



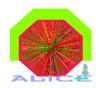
Fast track reconstruction for the TPC

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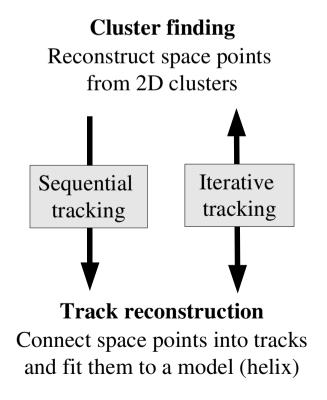
Track reconstruction in the TPC

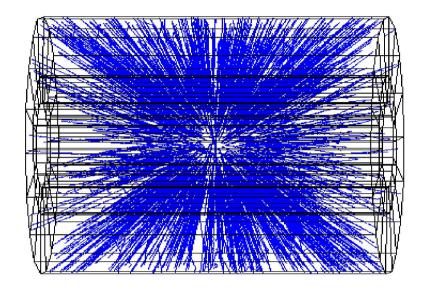
TPC occupancy:

estimation:

 $dN_{ch}/d\eta$ =8000 : **20000** tracks in the TPC

two approaches:

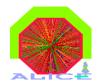




- Sequential tracking
 - Cluster finding (weighted mean)
 - Track follower
- Iterative tracking
 - Hough transform on Raw ADC-Data gives track candidates
 - Cluster fitting with respect to track parameters



Sequential tracking – the algorithms

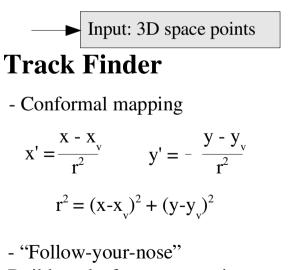


► Input: ADC-sequences above threshold

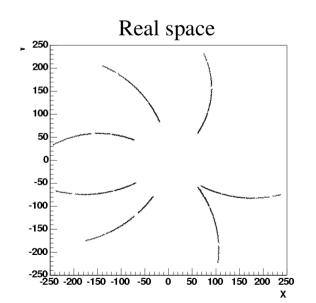
Cluster Finder

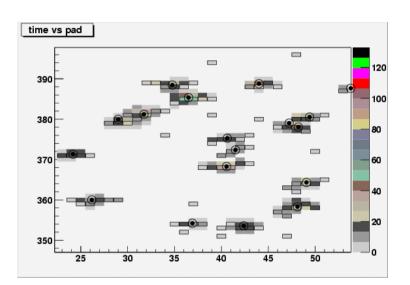
- Simple sequence matching between neighboring pads
- 2 lists in memory principle: current and previous pad(s)
- Centroids calculated as weighted mean of ADC-values

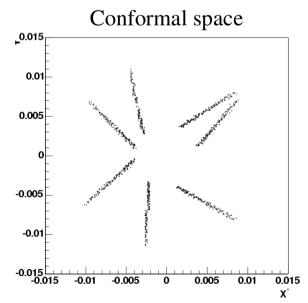
Simple deconvolution scheme: Split clusters at local minima



Build tracks from outer to inner TPC-radius



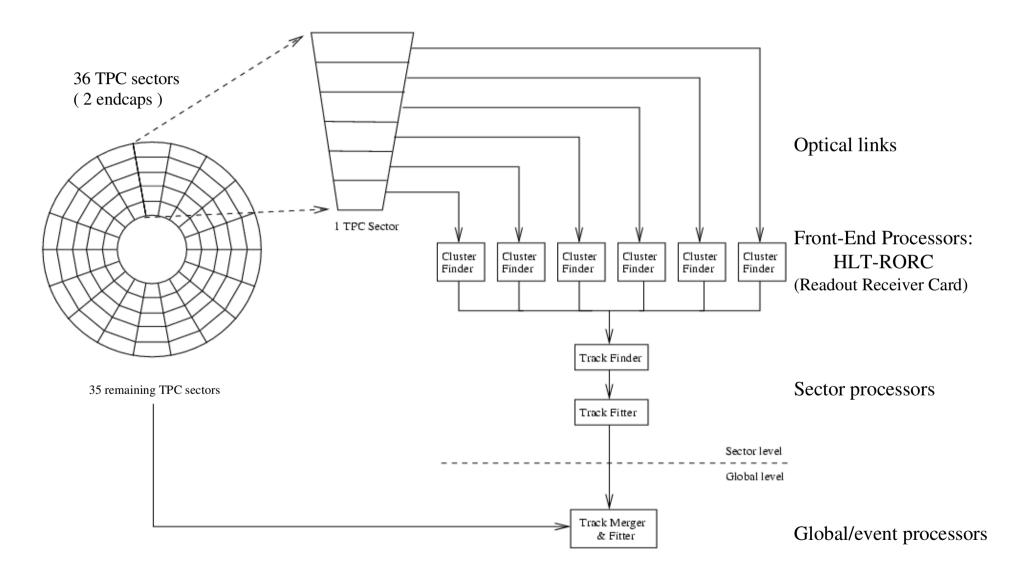






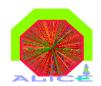
Sequential tracking – dataflow

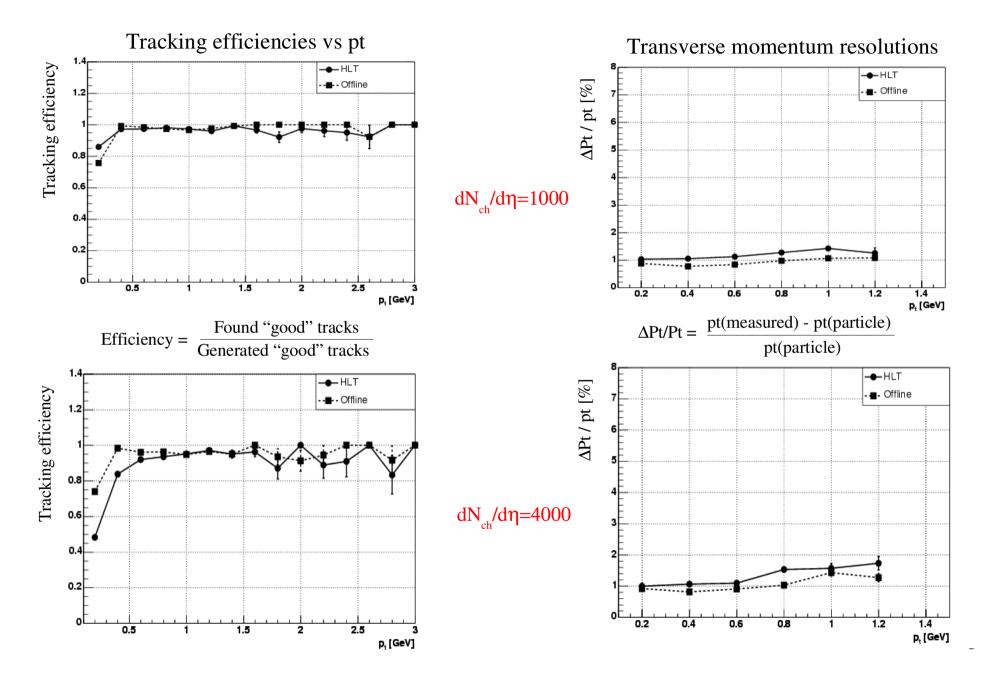






Sequential tracking – performance

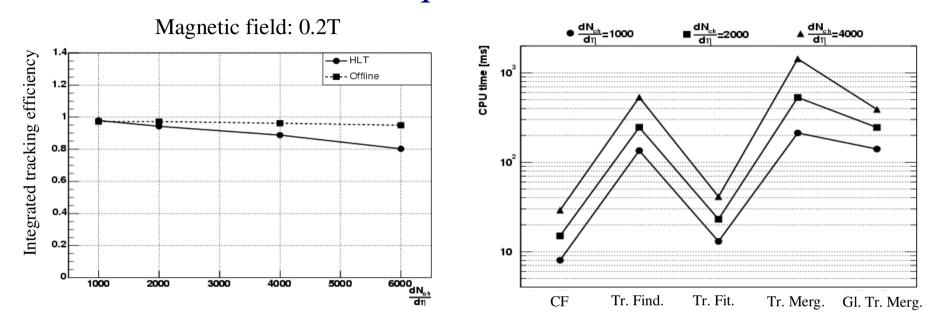








Sequential tracking – performance/ computing requirements

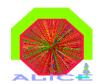


	<u>Pentium III, 800 MHz</u>		<u>Pentium 4, 2800 MHz</u>	
$dN_{_{ch}}/d\eta$	CPU-time [s]	#CPU	CPU-time [s]	#CPU
1000	7.5	1500	3.4	680
2000	14.0	2800	6.3	1260
4000	29.5	5900	13.2	2650
6000	47.3	9460	21.2	4240

#CPU = Equivalent number of required CPUs @ 200 Hz processing rate



Iterative tracking – the algorithms

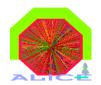


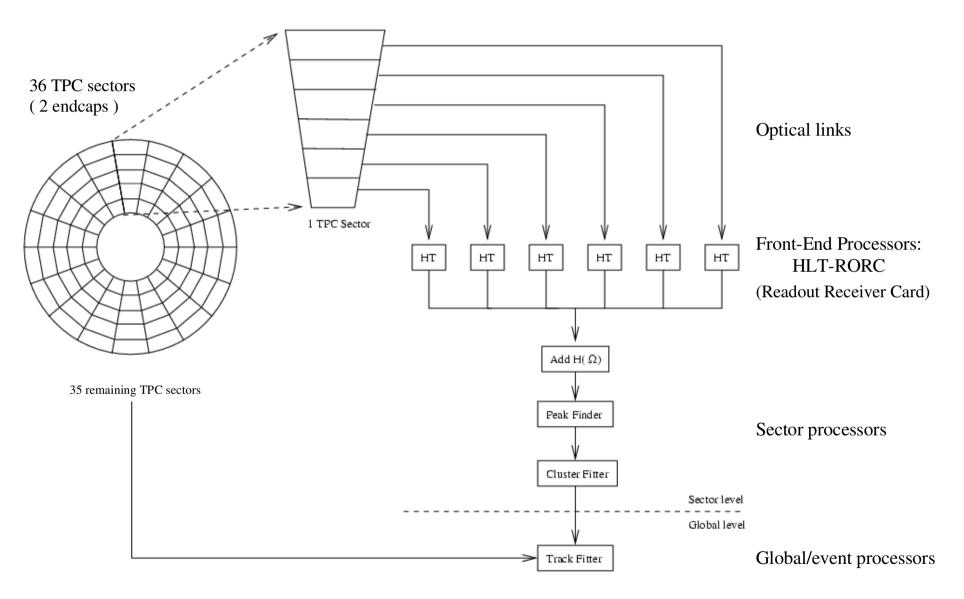
Input: ADC-sequences above threshold TPC Sectors к [cm⁻¹] y **Hough Transform** 0.003 - Apply the circle HT directly $(\mathbf{t}_1 \ \mathbf{\phi}_1)$ Ψ₀₁ 0.002 on raw ADC-data х $(t_2 \phi_2)$ 0.001 - Track candidates corresponds to local maxima in 2D parameter space R = -0.001 Center of curvature -0.3 -0.2 -0.1 0.1 0.2 0.3 w_ [rad] Input: Track candidates Limebin Timebin **Cluster Fitter** 438 2D gauss-fit (5 parameters) - Fit the clusters along the trajectories 436 - position in pad and time - Track parameters provide input - widths in pad and time (keep fixed) 434 parameters to the fit - amplitude 432 - deconvolution is done based on the Initial position (trajectory crossing) knowledge of the cluster shapes ★ Position after fit 430 50 56 52 48

Pad



Iterative tracking – dataflow

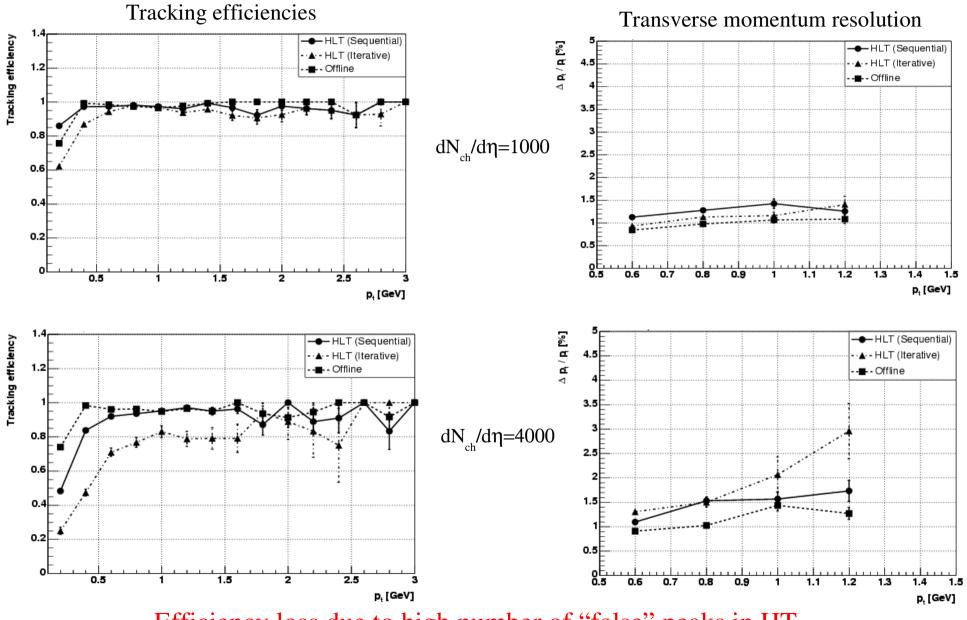






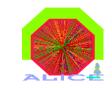
Iterative tracking - performance





Efficiency loss due to high number of "false" peaks in HT





Iterative tracking – computing requirements

- <u>Hough Transform:</u> $(dN_{ch}/d\eta=4000)$
- 3.5 s per sub-sector * 6 * 36
- = 750 s for complete TPC event
- $\longrightarrow 150\ 000\ CPUs\ @\ 200\ Hz\ processing\ rate \qquad (PIII\ 800\ MHz)$
 - Heavy IO-bound algorithm, as extensive and repetitive access to memory is needed (filling histograms).
- Algorithm is however local by nature, high degree of parallelization.
- ongoing development of fast algorithm, C. Cheshkov

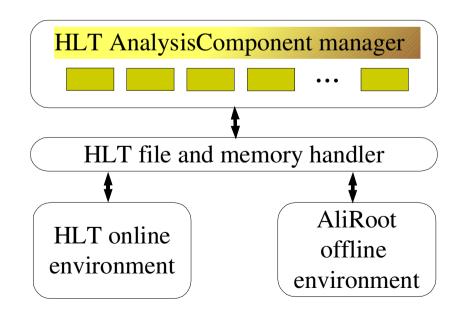
Suitable for implementation in FPGA co-processor on the HLT-RORC.







- Fully implemented and tested
- Analysis components developed within AliROOT
- Data internally organized in simple C structures to minimize overhead
- There is already some kind of abstract interface, the file and memory handler
 - -> connects analysis components to either online or offline framework



However:

 realization of analysis chain in AliROOT still "hand-knitted"

• "user " of online framework needs to know a lot about pub/sub framework to implement components





Issues and open questions

- we have to move from prototype implementations to a "production version"
- need uniform policy how to build an HLT analysis chain applicable to all sub detectors
- analysis component concept
- better separation of transport and analysis components in the online framework





Acknowledgment

- Talk based on work of Anders Vestbø
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