



Recent Developments in ROOT I/O

Support for foreign classes

LCG meeting

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<ftp://root.cern.ch/root/foreign.ppt>

Evolution of ROOT I/O



1995

- Hand-written Streamers
- Streamers generated via rootcint
- Support for Class Versions
- Support for ByteCount
- Several attempts to introduce automatic class evolution
- Persistent class Dictionary (StreamerInfo) written to files
- rootcint modified to generate automatic Streamers
- can generate code for "DataObjects" classes in a file
- Support for STL and more complex C++ cases
- Trees take advantage of the new scheme
- Can read files without the classes
- Persistent Reference pointers
- Support for foreign classes



3.00

3.01

3.02

New

3.03

2002

PSimHit.h



```
#include "LocalPoint.h"
#include "LocalVector.h"
#include "TObject.h"

class DetUnit;

class PSimHit : public TObject {
public:

    PSimHit() : theDetUnitId(-1) {}
    PSimHit( const Local3DPoint& entry, const Local3DPoint& exit,
            float pabs, float tof, float eloss, int particleType,
            int detId, unsigned int trackId) :
        theEntryPoint( entry), theExitPoint(exit),
        .....

    float      pabs()          const {return thePabs;}
    float      tof()           const {return theTof;}
    float      energyLoss()    const {return theEnergyLoss;}
    int        particleType()  const {return theParticleType;}
    int        detUnitId()     const {return theDetUnitId;}
    unsigned int trackId()     const {return theTrackId;}

private:

    // properties
    Local3DPoint theEntryPoint; // position
    Local3DPoint theExitPoint;
    float        thePabs;      // momentum
    float        theTof;       // Time Of Flight
    float        theEnergyLoss; // Energy loss
    int          theParticleType;

    // association
    int          theDetUnitId;
    unsigned int theTrackId;

    ClassDef(PSimHit,1)
};
```

```
#include "LocalTag.h"
#include "Point2DBase.h"
#include "Point3DBase.h"
```

```
typedef Point2DBase< float, LocalTag> Local2DPoint;
typedef Point3DBase< float, LocalTag> Local3DPoint;
```

```
// Local points are two-dimensional by default
typedef Local3DPoint      LocalPoint;
```

Point3DBase.h



```
#include "PV3DBase.h"
#include "Point2DBase.h"
#include "Vector3DBase.h"
#include "Rtypes.h"

template <class T, class FrameTag>
class Point3DBase : public PV3DBase< T, PointTag, FrameTag> {
public:

    typedef PV3DBase< T, PointTag, FrameTag>      BaseClass;
    typedef Vector3DBase< T, FrameTag>           VectorType;
    typedef Basic3DVector<T>                    BasicVectorType;

    Point3DBase() {}

    Point3DBase(const T& x, const T& y, const T& z) : BaseClass(x, y, z)
    {}

    .....
    ClassDefT(Point3DBase,1)
    };
    ClassDef2T2(Point3DBase, T, FrameTag)
```

Basic3DVector.h



```
#include "Basic2DVector.h"
#include <iosfwd>
#include <cmath>
#include "Rtypes.h"

template < class T>
class Basic3DVector {

public:
    // default constructor
    Basic3DVector() : theX(0), theY(0), theZ(0){}

    Basic3DVector( const T& x, const T& y, const T& z) :
        theX(x), theY(y), theZ(z) {}

    T x() const { return theX;}
    T y() const { return theY;}
    T z() const { return theZ;}
    ....
private:
    T theX;
    T theY;
    T theZ;

ClassDefT(Basic3DVector,1)
};
ClassDefT2(Basic3DVector,T)
```

Running rootcint on PSimHit.h

Building the shared lib



```
rootcint -f Dict.cxx -c PSimHit.h LinkDef.h
g++ -fPIC -I$ROOTSYS/include -c Dict.cxx
g++ -fPIC -I$ROOTSYS/include -c PSimHit.cxx
g++ -shared -g PSimHit.o Dict.o -o libHit.so
```

```
#pragma link off all globals;
#pragma link off all classes;
#pragma link off all functions;
```

```
#pragma link C++ class LocalTag+;
#pragma link C++ class PointTag+;
#pragma link C++ class VectorTag+;
#pragma link C++ class Basic2DVector<float>+;
#pragma link C++ class Basic3DVector<float>+;
#pragma link C++ class PV2DBase<float, VectorTag, LocalTag>+;
#pragma link C++ class PV2DBase<float, PointTag, LocalTag>+;
#pragma link C++ class PV3DBase<float, VectorTag, LocalTag>+;
#pragma link C++ class PV3DBase<float, PointTag, LocalTag>+;
#pragma link C++ class Vector2DBase<float, LocalTag>+;
#pragma link C++ class Vector3DBase<float, LocalTag>+;
#pragma link C++ class Point2DBase<float, LocalTag>+;
#pragma link C++ class Point3DBase<float, LocalTag>+;
#pragma link C++ class PSimHit+;
```

LinkDef.h

Classes used by PSimHit
use C++ templates
heavily
All Template instances
must be declared

Writing CMS PSimHit objects



```
void demol() {
    //create a new ROOT file
    TFile f("demol.root","recreate");

    //Create a PSimHit with the default constructor
    PSimHit h1;

    //Write it to the file with the key name hit1
    h1.Write("hit1");

    //Create a normal PSimHit with the entry and exit point
    Local3DPoint pentry(1,2,3);
    Local3DPoint pexit(10,20,30);
    float pabs      = 41;
    float tof       = 1.67e-8;
    float eloss     = 5.78e-3;
    int  pType      = 12;
    int  detId      = 67;
    int  trackId    = 1234;
    PSimHit h2(pentry,pexit,pabs,tof,eloss,pType,detId,trackId);

    //Write it to the file with the key name hit2
    h2.Write("hit2");
}
```

Reading CMS PSimHit objects



```
void demo2() {
    //connect the ROOT file demo1.root in readonly mode
    TFile *f = new TFile("demo1.root");

    //Read hit2
    PSimHit *hit = (PSimHit*)f->Get("hit2");

    //print some hit members
    cout <<" X1= "<<hit->entryPoint().x()
         <<" Y2= "<<hit->exitPoint().y()
         <<" pabs= "<<hit.pabs()<<endl;
    delete hit;

    //Open the ROOT browser and inspect the file
    new TBrowser;

    //click on "ROOT files", then "demo1.root", with the
    //right button, select menu items "Inspect", "DrawClass"
    //on hit2
}
```


Browsing the file



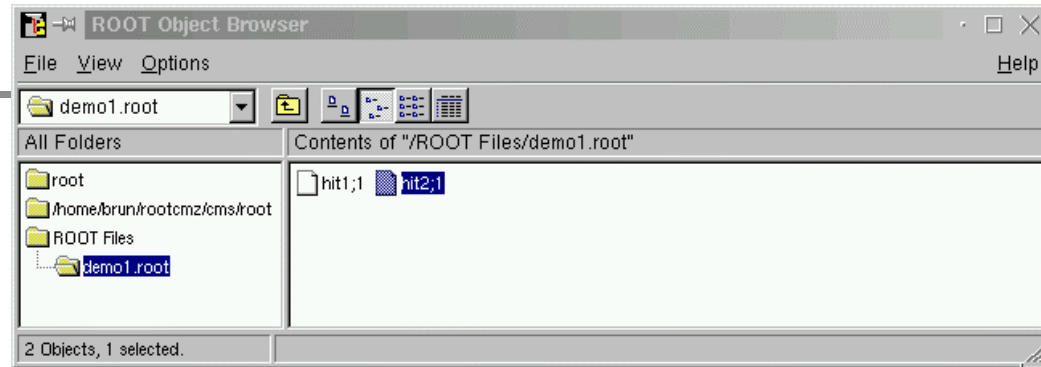
```
root [0] TFile f("demo1.root")
root [1] TBrowser b
root [2] f.ls();
```

TFile* demo1.root
KEY: PSimHit hit1;1
KEY: PSimHit hit2;1

```
root [3] f.Map();
```

```
root [4] hit2.Dump();
```

```
theEntryPoint      ->874a01c   position
theEntryPoint.theVector ->874a01c
theEntryPoint.theVector.theX 1
theEntryPoint.theVector.theY 2
theEntryPoint.theVector.theZ 3
theExitPoint       ->874a030
theExitPoint.theVector ->874a030
theExitPoint.theVector.theX 10
theExitPoint.theVector.theY 20
theExitPoint.theVector.theZ 30
thePabs            41          momentum
theTof             1.67e-08    Time Of Flight
theEnergyLoss      0.00578     Energy loss
theParticleType    12
theDetUnitId       67
theTrackId         1234
fUniqueID          0          object unique identifier
fBits              50331648    bit field status word
```



```
20011008/091050 At:64      N=86      TFile
20011008/091050 At:150     N=128     KeysList
Address = 278 Nbytes = -27 =====G A P=====
20011008/091050 At:305     N=140     PSimHit
20011008/091050 At:445     N=140     PSimHit
20011008/091050 At:585     N=952     StreamerInfo CX = 2.66
20011008/091050 At:1537    N=64      FreeSegments
20011008/091050 At:1601    N=1       END
```

The description of all classes in a file is written in one single record when the file is closed
StreamerInfo



ClassDef/ClassImp changes



We have redesigned the **ClassDef/ClassImp** facility to drastically reduce the number of macros necessary. We are down to 3 macros for all the situations. The only macro required is now **ClassDef**. In particular, **ClassDefT** and all its variations are now obsolete. **ClassImp** (and **templateClassImp** for class template) are not compulsory anymore and are now used only to record the location of the implementation file. One future extension will be to allow the registering of more than one implementation file.

This upgrade is intended to be backward compatible ... `__unless__` you have implemented your own **ClassImp** type of macro.

Note that it requires a complete regeneration of ALL the dictionaries.

Point3DBase.h



```
#include "PV3DBase.h"
#include "Point2DBase.h"
#include "Vector3DBase.h"
#include "Rtypes.h"

template <class T, class FrameTag>
class Point3DBase : public PV3DBase< T, PointTag, FrameTag> {
public:

    typedef PV3DBase< T, PointTag, FrameTag>      BaseClass;
    typedef Vector3DBase< T, FrameTag>           VectorType;
    typedef Basic3DVector<T>                     BasicVectorType;

    Point3DBase() {}

    Point3DBase(const T& x, const T& y, const T& z) : BaseClass(x, y, z)
    {}

    .....
    ClassDef(Point3DBase,1)
};
```

Basic3DVector.h



```
#include "Basic2DVector.h"
#include <iosfwd>
#include <cmath>
#include "Rtypes.h"

template < class T>
class Basic3DVector {

public:
    // default constructor
    Basic3DVector() : theX(0), theY(0), theZ(0){}

    Basic3DVector( const T& x, const T& y, const T& z) :
        theX(x), theY(y), theZ(z) {}

    T x() const { return theX;}
    T y() const { return theY;}
    T z() const { return theZ;}
    ....
private:
    T theX;
    T theY;
    T theZ;

ClassDef (Basic3DVector,1)
};
```



Support for foreign classes

- Foreign classes (not instrumented with ROOT includes, ClassDef, etc) can be parsed by a new version of **rootcint** to produce the necessary code for computing the members offsets.
- The **TStreamerInfo** class has also some mods to digest foreign classes.
- Current implementation using a **shadow class**
 - **Vincenzo** (define public private) was also implemented but could not be used with VC++
 - **Victor** currently testing a new idea that could simplify the whole process if it works everywhere

Point3DBase.h



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#include "Vector3DBase.h"

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public:

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    Point3DBase() {}

    Point3DBase(const T& x, const T& y, const T& z) : BaseClass(x, y, z)
    {}

    .....
};
```

Browsing the file



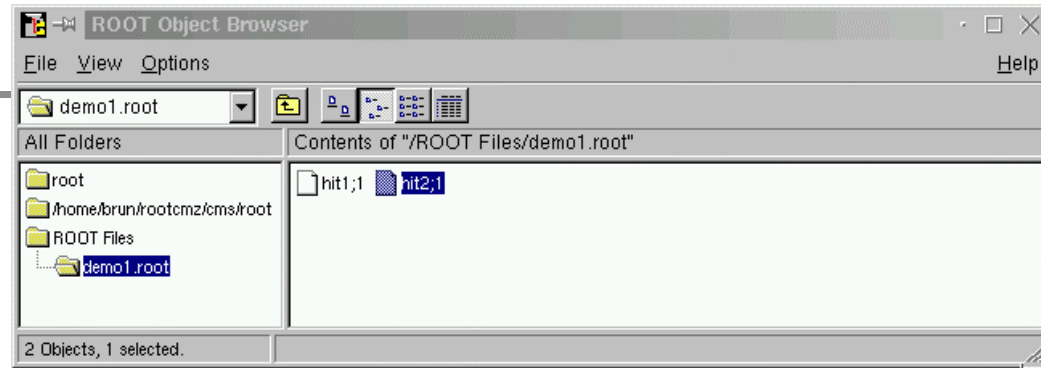
```
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root [1] TBrowser b
root [2] f.ls();
```

TFile* demo1.root
KEY: PSimHit hit1;1
KEY: PSimHit hit2;1

```
root [3] f.Map();
```

```
root [4] hit2.Dump();
```

```
theEntryPoint          ->874a01c   position
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theEntryPoint.theVector.theX 1
theEntryPoint.theVector.theY 2
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theExitPoint.theVector ->874a030
theExitPoint.theVector.theX 10
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thePabs                41          momentum
theTof                 1.67e-08    Time Of Flight
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fUniqueID              0          object unique identifier
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20011008/091050	At:1537	N=64	FreeSegments
20011008/091050	At:1601	N=1	END



STL support for foreign classes



- Several recent improvements by **Victor** in **rootcint**.
- In particular **Victor** has added support for all **STL containers** in foreign classes.
- Currently the code to support STL is generated in **rootcint**. We hope to provide native support in **TStreamerInfo** for **vector<myClass>** like we do for **TClonesArray**.