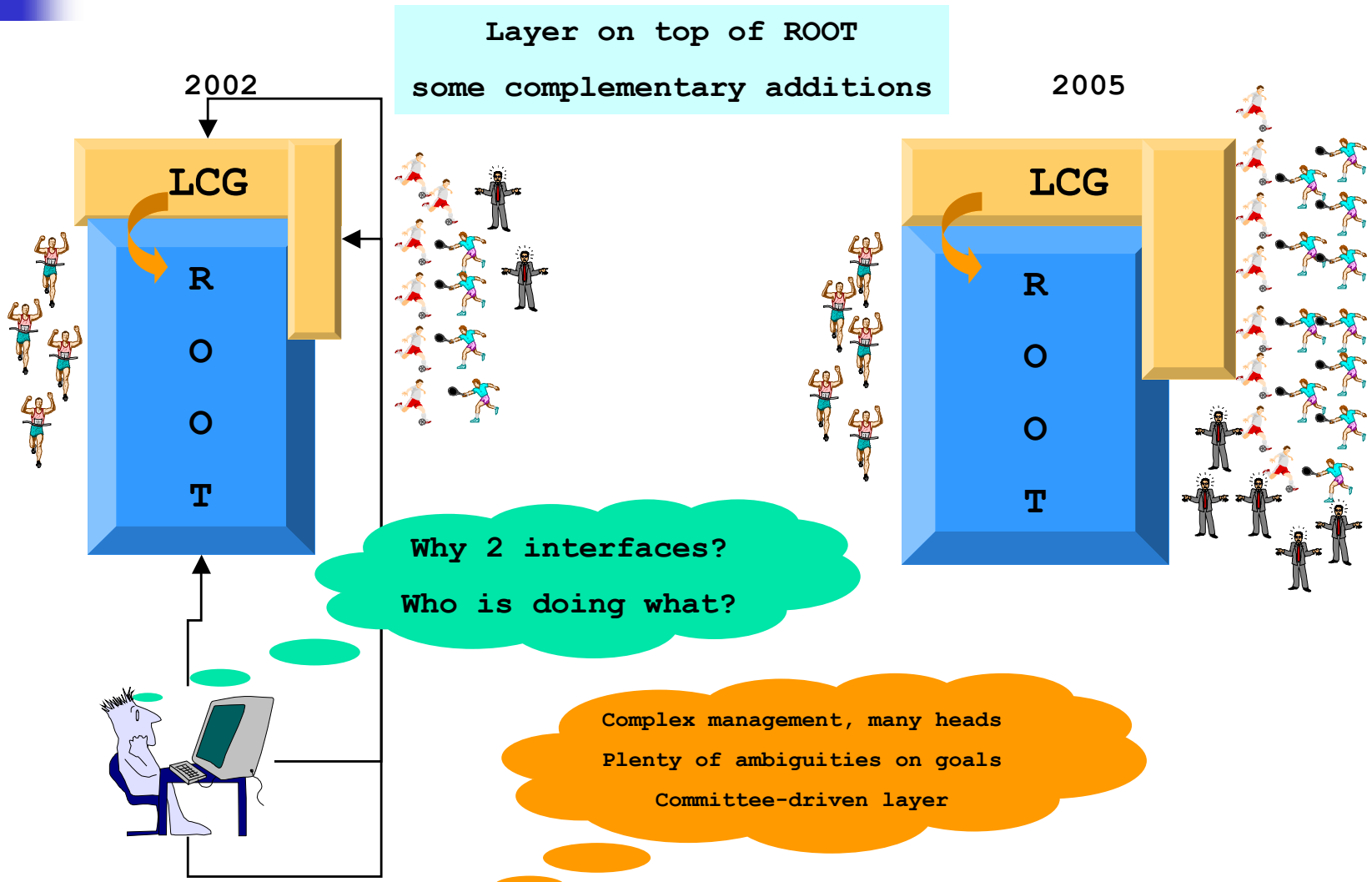
We more or less agree on the domain decomposition.

We agree that RTAGS are necessary and useful..

The mapping between domains and responsibilities is wrong

LCG - ROOT : Scenario 1

My understanding of the LCG proposal

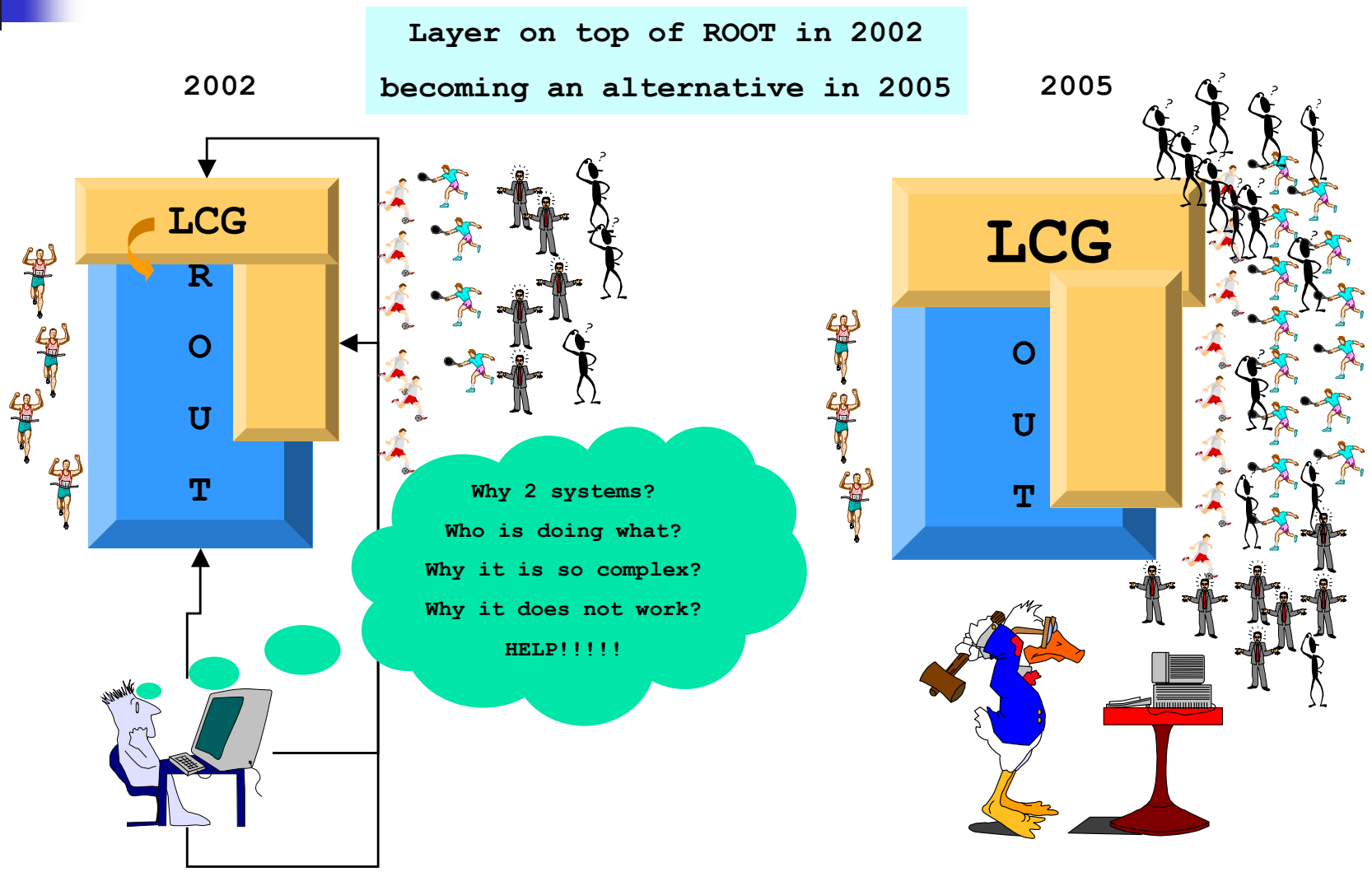


LCG - ROOT : Scenario 1 comments

- Assuming that S1 is the way to go, we will provide the best possible service (as provider).
- We anticipate a committee-driven system that will not be in the interest of the users.
- It will be difficult to maintain a coherent view between ROOT and the other projects working in the same domains.
- Cannot be a motivating environment because you cannot be creative in this context.
- Motivation will come from the large ROOT users base (LHC being a fraction only).

LCG - ROOT : Scenario 2

The conditions for a failure



LCG - ROOT : Scenario 2 Comments

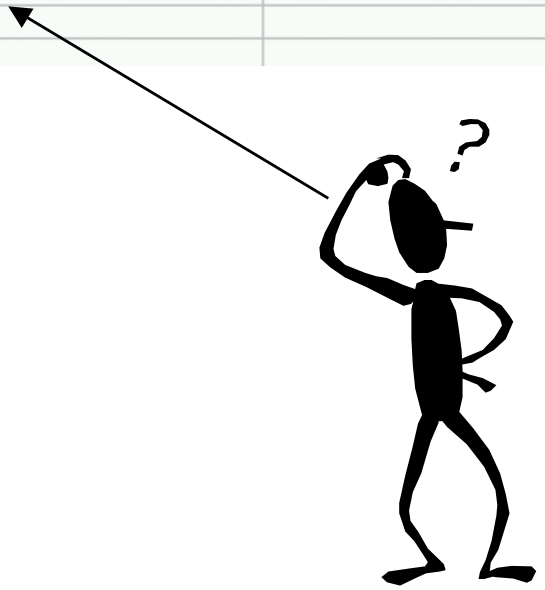
- The risk is that Scenario 1 may drift gradually to Scenario 2.
- User-Provider relation at the beginning
- Parts of ROOT copied to the new project
- Two parallel projects
- ROOT: seen as a pain in the neck
- We better stop ROOT now in the LCG context if the "secret idea" is to follow this scenario.

Personnel resources

Approximate expected resources:	
20	LCG (17 now)
3	CERN IT DB
5	CERN IT API G4
5	CERN IT API other
5	CERN EP non-expt
10	ATLAS
0	ALICE (currently forseen contributions of 4 FTEs come through ROOT)
10	CMS
3	LHCb
61	**Total**

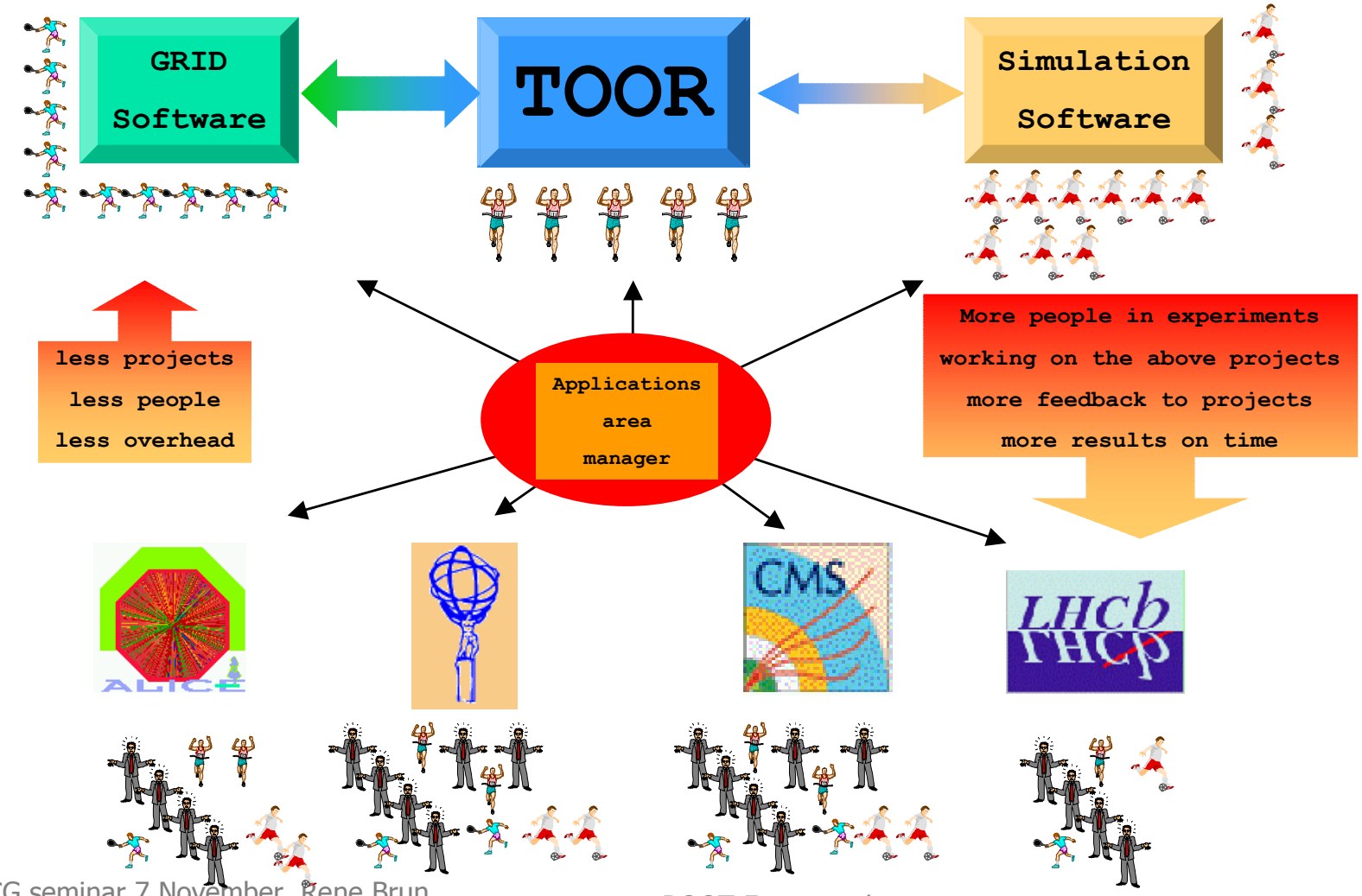
These are contributions to LCG software.
ROOT contributions are not shown here;
the LCG software will be a user of ROOT.

These numbers are all very approximate.



LCG - ROOT : Scenario 3

The conditions for success



LCG - ROOT : Scenario 3 comments

- More realistic mapping of existing responsibilities
- Clear path for ROOT and users
- Minimize possible divergences
- Facilitate the task of the applications coordinator, but gives him more responsibility.
- Easier to monitor progress
- Increase useful manpower in experiments

Summary 1

- We have developed a simple and powerful framework now in use by thousands of people in most HEP labs.
- We have many outside contributors.
- As already expressed to the Blueprint architects, we are willing to discuss the evolution of ROOT in close cooperation with the LHC experiments.
- Scenario 1 & 2 will end-up into fights and fat systems. It is our duty to ring the bell!
- We invite end-users in LHC experiments to reassess the situation in view of the realistic scenario 3.

Summary 2

- Software is not a technical problem. It is mainly a sociological problem.
- It is easy to write many lines of code. It is more difficult to give a momentum to a system.
- Our goal should not be to write software per se, but to make sure we deliver a simple, robust, coherent framework in time for the LHC.
- We must create the conditions to remove all possible ambiguities on the path to follow.
- Users must give feedback now, not in 2005.