

SEESAW, SUSY
AND $SO(10)$

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TORINO, 04

BASC, SENJANOVIĆ, VISSANI, 01, 02, 04
AZARKH, BASC, HELFO,
SENJANOVIĆ, VISSANI, 03, 04

SEESAW

LEFTHANDED
NEUTRINO

$$(B-L)(\nu) = -1$$



ν E DOUBLET
OF $SU(2)_L$



IF LR SYMMETRY
ASSUMED

$$(B-L)(\nu^c) = +1$$



ν^c E DOUBLET
OF $SU(2)_R$
(SM SINGLET)



$M_{\nu R} \propto \langle \Delta_R \rangle$ — TRIplet
OF $SU(2)_R$

LARGE (MAJORANA MASS)

MAJORANA

$$\nu^c M_{\nu R} \nu^c + \nu^c M_{\nu D} \nu$$

DIRAC
 $M_{\nu D} \propto \langle \phi \rangle$

BIDoublet OF
 $SU(2)_L \times SU(2)_R$



INTEGRATE OUT
HEAVY ν^c

$$M_{\nu} = - M_{\nu D}^T M_{\nu R}^{-1} M_{\nu D}$$

SMALL
MASS

- YANAGIDA
- GLASHOW
- GEU-MANN, RABOUD, SLANSKY
- KOMAPASRA, SENJHOUIC

ANOTHER CONTRIBUTION TO SEESAW

$$\nu^c M_{\nu R} \nu^c$$

COMES FROM

$$\nu^c \Delta_R \nu^c$$

$SU(2)_R$ TRIPLET

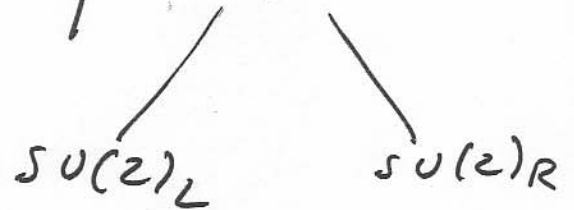


LR SYMMETRY

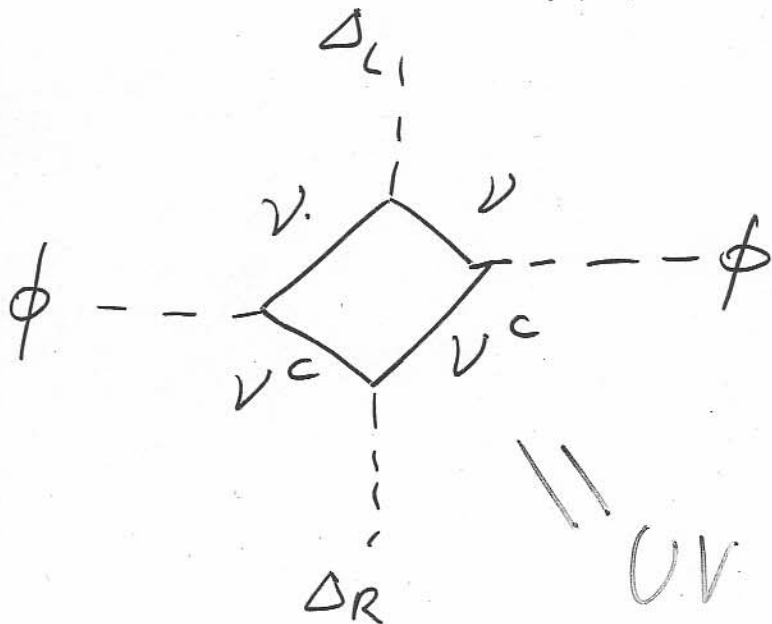
$$\nu \Delta_L \nu$$

$SU(2)_L$ TRIPLET

LR MODELS: $H, \bar{H} \longrightarrow \phi (2, 2)$



\Rightarrow TERM $\Delta_R \phi^2 \Delta_L$ PRESENT FROM



- $\nu^c \phi \nu$
- $\nu^c \Delta_R \nu^c$
- $\nu \Delta_L \nu$

UV DIVERGENT!

$$V = -M^2 (\Delta_R^2 + \Delta_L^2) + \Delta_R \phi^2 \Delta_L$$

\uparrow
 LARGE MASS

$$\Rightarrow \langle \Delta_L \rangle \approx \frac{\langle \Delta_R \phi^2 \rangle}{M^2} \sim \frac{M_w^2}{M}$$

SINCE $\langle \Delta_R \rangle \approx M$

$\langle \phi \rangle \approx M_w$

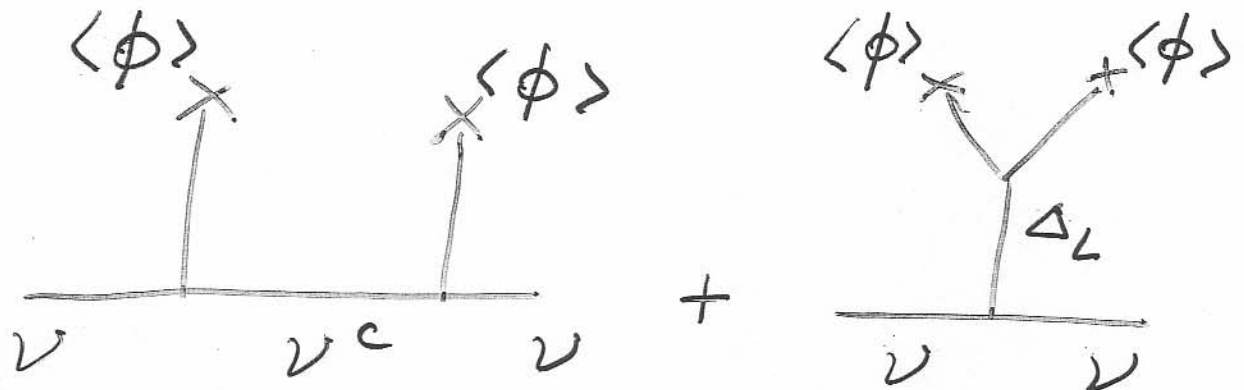
$$\Rightarrow \nu \langle \Delta_L \rangle \nu$$

\parallel
 $M_{\nu L}$

ANOTHER CONTRIBUTION
TO SEESAW

NEUTRINO MASS

$$M_N = -M_{\nu D}^T M_{\nu R}^{-1} M_{\nu D} + M_{\nu L}$$



$SU(2)_L$ SINGLET (ν^c)

$SU(2)_L$ TRIPLET (Δ_L)

TYPE I

TYPE II

OR

OR

CANONICAL
SEESAW

NONCANONICAL
SEESAW

IN GENERAL $M_{\nu L}$, $M_{\nu R}$, $M_{\nu D}$ ARBITRARY

- IMPORTANT TO CONNECT TO CHARGED FERMION SECTOR

- A FRAMEWORK NEEDED

\Rightarrow GRAND UNIFIED THEORY
($SO(10)$)

WHY GRANDUNIFICATION ?

- ① TOO MANY FORCES (3) IN SM.
- ② TOO MANY REPRESENTATIONS
(3 FAMILIES OF L, e^c, Q, u^c, d^c)
- ③ QUANTIZATION OF ELECTRIC CHARGE
(IN SM POSSIBLE EXPLANATIONS
— MAGNETIC MONOPOLES
— ANOMALY CANCELLATION)
↖
BOTH PRESENT IN GUT

1) FERMION MASSES AND MIXINGS

- GUTS ARE NOT THEORIES OF FLAVOUR.

- STILL ~~SOME~~ SOME CONSTRAINTS

MSSM

$$W_Y = H_Q Y_U u^c + \bar{H}_Q Y_D d^c + \bar{H}_L Y_E e^c$$

BUT IN A GUT

$$Q, L, u^c, d^c, e^c \subset \Psi$$

\Rightarrow RELATIONS BETWEEN Y_U, Y_D, Y_E ?

HOW TO IMPROVE THE FIT?

(1) NEW HIGGS REPRESENTATIONS

SU(5)

$$45_H = \overline{H}_{25}^P \left(= -\overline{H}_{59}^P \right)$$

$$\sum_{p=1}^5 \overline{H}_{ps}^P = 0$$

$$\Delta W_Y = \overline{45}_H \ 5 \ \overline{Y}_{45} \ 10$$

✓

SO(10)

- ANOTHER ~~10~~ $10_H \Rightarrow$
NOT ENOUGH

- $\theta_c \neq 0$ ✓

- $m_d = m_e$
 $m_s = m_\mu$
 $m_b = m_\tau$
SO(6) = SU(4)_c
NOT BROKEN
⇓
BAD!

- BUT $\overline{126}_H$ OK!

$$\Delta W_Y = \overline{126}_H \ 16 \ \overline{Y}_{126} \ 16$$

LAZARIDES, SHAFI,
WEISSERICH, 81
BABU, MOHAPATRA, 93

↓
MUST GET A VEV IN
(2, 2, 15)_H

↳ BREAKS SU(4)_c!

WITH 10_H AND $\overline{126}_H$:

$$W_Y = 10_H 16 \underset{10}{Y} 16 + \overline{126}_H 16 \underset{126}{Y} 16$$

UNDER PATI-SALAM $SU(2)_L \times SU(2)_R \times SU(4)_C$

$$10_H = \underline{(2, 2, 1)} + (1, 1, 6)$$

$$16 = (2, 1, 4) + (1, 2, \bar{4})$$

$$\overline{126}_H = \underline{(1, 3, 10)} + \overset{\uparrow \nu_R}{\underline{(3, 1, \bar{10})}} + \underline{(2, 2, 15)} + (1, 1, 6)$$

UNDERLINED HAS NONZERO VEV

$$M_{\nu_R} = \langle \underline{(1, 3, 10)} \rangle \underset{126}{Y}$$

= M_R (SCALE OF $SU(2)_R$ BREAKING)

✓
LARGE, $O(M_{GUT})$

③ NO FLAVOUR SYMMETRY

ONLY GUT - SO(10)

TO ENSURE AUTOMATICALLY
R-PARITY WE ARE FORCED

NOT TO USE $16_H + \overline{16}_H$,

BUT INSTEAD

$$126_H + \overline{126}_H$$

5 INDEX
ANTISYMMETRIC
(ANTI) SELF-DUAL

$$R = (-1)^{3(B-L) + 2S}$$

FOR BOSONS ($S=0$)

$$16 \xrightarrow{R} -16$$

$$126 \xrightarrow{R} +126$$

STABLE
LSP!

$$(B-L)_{\langle 16 \rangle} = 1$$

$$(B-L)_{\langle 126 \rangle} = 2$$

WE NEED BOTH

$$V_{10} = \langle (2, 2, 1)_{10} \rangle \neq 0 \quad \begin{pmatrix} V_{10}^u & 0 \\ 0 & V_{10}^d \end{pmatrix}$$

$$V_{126} = \langle (2, 2, 15)_{\overline{126}} \rangle \neq 0 \quad \begin{pmatrix} V_{126}^u & 0 \\ 0 & V_{126}^d \end{pmatrix}$$

$$M_U = V_{10}^u Y_{10} + V_{126}^u Y_{126}$$

$$M_d = V_{10}^d Y_{10} + V_{126}^d Y_{126}$$

$$M_{\nu_D} = V_{10}^u Y_{10} - 3 V_{126}^u Y_{126}$$

$$M_e = V_{10}^d Y_{10} - 3 V_{126}^d Y_{126}$$

$$M_{\nu_R} = \langle (1, 3, 10)_{\overline{126}} \rangle Y_{126} = \nu_R Y_{126}$$

$$M_{\nu_L} = \langle (3, 1, \overline{10})_{126} \rangle Y_{126} = \nu_L Y_{126}$$

$$\langle (2, 2, 15) \rangle \rightarrow \langle 15 \rangle = \begin{pmatrix} 1 \\ 1 \\ -3 \end{pmatrix} \propto (B-L)$$

SU(3) SINGLET

$$M_N = -M_{\nu_D}^T M_{\nu_R}^{-1} M_{\nu_D} + M_{\nu_L}$$

TYPE I
SEESAW

TYPE II
SEESAW

MODEL
DEPENDENT

$$\rightarrow \text{FROM } \left(\frac{v_{10}^d}{v_{10}^u} \right), \left(\frac{v_{126}^d}{v_{126}^u} \right), \left(\frac{v_L}{v_{126}^u} \right), \left(\frac{v_R}{v_{126}^u} \right)$$

DEFINE

$$X = \left(\frac{v_{10}^d}{v_{10}^u} \right) / \left(\frac{v_{126}^d}{v_{126}^u} \right)$$

$$y = \left(\frac{v_{10}^d}{v_{10}^u} \right)$$

$$\alpha = \frac{16}{X^2 \left(\frac{v_L}{v_{126}^u} \right) \left(\frac{v_R}{v_{126}^u} \right)}$$

$$\beta = \frac{4}{\left(\frac{v_R}{v_{126}^u} \right) \left(\frac{v_{126}^u}{v_{126}^d} \right)}$$

TO GET

$$\begin{aligned} \textcircled{1} \rightarrow (1-X)M_E &= 4yM_U - (3+X)M_D \\ \textcircled{2} \rightarrow \beta M_N &= -\alpha \left[\frac{3(1-X)M_D + (1+3X)M_E}{4} \right] (M_D - M_E)^{-1} \\ & * \left[\frac{3(1-X)M_D + (1+3X)M_E}{4} \right] + (M_D - M_E) \end{aligned}$$

→ SIMPLIFIED ANALYSIS

- 2ND AND 3RD GENERATIONS ONLY
- REAL PARAMETERS

$$D(1-x)M_E = 4yM_U - (3+x)M_D$$

KNOWN: $m_{\tau,\mu}$, $m_{\tau,c}$, $m_{b,s}$

+ ANGLE BETWEEN U AND D (θ_{cb})

UNKNOWN: x , y

+ ANGLE BETWEEN E AND D (θ_D)

3 EQUATIONS FOR 3 UNKNOWNNS

EQUATION

$$\textcircled{2} \beta M_N = -\alpha \left[\frac{3(1-x)M_D + (1+3x)M_E}{4} \right] * (M_D - M_E)^{-1} * \left[\frac{3(1-x)M_D + (1+3x)M_E}{4} \right] + (M_D - M_E)$$

DETERMINED UP TO α AND β :

$\alpha \rightarrow \infty$: TYPE I SEESAW

$\alpha \rightarrow 0$: TYPE II SEESAW

MIXED TYPE I + TYPE II CASE:

- ASSUME $m_2 \approx 0 \ll m_3$ (-2 GENERATIONS)
- FINITE θ_2 (- REAL)

$$\tan 2\theta_e = \frac{\sin(2\theta_2)}{2\sin^2\theta_2 - \Delta}$$

$$\Delta = \frac{1}{1-9\alpha} [-5\alpha + (1-4\alpha)\epsilon]$$

$$\epsilon = \frac{m_b - m_c}{m_b} \quad - \text{EXPERIMENTALLY SMALL}$$

TYPE I ($\alpha = \infty$) : $\Delta = \frac{5+4\epsilon}{9}$, θ_e SMALL

TYPE II ($\alpha = 0$) : $\Delta = \epsilon$, θ_e LARGE

TYPE II SEESAW FAVOURED

IF M_2 RESTORED ~~RESTORED~~

\Rightarrow 2 SOLUTIONS

$$\epsilon_u = \frac{\omega_e}{\omega_t}$$

$$\epsilon_d = \frac{\omega_s}{\omega_b}$$

$$\epsilon_e = \frac{\omega_\mu}{\omega_\tau}$$

$$\epsilon_i, \theta_q \sim 10^{-2}$$

$$\epsilon_i, \theta_q \sim \sigma(\delta)$$

1ST SOLUTION (~~OR~~ SMALL θ_D)

$$M_N \sim -\alpha \begin{pmatrix} \delta & \delta/\epsilon \\ \delta/\epsilon & 1/\epsilon \end{pmatrix} + \begin{pmatrix} \delta & \delta \\ \delta & \epsilon \end{pmatrix}$$

TYPE I

TYPE II

$$\tan 2\theta_e \simeq \frac{2\delta(1 + \frac{\alpha}{\epsilon})}{\delta(1 + \alpha) + \epsilon + \frac{\alpha}{\epsilon}}$$

- DUTA, MIHURA,
KOLAPATRA, 04
- BAC SENIANDVIĆ,
VISSANI, 04

$$\epsilon \sim \sigma(\delta) \quad b-\tau \text{ (EXP)}$$

$$\boxed{\theta_e \simeq \sigma(1) \Leftrightarrow \alpha \lesssim \sigma(\delta^2)} \quad (\text{TYPE II})$$

TYPE I ($\alpha \rightarrow \infty$) EXCLUDED $\Rightarrow \theta_e \simeq \sigma(\delta)$

2ND SOLUTION (LARGE θ_D)

$$M_N \sim -\alpha \begin{pmatrix} \delta^2 & \delta \\ \delta & 1 \end{pmatrix} + \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

$$\tan 2\theta_e \simeq \frac{1 + \alpha\delta}{1 + \alpha}$$

$$\boxed{\theta_e \simeq \sigma(1) \iff \alpha \lesssim \sigma(1)}$$

TYPE $\bar{4}$ OR MIXED

IN NO CASE $\alpha \rightarrow \infty$ (TYPE I)
CAN GIVE LARGE $\theta_e = \theta_{ATM}$

BAJC, SENJANOVIĆ, VISSANI, 04

POSSIBLE TO UNDERSTAND

WHY $\theta_{atm} \approx \text{LARGE}$ IN

TYPE II SEE-SAW:

$$M_{\nu L} \propto Y_{126}$$

$$\begin{cases} M_d = v_{10}^d Y_{10} + v_{126}^d Y_{126} \\ M_e = v_{10}^d Y_{10} - 3 v_{126}^d Y_{126} \end{cases}$$

$$\Rightarrow Y_{126} \propto M_d - M_e$$

$$\Rightarrow M_{\nu L} \propto M_d - M_e$$

BRAMHACHARI, MOHAPATRA, 98

APPROX.:

- 2-3 GENERATION CASE
- NEGLECT $m_{s,\mu} \ll m_{b,\tau}$
- M_d AND M_e HAVE SMALL MIXINGS

$$M_{\nu L} \propto \begin{pmatrix} 0 & 0 \\ 0 & m_b - m_\tau \end{pmatrix}$$

BAJC,
SENJANOVIĆ,
VISSANI, 02

LARGE $\theta_{atm} \iff b-\tau$ UNIFICATION

IN MINIMAL SUSY $SO(10)$:

- LARGE θ_{ATM} GOOD ARGUMENT FOR TYPE II SEESAW DOMINATION
- $b-\tau$ UNIFICATION COULD BE EXPLAINED
- ANOTHER SOLUTION (LARGE θ_D) WITH POSSIBLE MIXED TYPE I + II SEESAW