

Simulation of Data Flow Architecture in Parallel environment

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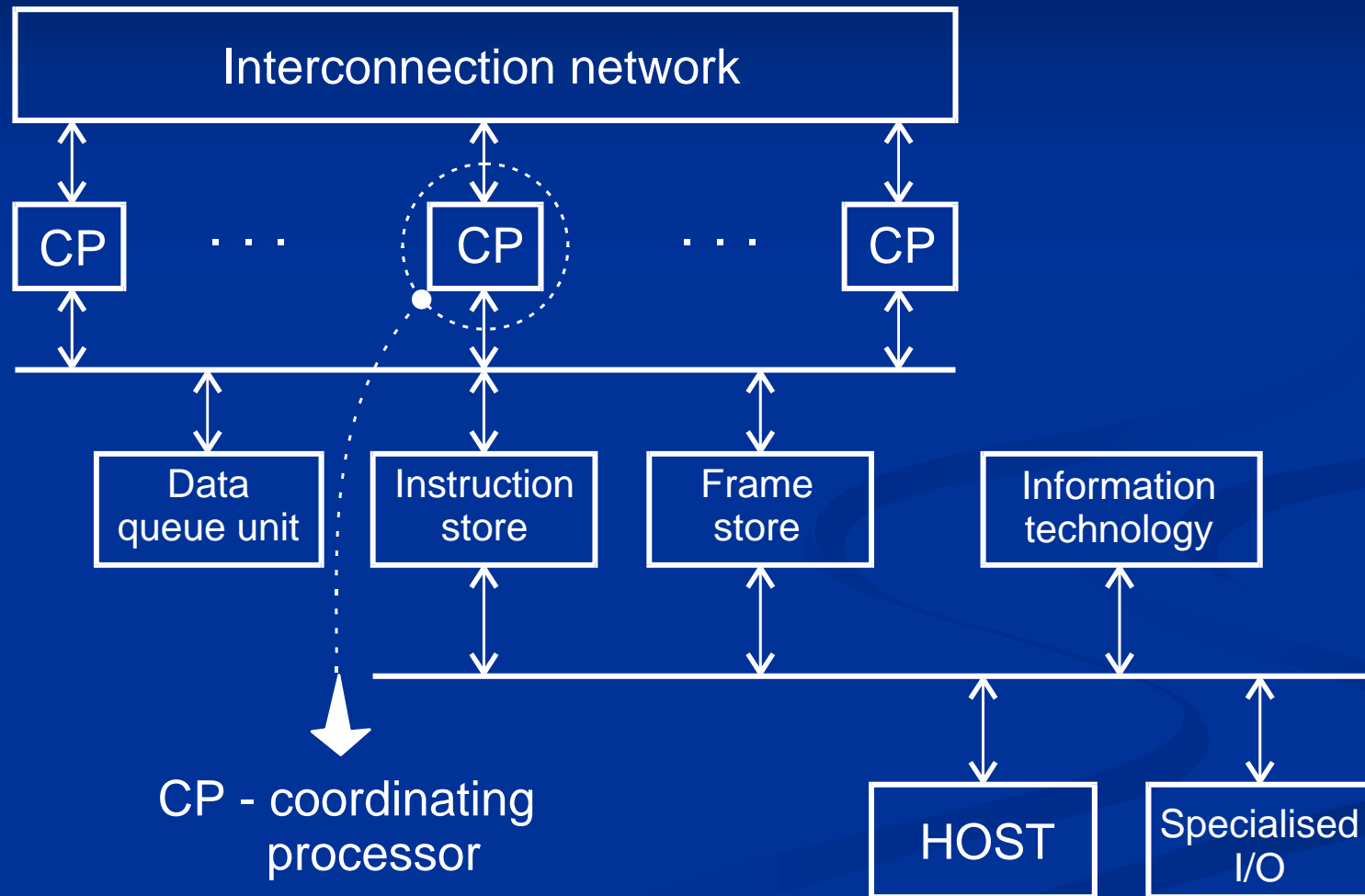


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Introduction

- What is data flow architecture
- Coordinating processors
- Programming model of DF KPI architecture
- Simulation of DF KPI architecture
- Migration to parallel environment
- Using the GRID for simulation

Data Flow Architecture



Program writing

- Description of problem
- Space partitioning problem (BSP Trees)
- Using functional languages
- Functional language HASKELL
- Building data flow graph DFG
- Simple transformation from Haskell to DFG

Example of Haskell code

normalize :: Vector -> Vector

normalize v = (Vector x y z)

where

dist = length v

x = vector_X v / dist

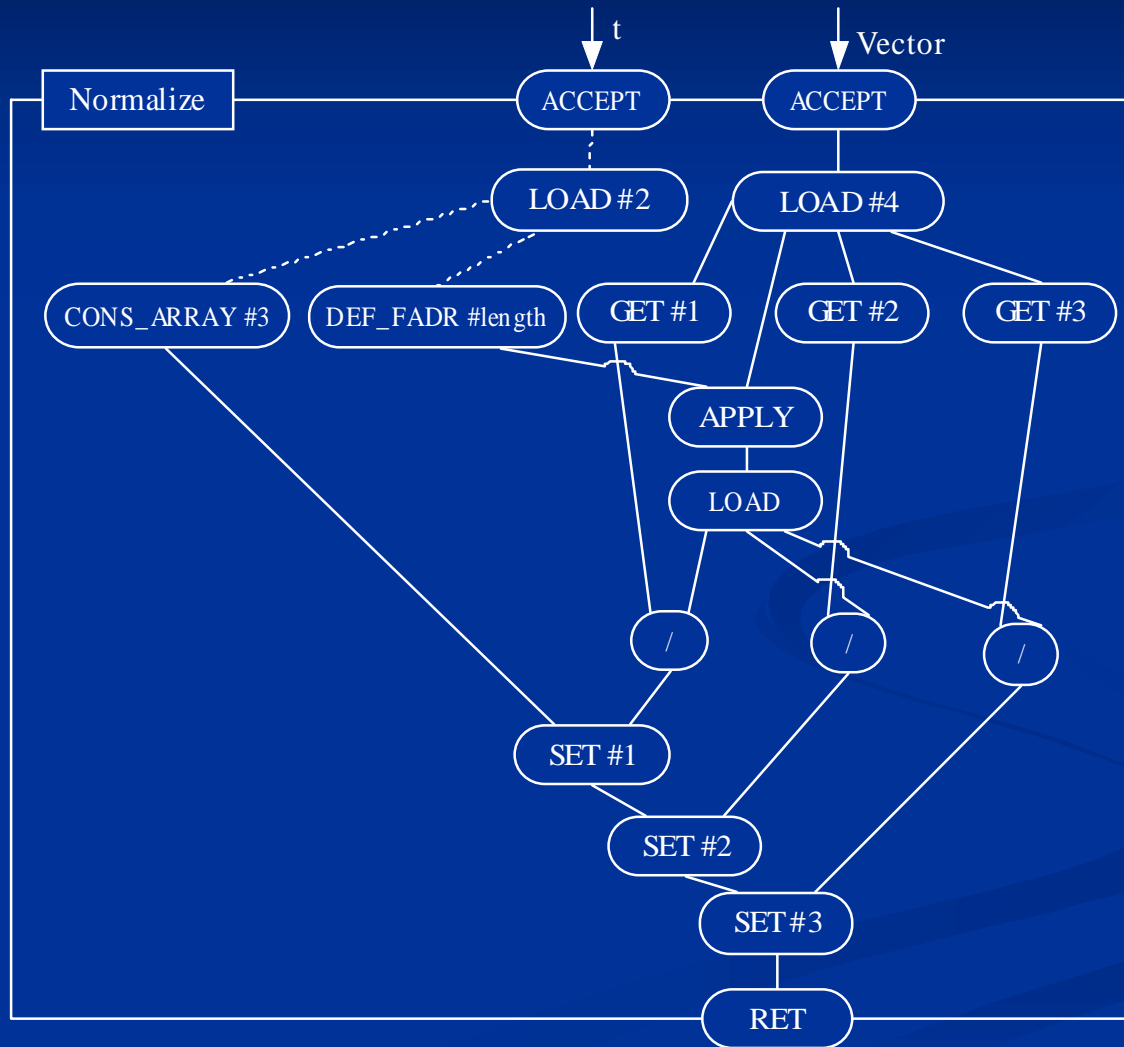
y = vector_Y v / dist

z = vector_Z v / dist

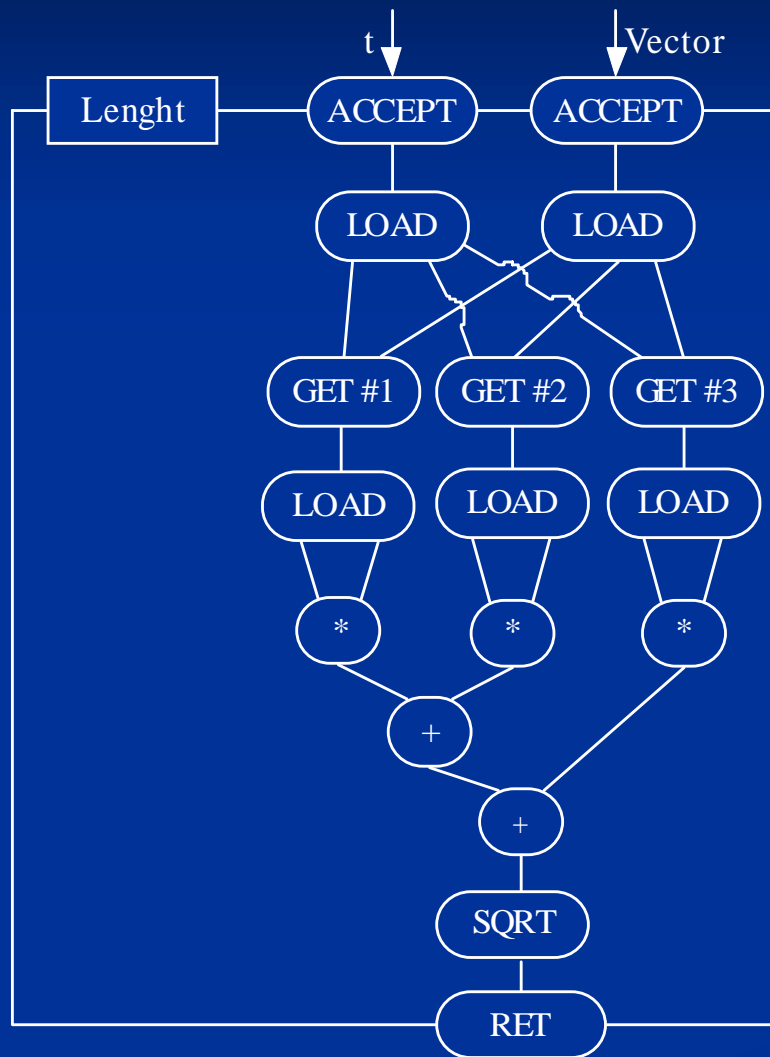
length :: Vector -> Double

length v = sqrt(vector_X v * vector_X v +
vector_Y v * vector_Y v +
vector_Z v * vector_Z v)

DFG of function Normalize



DFG of function Lenght



Example of Haskell source code:

length :: Vector -> Double

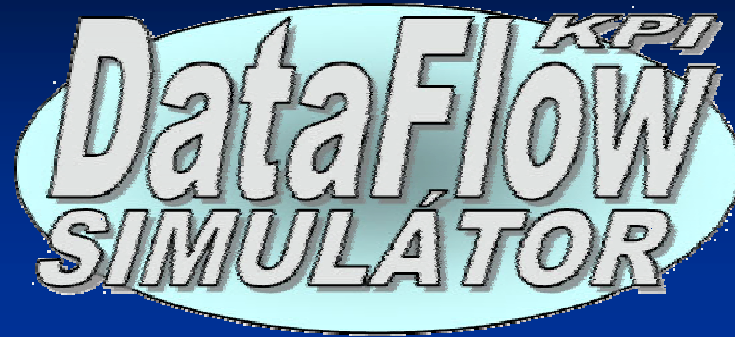
**length v = sqrt(vector_X v * vector_X v +
vector_Y v * vector_Y v +
vector_Z v * vector_Z v)**

Simulation tasks

- Emulation of instruction set
- 32 instructions (operators)
- 5 stages in coordinating processor
- Memory system – DQU, FS, IS
- Matching vector – MV
- Structures (array, list, tree)

Migration to parallel environment

- The precise simulator it is possible to obtain by using:
 - Grid solution
 - Cluster solution
 - Tightly coupled multiprocessor computer
- Coordinating processors = one node
- Communication traffic between coordinating processors



Questions ?

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