Two Particle Separation with tile HCAL

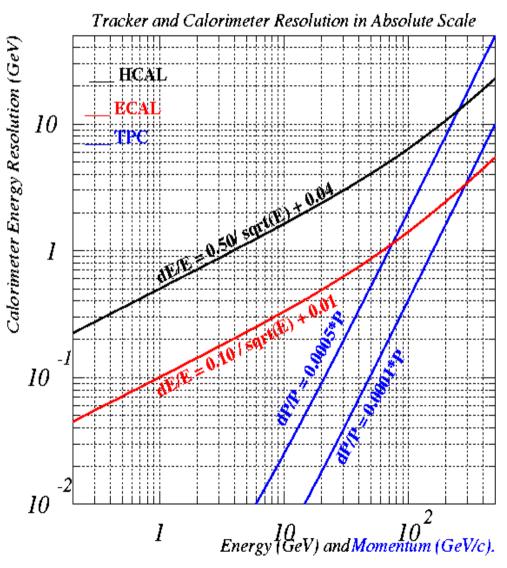
V.Morgunov, A.Raspereza



LC Workshop, Paris 20/4/2004

Particle Flow Concept

- ▶ P-flow concept : attempt to reconstruct every single particle in event
- Tracker information → 4P vectors of charged objects
- Ecal \rightarrow 4P vectors of photons
- Ecal + HCal → 4P vectors of neutral hadrons (contain ~ 14% of jet energy)
- ◆ Efficient separation of neutral and charged objects is an issue → highly granulated calorimeters are required



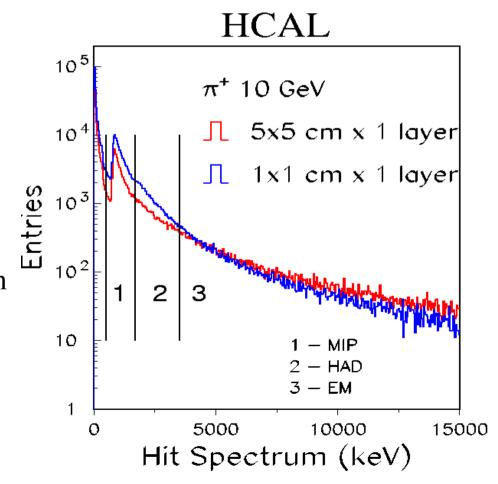
Simulation (Setup and Goals of Study)

- Goals
 - Develop shower reconstruction/separation procedure
 - Investigate shower separation capability of algorithm in dependence of calorimeter granularity, distance between showers, particle energies
- Simulation setup (closely follows envisaged prototype geometry)
 - 40 layers of ECAL layers 1-30: 1.4mm W, 1mm G10, 0.5mm Si, 1mm G10 layers 31-40: 4.2mm W, 1mm G10, 0.5mm Si, 1mm G10
 - 40 layers of tile HCAL (analog) each layer: 20mm Fe, 5mm Scintillator
- Studied tile size options / readout schemes:
 1x1cm² x 1lay, 3x3cm² x 1lay, 3x3cm² x 2lay, 5x5 cm² x 1lay
- Simulation is done with GEANT3, FLUKA+MICAP

Reconstruction Step #1 : Clustering

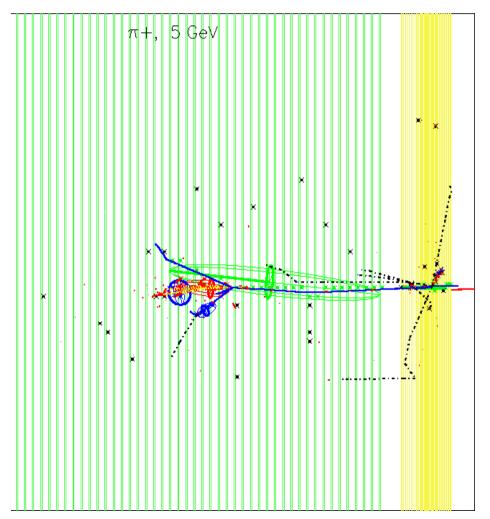
Two steps of reconstruction

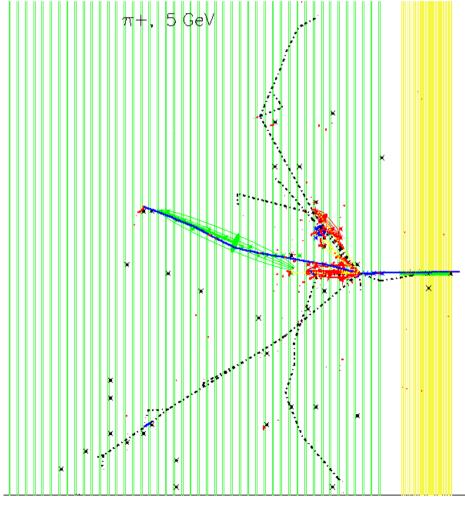
- 1. Clustering
- 2. Shower building
- Clusters: structures inside shower
- Hits are classified into 3 categories:
 - MIP: hits from single tracks
 - EM : high density hits
 - HAD: hits produced by group of close-by tracks in vicinity of nuclear interaction
- Clustering is performed separately on each category (clustering algorithm from <u>V.Morgunov</u>)
- Fourth hit category after clustering :
 - Neutron hits (spatially separated from reconstructed clusters)



Clustering (Event Displays)

CLUSTERS: MIP EM HAD NEUT



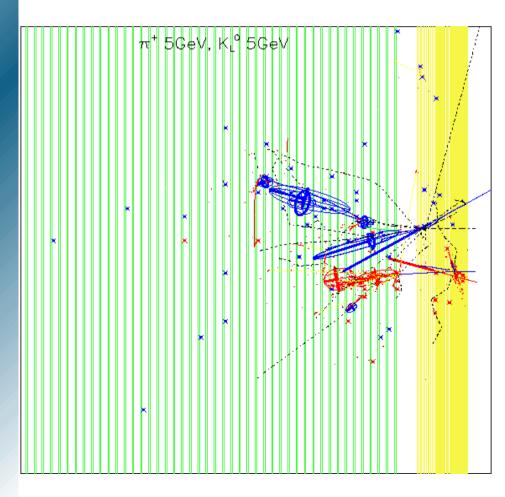


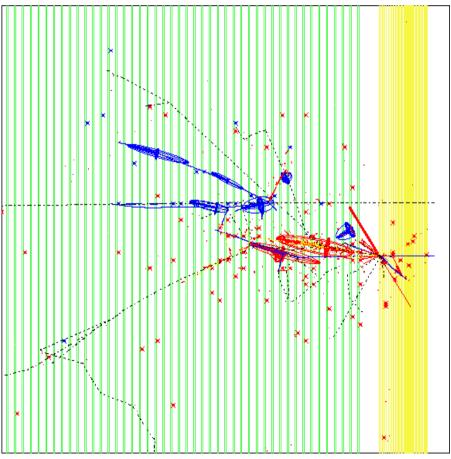
Step #2: Shower Reconstruction

- * Shower tree of HAD and EM clusters topologically connected by tracks (MIP clusters) + initiated by neutrons (spatially disconnected from tree) hits/clusters
- * Track reconstructed with tracking system seeds shower: find starting cluster (cluster closest to track intersection point with ECAL front plane)
- * Reconstruction of total shower by collecting clusters into tree and adding close neutron hits/clusters (iterative procedure : parameters governing shower reconstruction are iteratively adjusted till E_{shower} fits best P_{track}) \rightarrow algorithm is selfadaptive to HCAL segmentation
- * Remaining clusters/hits are assigned to neutral objects
- * Initial study: analysis of simple situation of two close by showers (neutral and charged)

Showers (Event Displays)

Two showers from 5GeV π^+ and 5GeV K^0 Distance – 15cm

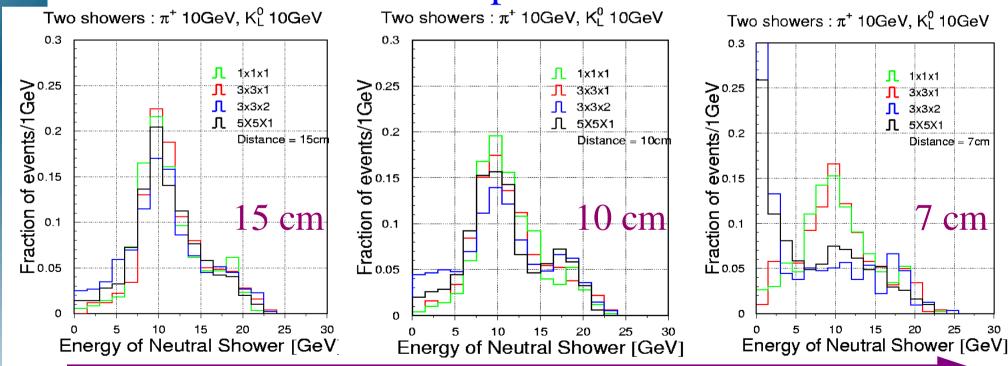




Shower Separation

Criterion to estimate performance:

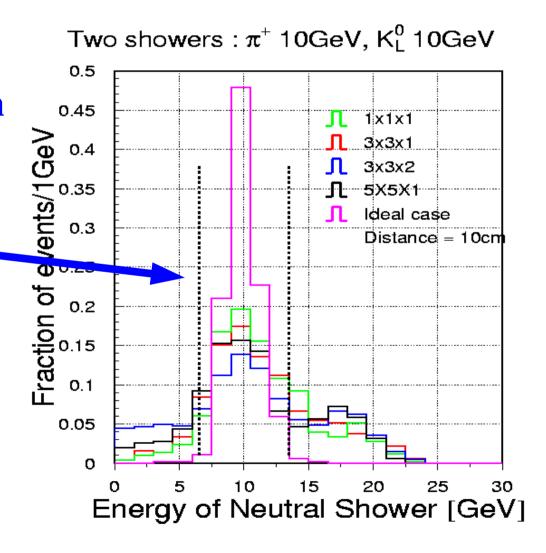
Energy spectrum of neutral shower as a function of distance between initial particles and HCAL tile size



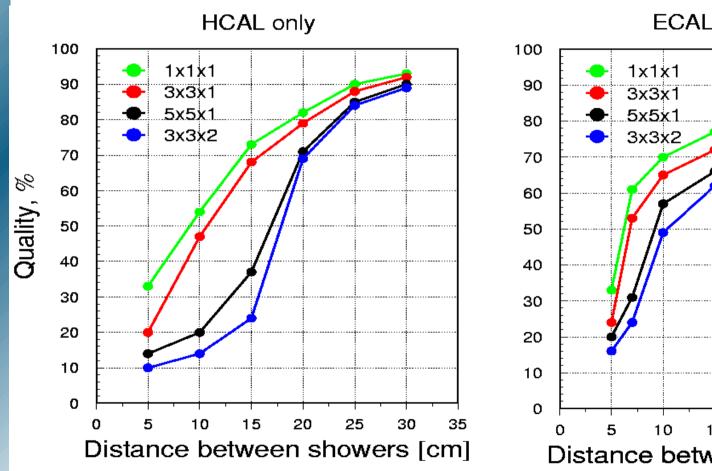
Definition of Shower Separation Quality

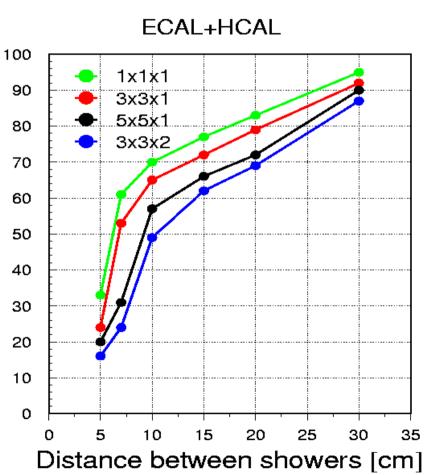
Separation quality = fraction of events in which reconstructed energy of neutral shower lies in the range E_{true} +/- 3σ , **σ**– nominal energy resolution of neutral shower (no close by

shower)

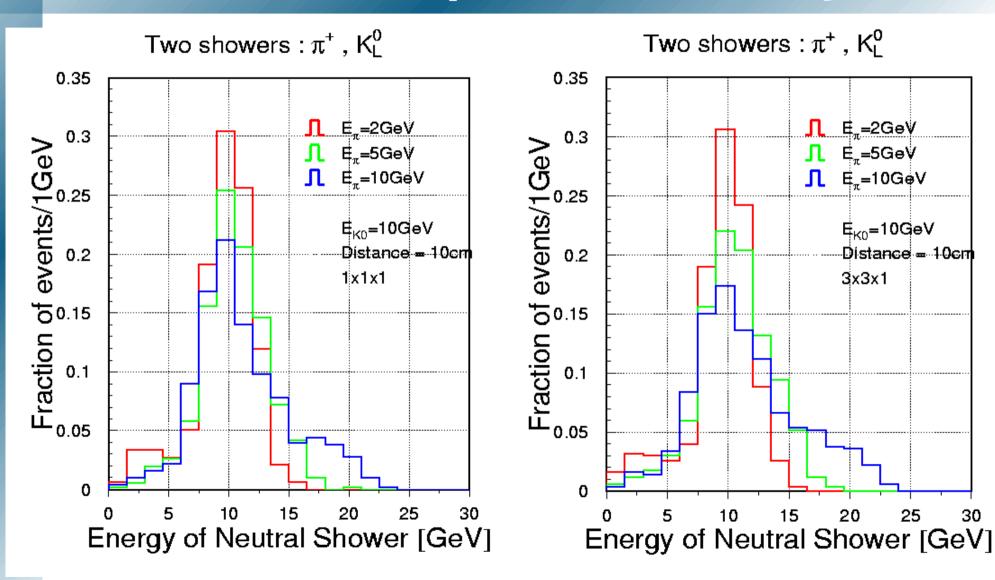


Separation Quality vs Transversal and Longitudinal Segmentation





Energy Dependence of Shower Separation Quality



Summary and Outlook

- Algorithm of shower separation / reconstruction is being developed within DESY CALO group
- First results showed that reconstruction quality is sensitive to transversal and longitudinal segmentation of tile HCAL
- Quality of reconstruction gets worse with increasing tile size and going to readout scheme when layers are joined in depth
- Further development/tuning of algorithm and more detailed study are planned (from simple two particle case to realistic jets)