# Reimplementation of the ATLAS Online Event Monitoring Subsystem

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- Online Monitoring
- Current implementation and its drawbacks
- My reimplementation
- Performance comparison
- Conclusion

## Getting the context: Atlas Online Software

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- System of the Atlas Trigger DAQ Project
- Main purpose: configure, control and monitor data acquisition system
- Provides a GUI, which allows to control the data acquisition system
- "Glue" of several TDAQ sub-systems
- Open Source project

TDAQ



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Detector









- Scalability problem due to bottleneck in machine A
- Monitors will not notice if sampler crashed
  - They just stop receiving events...
- Users will have to worry about thread management in sampler
  - Start thread on StartSampling
  - Cleanly exit it on StopSampling
  - Often causes problems



- Core of scalability problem: central distributor
- Bottleneck due to...
  - routing of events through central distributor
  - multiple distribution of identical events to different monitors



- Platform independent C++
- Using Online Monitoring IPC based on CORBA (omniORB 4)
- minimal and deterministic effect on the data flow system performance
- High scalability
- Get rid of all drawbacks... ;-)



- Sampler has to decide about criteria
  - $\rightarrow$  saves a lot of bandwidth
- Sampler has to send each event once (per selection criteria)
- Distributor necessary to protect sampler from inrushing monitors (gatekeeper function)

## **Basic improvement ideas**

- Get rid of distributor for communication  $\rightarrow$  P2P
- Moving load to monitors for means of scalability
  - Current: share bandwidth, accumulate load
  - Idea: share load, accumulate bandwidth ;-)
  - Distributor only for connection management and error recovery
- Keeping only crucial things in sampler
  - Criteria decisions

TDAQ

- One-time sending of each event (→ at least one connection per sampler/criteria)
- Sampler thread management
  - Start sampling thread with first subscription
  - End sampling thread with loss of last subscription
  - User code not aware of threads



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→ But: new problems arise with this structure



- Each monitor acts as a sampler for his children
- Exits/crashes of monitors critical...
- We have to distinguish between different types of exits
  - Leaf monitor → trivial
  - Monitor with outdegree > 0  $\rightarrow$  more complicated
  - Root monitor  $\rightarrow$  critical









- Crash of sampler
  - Distributor pings all samplers in reasonable intervals → can notify monitors about crash
- Crash of arbitrary monitors
  - Detected like normal exit! 
    no problem
- Crash of distributor
  - No influence on ongoing data exchange
  - Just restart...



	Current implementation	Reimplementation	$cr_i = \#$ criteria in sampler i s = # samplers $ch_i = \#$ children of monitor $C = \max$ . children/monitor a = # sampled bytes
Sampler <i>i</i>	$2 \cdot cr_i + e \cdot cr_i = O(e \cdot cr_i)$	$2 \cdot cr_i + e \cdot cr_i = O(e \cdot cr_i)$	m = # monitors
Monitor <i>i</i>	2 + e = O(e)	$2 + e + ch_i \cdot e = O(e)$	
Distributor	Init & Shutdown : $2m = O(m)$ Run : $e \cdot m + e \sum_{\substack{i=1 \\ \leq m}}^{s} cr_i \leq 2m \cdot e = O(m \cdot e)$	Init & Shutdown : $2m = O(m)$ Run : 0	



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Samplers in partition

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## Reimplementation fulfills all needs

- Improved speed
- As seen: Optimal scalability (constant!)
- Enhanced error recovery
- Configurable tradeoff between latency and CPU/bandwidth requirements (tree type unary, binary, ...)
- Users do not need to care about thread management



#### Infor your attention!

- Questions?
- Criticism?

