Beam Conditions Monitoring at CMS

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On behalf of the

CMS BCM project

<u>Outline</u>

- Why fast beam conditions monitoring within CMS
- The CMS BCM
- Location, location, location
- PCVDD as a sensor
- BCM Testbeam results and PCVDD benchmarks
- Back end logic
- Observations and Outlook

Radiation Monitoring: What CMS requires

- Provide an on-line monitor for beam conditions => BCM
 - Protection of sub- detectors from adverse beam conditions
 - Ability to request beam-abort
 - Optimization of beam Conditions
- Provide mapping of the radiation field => BCM + active/passive monitors
 - Benchmark activation simulations
 - There is a factor 3 uncertainty in the FLUKA simulations
 - Small and cheap active/passive monitors to measure dose (ionization) and particle fluence (displacement damage)
 - Identify leaks in the shielding
 - Map out activity prior to first shutdown
- Provide a long-term monitoring of integrated radiation exposure =>active/passive monitors +RAMSES
 - Post-mortem diagnosis in case of device failure
 - Tool for corrective measures for background mitigation
 - Activation levels for access

Fast Monitoring: The Beam Conditions Monitor

The BCM is to be the central component of the monitoring system

- Sensors placed close to beampipe (within the Pixel service-tube volume)
- Sensors have to discriminate bad beam conditions over normal running conditions
 ⇒ Other radiation monitors (passive or long sampling) will not see beam losses

Conditions at z=3m,r=4cm

- Normal pp background = $31 \text{mGy/sec} \Rightarrow 2.7 \text{ MIP equivalent/cm}^2$ per bunch crossing
- 1 proton on the TAS generates ~0.65nGy =>~2.3 MIP/cm² per bunch crossing
 - In the process of simulating # hits and energy distribution per bunch crossing
 - Attempting to model of low energy looper density

The Role of the BCM

- Allow to protect equipment during instabilities/accidients
- Provide fast feedback to the machine for optimization of beam conditions
- Provide high time resolution diagnostics for beam accidents/ bad background conditions

If all is well, the BCM should a completely redundant system: ie the LHC machine protections should be more than sufficient. However: Machine protection group strongly encourages us to implement a system within the experimental volume.

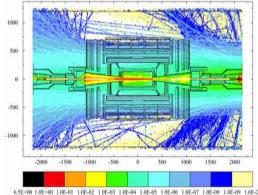
Beam Conditions Monitoring

Operational requirements

- BCM to be designed for both beam monitoring and as a protection system for the inner tracker region of CMS
- Completely reliable system
- Measure beam conditions under standard operating conditions
- Monitor the beam for the onset of unsuitable beam conditions
 - Identified by increased per bunch crossing flux
 - Post mortem analysis required:

=>Time stamping on the bunch crossing time scale

- Monitor the environment during the Pilot Run
- Monitor the inter-bunch spacing during normal operations
- Survive the extreme burst irradiation conditions
 associated with beam abort failures
 - ie fluxes of $\sim 10^8$ per cm² per bunch crossing



BCM Front end requirements

Should be fast

- Has to be able to handle normal operation hits within 8-10ns
- Sensors AC coupled to amplifers have to restore to baseline under 12ns
- Use Std 40MHz CLK to sync with CMS (assumes intelligent FE electronics)

Should be able to monitor within the inter-bunch spacing

- Restricts the positioning from the IP ie z=12.5ns
- Use 40MHz CLKing, but with inverted clock
- Need to single MIP sensitivity in interbunch spacing

Should provide flexible inputs to the BCM backend

- Adjustable threshold (done in terms of counters)
- Analog pulse amplitude to be sampled

Should be able to see the onset of adverse beam conditions

Should not tie ourselves to particular accident scenarios

Should be able to see normal and startup conditions

Monitoring single 450GeV pilot bunch => Single MIP sensitivity

Should be able to survive unsynchronised beam aborts and other blasts

– FE amplifier protection (for bursts and sustained bursts)

Should have a minimal material budget

– Use existing structures and thermal enclosure at $\eta \sim 4.5$

Difficult challenge: find space for services routing on tracker bulkhead
 Must be reliable

– CMS BCM is to be a 3-fold system

The 3 Component BCM

The BCM must be a simple and ultra reliable system with a dynamic range of

1 to 10⁸ MIPs per cm² per bunch crossing

 \Rightarrow We do not want to require this of a single subsystem

The 3 subsystem being proposed are:

Subsystem 1: The intelligent ammeter approach

- Digitize the DC level coming from a simple sensor
 - Look for sustained time above threshold
 - Needs careful grounding
 - Allows for tunable time-over-threshold window (0.5 to several orbits)

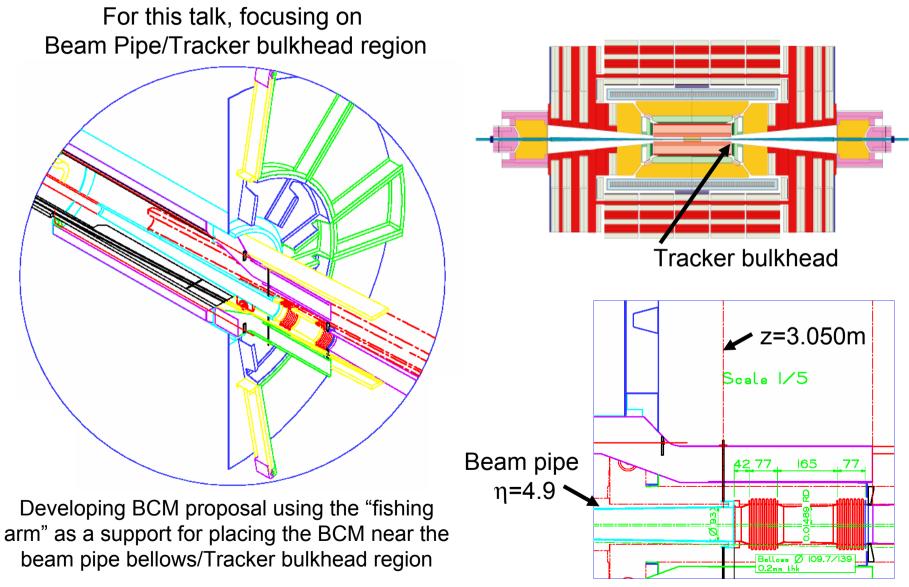
Subsystem 2: Bunch by bunch sampling. Minimal processing

- Simple sensor AC coupled to fast amplifier (~1GHz)
- Pass signal through staggered discriminators to assess levels
- Use discriminator outputs to form logical AND over BCM array
- Feed logical AND into Staggered circular buffers (different time scales)
 - Trigger abort signal on a majority level in buffer
 - Time scales set by active buffer depth (10 bunch crossings to 1 orbit)

Subsystem 3: Fast and full readout

 Use more complex system based on the CMS Pixel electronics: Sensitivity: 0 to ~10 MIPs per bunch crossing

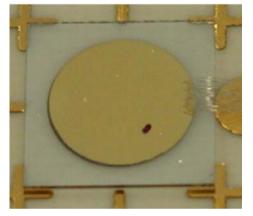
Location, location, location



BCM sensors: CVD Diamond

CMS BCM has opted for synthetic CVD Diamond

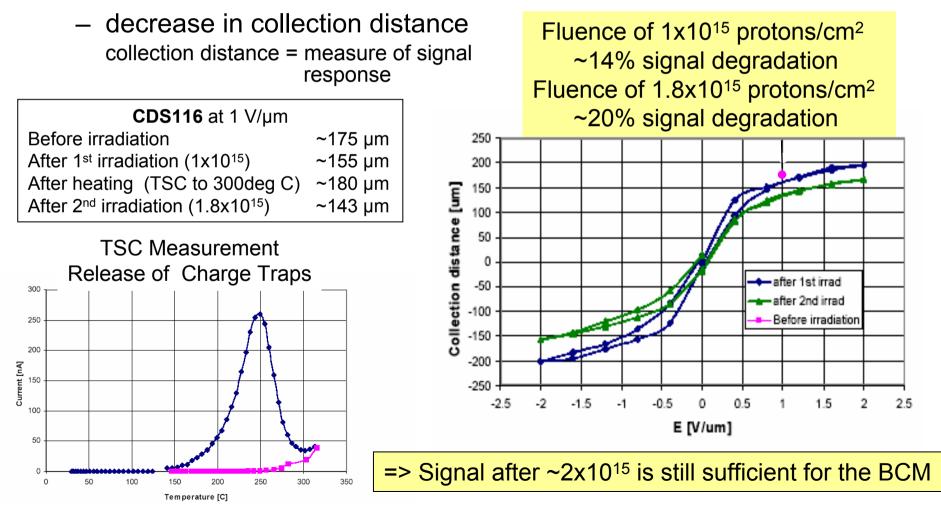
- Sensor does not require cooling
- Fast signal response: sub nano-second risetime
- Fast recovery: FWHM of MIP signal: O(2ns)
- Sensor Response covers required dynamic range
- Radiation tolerance



- ~20% loss in signal after charged hadron flux of $2x10^{15}$ cm⁻²
- Used poly-crystalline CVD diamond (PCVDD)
 - Commercially available in 1cmx1cm and 300 -500 μm thick
 - For $300\mu m$ thick sensor ~ 7000 electrons/MIP: Sufficient for BCM
 - Nominal signal collection done with bias of $1V/\mu m$
- Single Crystal CVDD: A possibility
 - Not easily available yet (size and cost). Expect developments in 2005.
 - No grain boundaries => Significant increase in signal, increased efficiency
 - For $300\mu m$ thick sensor ~ 18000 electrons/MIP. cf 22500 for Si
 - Lower Bias voltages (<100V)

Radiation damage in PCVD

- Use a simple pragmatic evaluation of radiation damage
- Measure sensor response to ⁹⁰Sr characterisation stand



Evaluation of PCVD: East Hall Test Beams

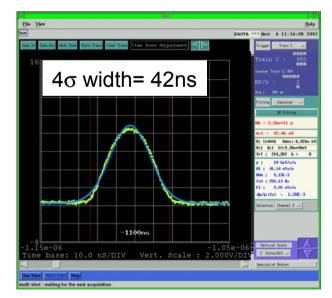
- Use the PS East Hall for testing PCVD sensor response
- Use dedicated "fast extraction" beam structure to test response and dynamic range of PCVD Diamond to particle bursts
 - Only possible due to Michael Hauschild (PS Coordinator) ,Rende Steerenberg (PS Operations), Luc Durieu (East Hall Coordinator)
 - Used both T7 Primary zone and T7 Secondary Zone
 - Also used T11 for calibration and cross check work

T7 Primary Beam:

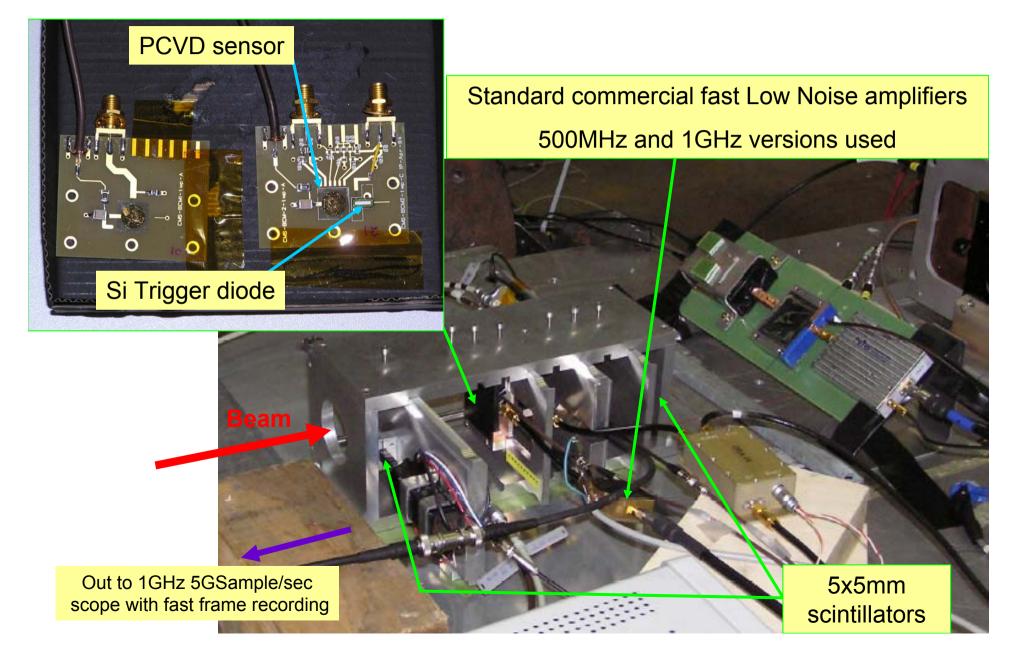
24 GeV protons **Intensity**: $8x10^{11}$ protons per spill Flux on PCVDD: 2.2 x10⁸ protons/cm²/spill Time structure: ~Gaussian. σ ~10.5ns

T7 Secondary beam:

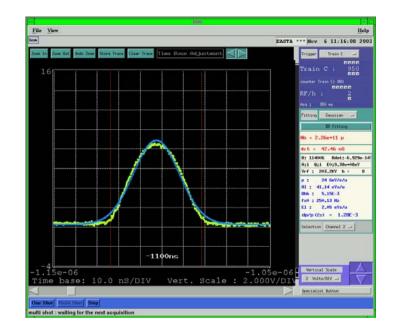
1-10 GeV protons/ pions (selectable) 60:40 ratio of p: π^+ Flux: max ~5x10⁶ protons/cm²/spill

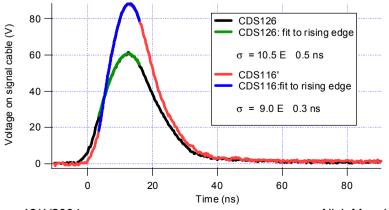


Evaluation of PCVD: East Hall Test Beams



The primary beam: 2.2x10⁸ protons/cm² per spill





Single	pulses	from	diam	nond
	·			

- Bias on Diamond = +1 V/um
- Readout of signal:
 - 16m of cable
 - no electronics

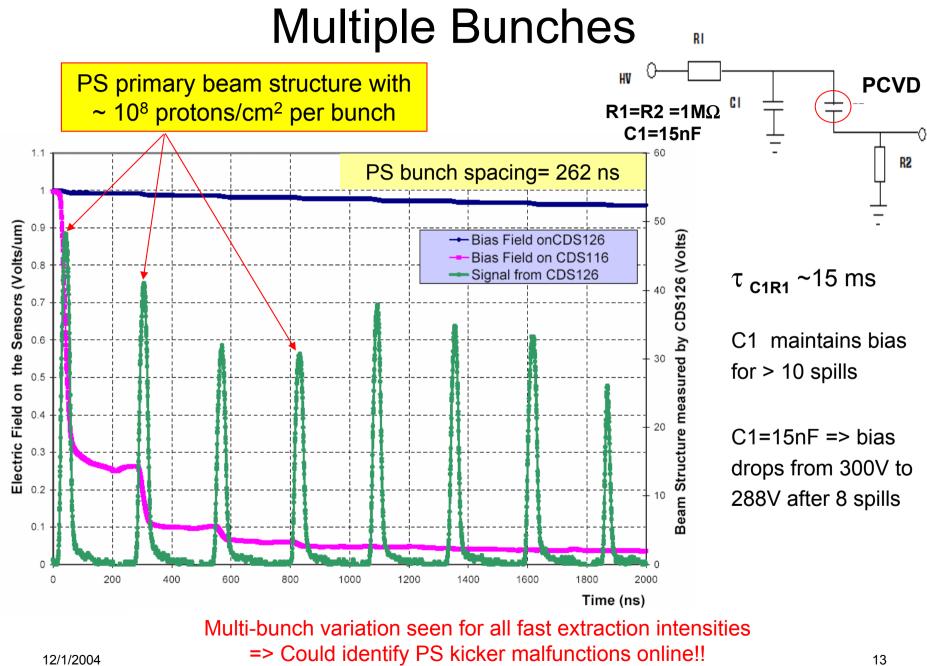
Time response

Fit Gaussian to leading edge of pulses

- σ (CDS126) =10.5 ± 0.5 ns
- σ (CDS116) = 9.0 ± 0.3 ns
- $\sigma(PS)=10.5$ ns with~6% distortion from the signal cable
- Output Signal in worst case scenario
- Signals from sensors are very large
 - V_max (CDS116) = 88 volts
 - => 1.8Amps into a 50 Ohm load

Typical CVD leakage current: O(10 pA) => Large signal maps to large FE load!!





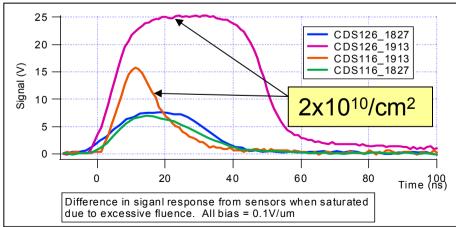
PCVDD Response and Linearity

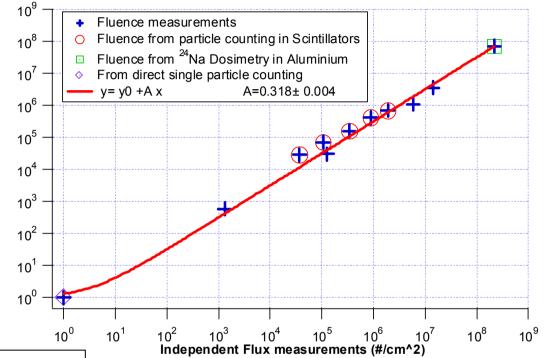
CVD Flux measurement (#/cm^2)

PCVDD response to beam is approximately linear over 10 orders of magnitude!!

- Based on several CVD samples
- Includes irradiated samples (fluence of 1.8x10¹⁵)

•Cross checked with indep measurement of fluence





Linearity (above) extends to 10¹⁰

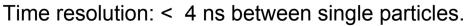
Problem with measurement: Reservoir capacitor insufficient to maintain bias field => signal current plateaus until charge is drained off

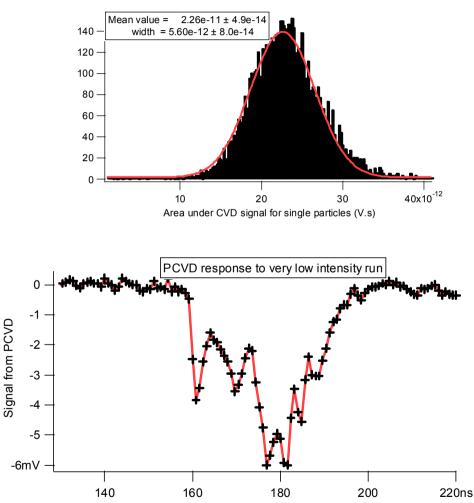
Low Flux Measurements

 Single particle PCVDD response MIP signal: ~2.3x10⁻¹⁰V.s

Fast extraction

- Look at ultra-low intensity run
- From calibrated TLD Dosimetry Spill flux= 600 particles/cm²
- => number of particles through detector
- From TLD measurements
 Number expected = 6.2 particles
- From multiple/single signal area ratio
 Number measured = 5.1 particles
- From flux measurement on PCVD signal
 Number measured = 5.3 particles



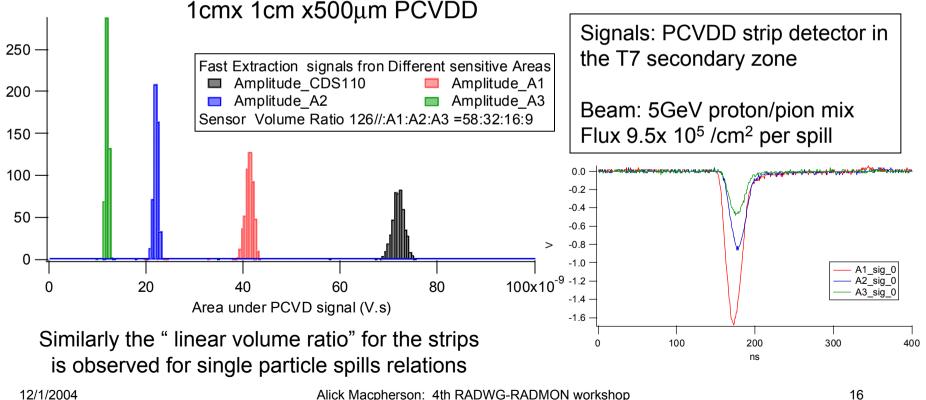


Time structure of beam spill

Different Sensor Volumes

PCVDD strip detector placed parallel to beam, beam traverses multiple strips

- PCVDD behaves as expected •
- Under fast extraction, signals proportional to active volume of sensor ۲
 - => Can reliably use structured metallization on a



Looking for MIPS

<u>CMS BCM:</u> Scenarios that require single particle sensitivity on a bunch by bunch basis

- Monitoring during the Pilot Run
- Monitoring the Inter-bunch spacing

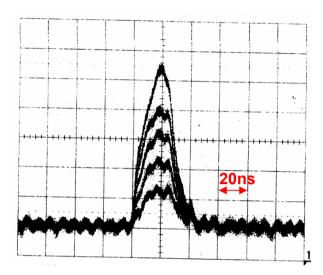
Single particle detection design choices for subsystem 3:

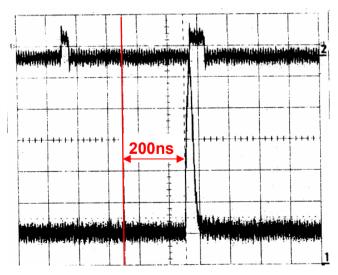
- CVD diamond in "Standard" position perpendicular to beam, signal amplified by fast low noise amplifier.
 - Simple, but difficult to get decent S/N ratio. MIP in 300um PCVD => ~50uV signal
- CVD diamond parallel to beam, signal amplified by fast low noise amplifier.
 - Simple, decent S/N ratio. Use commercial amplifiers.
 - Reduced cross-sectional area of sensor
- Pixelized CVD sensor mounted in perpendicular to the beam.
 - More Complicated. Utilise complete CMS Pixel FE electronics => analog readout + fast out for bunch by bunch monitoring. Fully time stamped monitoring.
 - Location and services are key constraints (now under review)

Fast Out of CMS Pixel Chip

CMS Pixels Fast-Out

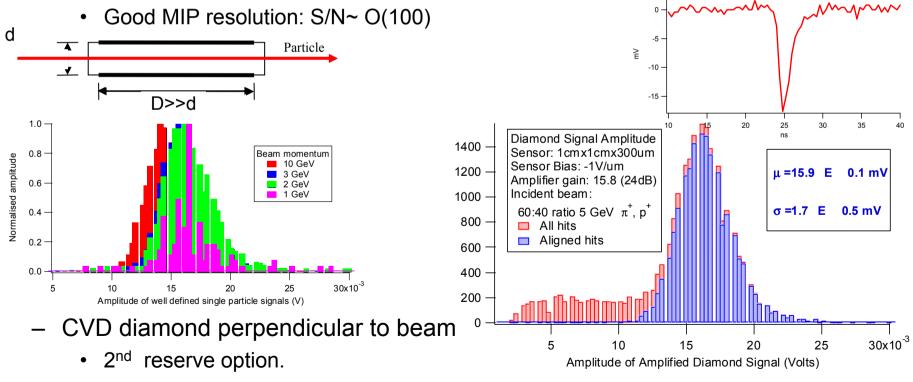
- Designed in Pixel chip to provide a Level 1 trigger input to CMS
- Treats the 8mmx8mm pixel array as 26 8mmx300um strips
- Gives fast-out signal if 1 or more "strips" is hit
- Multiple hits on a strip count as one
- •DACs set the scale of the analog levels
 - Have tested 5 analog levels
 - Level increments tested:
- 1 and 2 hit "strips" per chip
 => Per bunch crossing, have a range of 0 to 10 hit sensitivity on 8x8mm active area
- Can retain full CMS Pixel chip functionality
 - =>Standard pixel readout (at lower rate),
 - Maskable pixels and "strips",
 - Adjustable pixel thresholds etc
 - Time stamping





Single particle detection design choices

- Pixelized CVD sensor mounted in perpendicular to the beam.
 - Preferred design choice.
 - Currently evaluating mechanical/logistical constraints.
 - Potential for co-development with CVD-pixel luminosity monitor
- CVD diamond parallel to beam, signal amplified by fast low noise amplifier.
 - Backup single particle monitor solution.
 - Advantage: Use same amplifier readout chain as subsystem 1



The BCM Backend

General Comments

 The BCM Backend Has to be a standalone system data logging, online updates and post mortem analysis abilities

Subsystem 1: The intelligent ammeter approach

- Not difficult to implement: Mostly software and controls issues

Subsystem 2: Bunch by bunch sampling. Minimal processing

- Build from commercially available components
- Need dedicated logic hardware and interface to CMS DCS and DSS
- Need dedicated conditioning of BCM output into LHC beam abort interface

Subsystem 3: Fast and full readout

- CMS Pixel solution
 - Need to understand bump bonding of CVD to pixel chips
 - Logistics of services and optical readout of BCM signals need to be sovled
 - Spy events. Readout pixel chip at spy rate. Need to understand if this could/should be integrated into standard data stream
- PCVDD parallel to the beam
 - Use BE similar to subsystem 2 but with dedicated online display

Observations and outlook

Comments: Extensive PCVDD sensor testbeam at the PS has just finished

- Very successful BCM programme: Large amount of data still to process
- Linearity of PCVDD sensors established over ~9 orders of magnitude
- Time response under beam monitor condition found to be sufficient
- Reproducibility of sensors response after repeated "worst case" beam spills
- Sufficient signal integrity after exposure to radiation levels comparable to that expected by BCM over 10 year lifetime of the experiment

Observations and outlook

- Now satisfied with choice BCM sensor, and availability of fast amplifiers
- Choice of 3-fold system key providing reliable system that addresses the requirements imposed by CMS Technical Coordination and CMS integration
- Subsystem 3 (pixelised CVDD) makes sense based on the CMS Pixels fast-out signal line. But it's not trivial in terms of services and readout integration
- Identify subdetector protection procedures now that LV power supplies and cabling specified.
- CMS BCM Outlook
 - Q1 of 2005: Finish testbeam analysis, Outline mechanical design of BCM Q2 of 2005: Preliminary design of backend. Finalise cabling. Prototype subsystem 3 Mid 2005: Reassess status and review

Spare stuff

Measurements on voltage overshoot (fast)

