



1

## RICH calibration and alignment status







#### Disclaimer:

CDB is primarily for reconstruction so here presented only things needed for reconstruction, for simulation we need just everything.



#### What affects what ?



- $C_6F_{14}$  Ref. Idx.  $\rightarrow$  ring radius (AliRICHRecon)
- $CH_4$  Ref. Idx.  $\rightarrow$  ring radius (AliRICHRecon)
- $CH_4$  gain  $\rightarrow$  MIP charge cut (AliRICHTracker)
- $QE \rightarrow$  photon cluster weight (AliRICHRecon partly imp.)
- Dead map  $\rightarrow$  the same as above (to be implemented)
- Pedestals  $\rightarrow$  if we want to reapply sigma cut (to be implemented)



#### External info sources



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#### AliRICHRunParam



- P,T for CH<sub>4</sub> applied to each chamber
- T for C6F14: mean value stored; applied for each radiator
- HV: applied to each sector
- 7 objects like "RICH/TPHV/Ch1"
- Used by AliRICHParam
- Not known how to write (DCS)



#### AliRICHQE



- Segmentation corresponding to UV scanner
- 4x4 pads per point
- Stored just once
- Used by AliRICHParam
- 7 spices like "RICH/QE/Ch1"
- Not known how to write (DCDB)



### AliRICHPedestal



- Heaviest object
- Stored 2 times per day
- 7 objects "RICH/Pedestal/Ch1"
- Used by AliRICHParam
- Contains pedestal and threshold
- Reserved value for dead channel (-1)
- Known how to produce
- This might be centralized operation?



### AliRICHGainMap



- Only recalculated object
- Takes statistics
- Not implemented
- Strategy how to use (with respect to HV) not yet settled







- Chambers are rigid
- Only alignable object is chamber as a whole
- Survey stores ref points



#### AliRICHSurvey



- Format not yet fixed
- 7 objects "RICH/Survey/Ch1"
- Used to create initial AliRICHChamber



#### AliRICHChamber



- Contains all geometrical information
- Provides all transformations needed
- 7 objects like "RICH/Align/Ch1"



#### Alignment procedure for translation



# • Trivial as we have external reference (ESD tracks)



### Alignment procedure for rotation



- Use diff versus Pt plots
- Diff is Mip position minus track intersection
- For tilting use x diff
- For inclination use y diff
- For 2 chambers not yet fully tested