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ALICE T0 detector

Alignment and Calibration  
status



# Outline

- T0 detector
  - DBs
- Alignment
  - Status
  - Outlook
- Calibration
  - Status
  - T0 preprocessor
  - Outlook

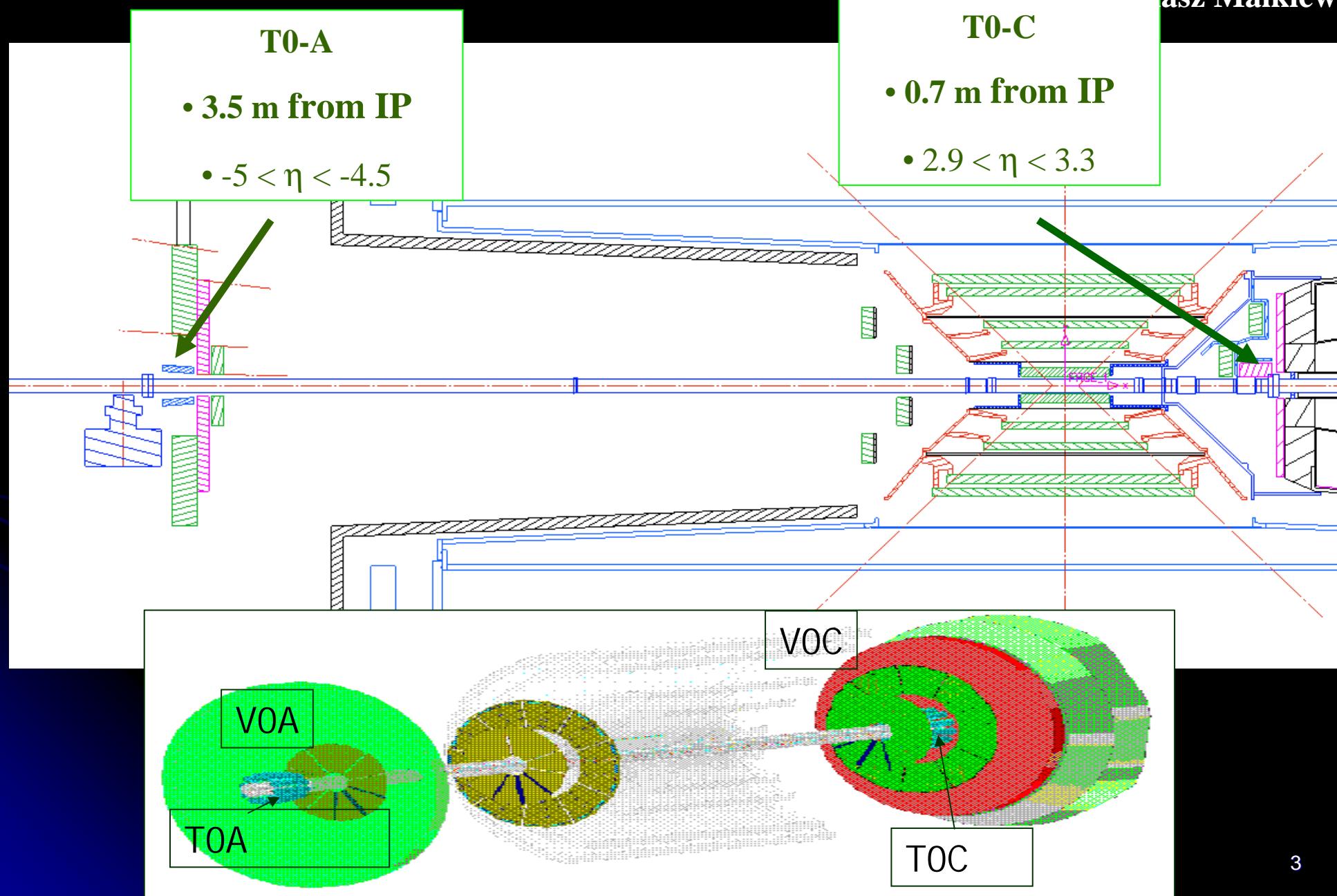


4.10.2006

# T0 detector in ALICE

ALICE Offline week

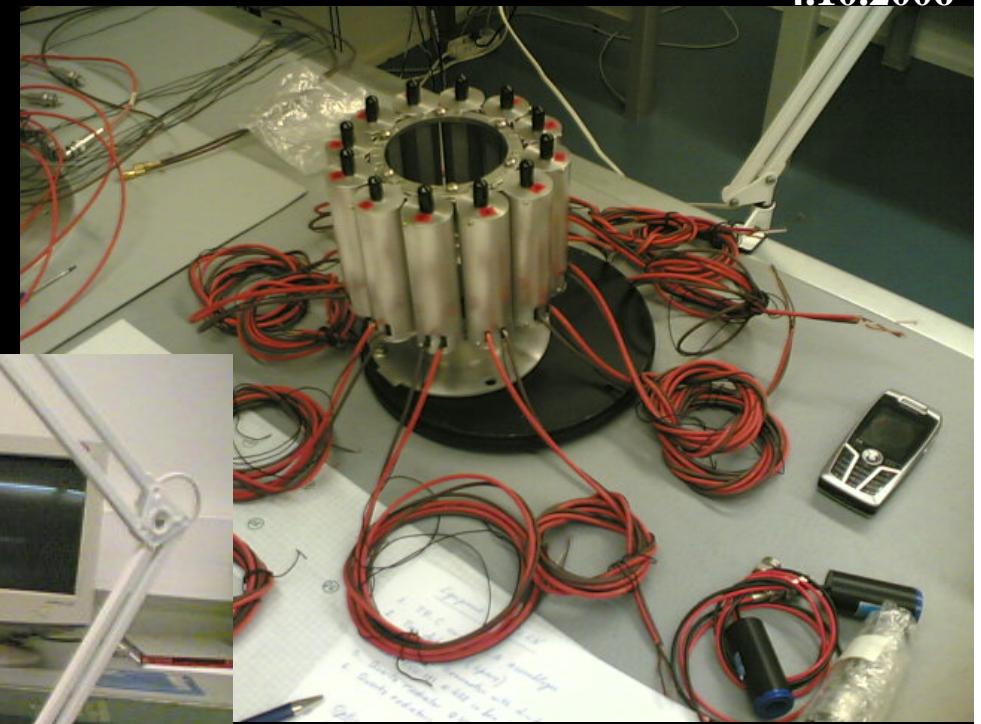
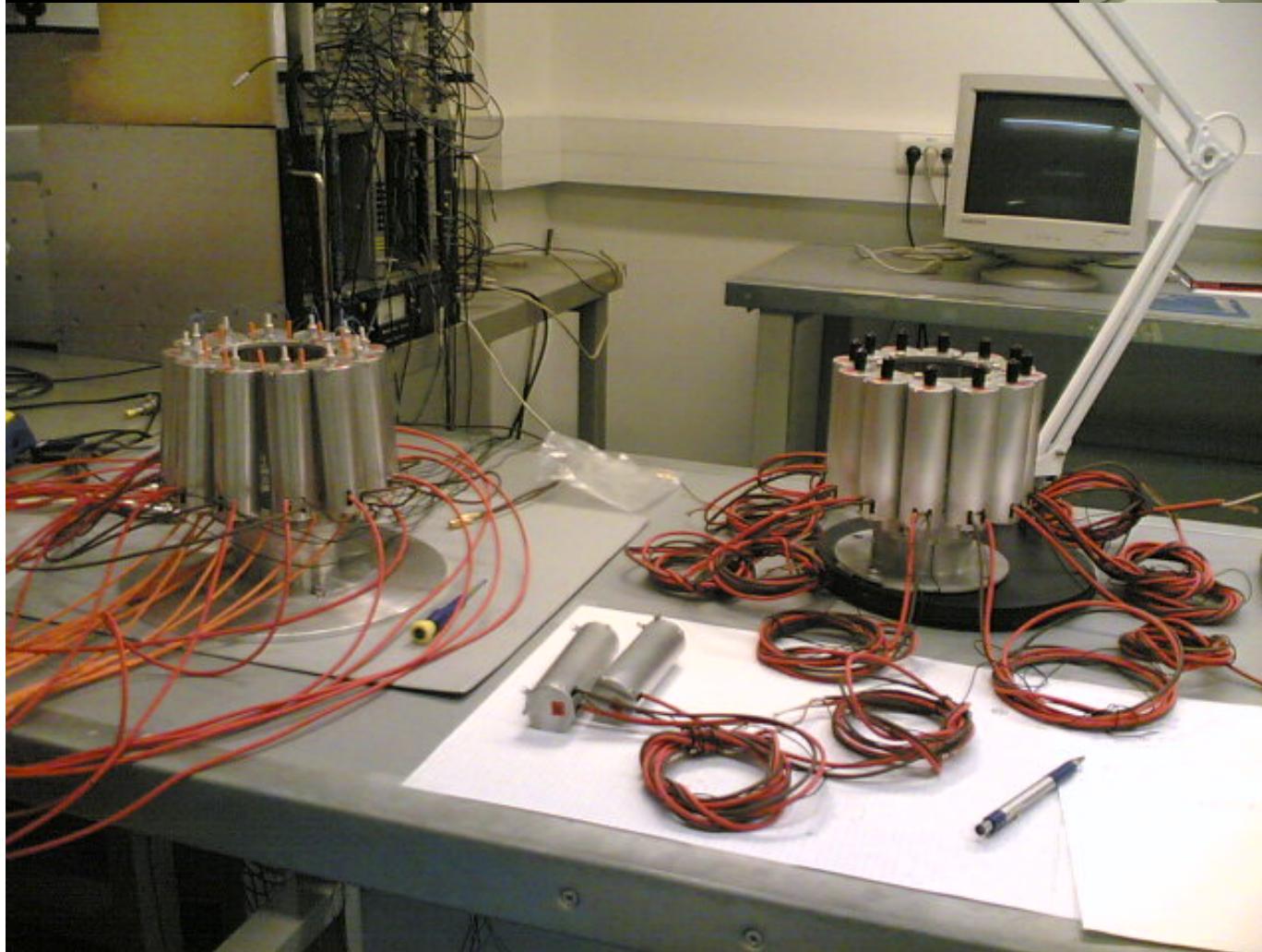
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4.10.2006

# T0-A assembled 21.09.2006





# T0 detector milestones

T0-A commissioning (beam run at CERN)	October 2006
<b>T0-C installation</b>	January 2007
Electronics production completed	February 2007
<b>T0-A installation</b>	June 2007 ?



- DCS:

- Application scope: configuration of systems and devices (modules and channels), front-end configuration (busses, thresholds); Archiving of monitored detectors and devices parameters
- Size: millions of records, Tera bytes

- HLT:

- Application scope: mini-DST like TAG/ESD database for physics studies and offline event selection

Size: up to  $10^9$  events and 30TB per year

- DCDB:

- Application scope: use by individual sub-detector groups and integration, repository and flow management for modules, components and their test data, cables, racks
- Size: millions of records, Tera bytes

- ECS:

- Application scope: inclusion/exclusion of sub-detectors to a partition
- Size: small number of small records

- DAQ:

- Application scope: parameter repository and resources assignment to DAQ tasks: configurations (current and stored), run parameters (current and stored)
- Size: possibly large number of small records

- Trigger:

- Application scope: repository for trigger classes (input to CTP), definition of trigger masks

Size: large number of small records

- Alignment and Calibration Database

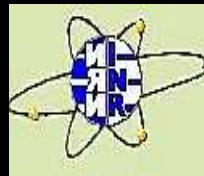


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# Manpower

Alla Maevskaia



*Institute for Nuclear  
Research Moscow  
Moscow Engineering Physics  
Russia*

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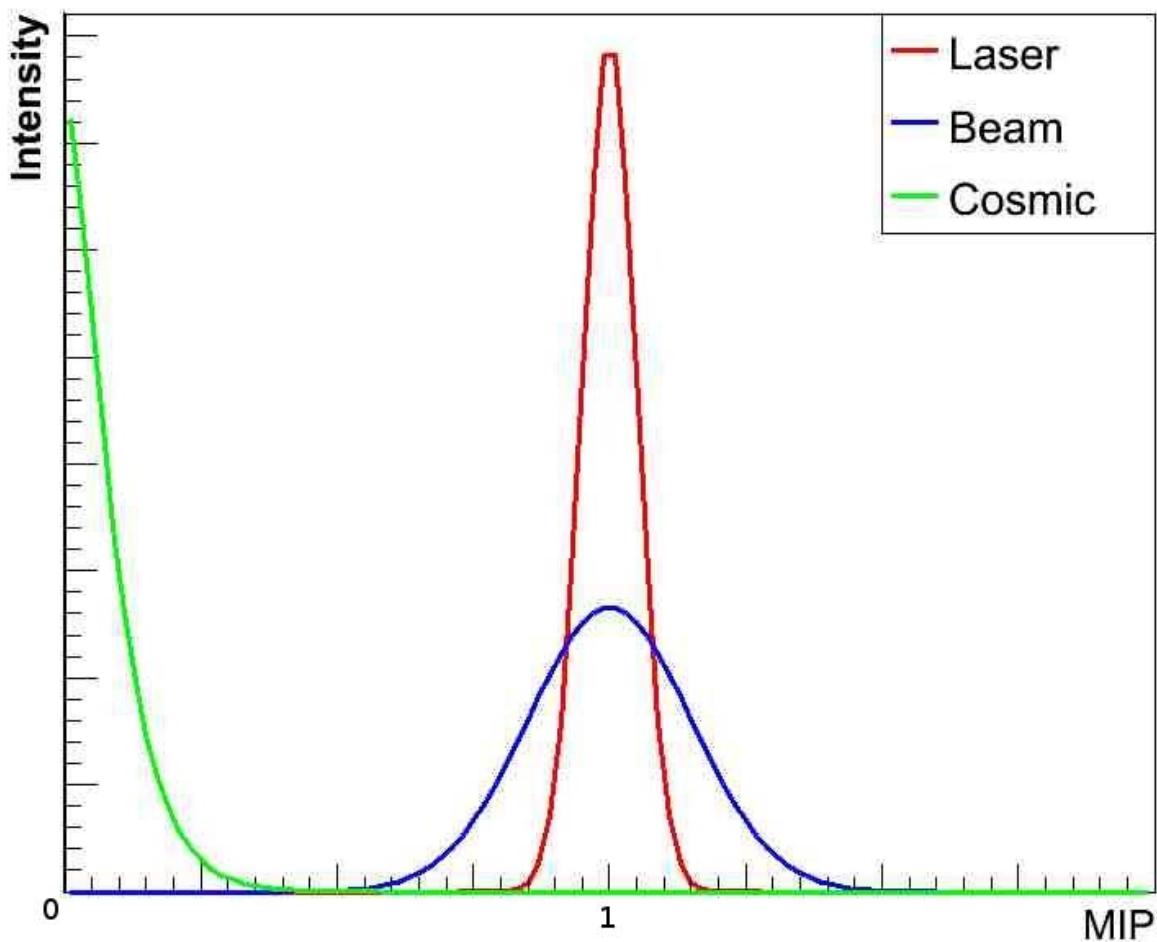


*University of Jyväskylä  
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Michał Oledzki



# T0 signal

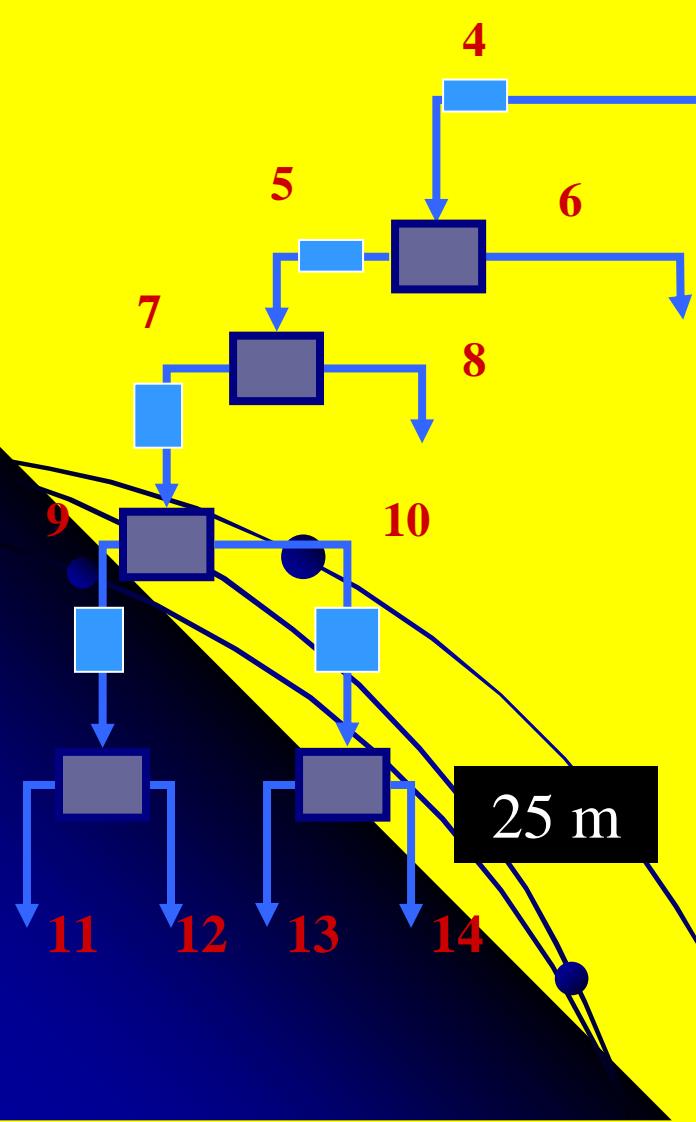


T0 signal w.r.t. ?

- Triggers:
  - BC 25 ns
  - L0 ~ 1.2  $\mu$ s
  - L1 ~ 5  $\mu$ s



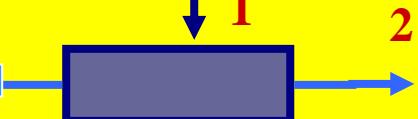
# T0 Laser Calibration System



**Picosecond Injection**  
Laser PIL040G, 408 nm

SM patchcord

**Variable Attenuator**  
48AT-0-FC-0-A11-01



**Maximum light output**  
(in MIP equivalent):

1 - 22000	8 - 900
2 - 9500	9 - 240
3 - 9600	10 - 220
4 - 9550	11 - 67
5 - 2800	12 - 66
6 - 2700	13 - 90
7 - 800	14 - 75

**Optical Splitter**  
FOBS-12P-111-50/125-  
MMM-405-50/50

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**Fused Splitter**  
FOBS-12-333-SSS-400-50/50

**FC/PC Adaptors AD31ZP4N**

**SM patchcord**

**MM patchcord**



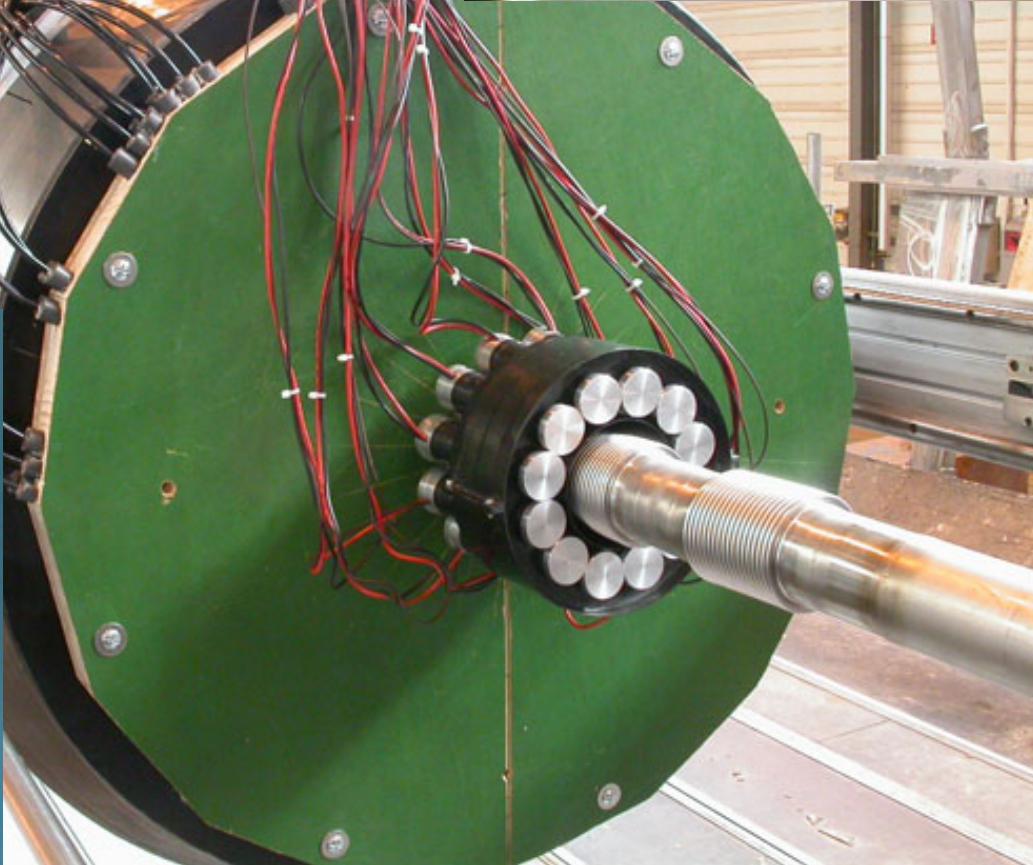
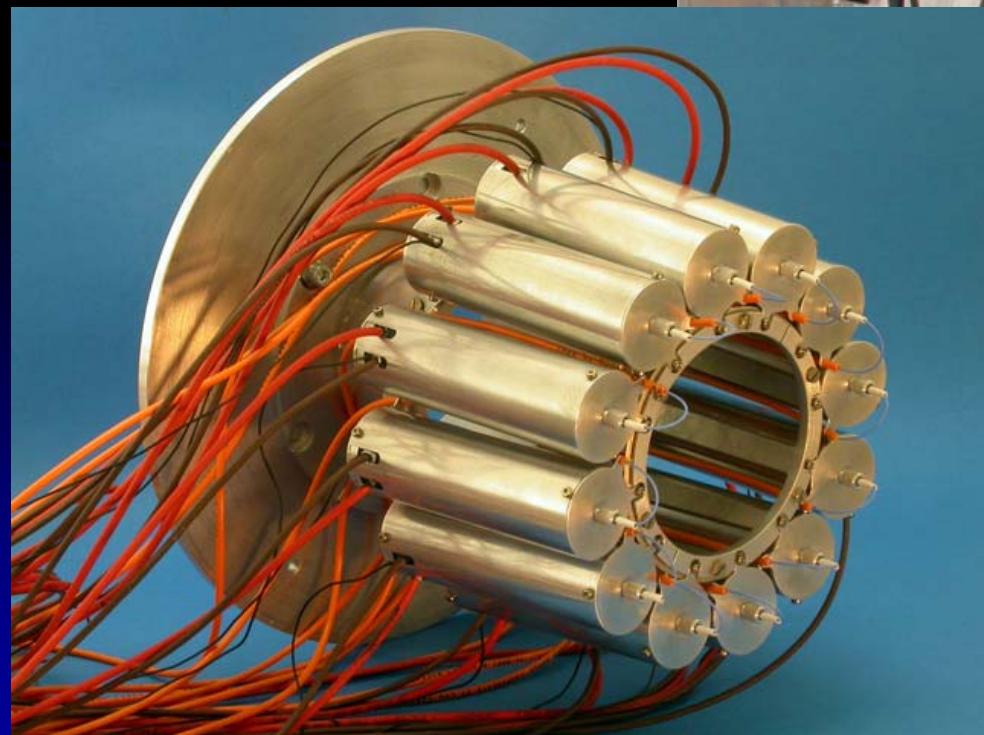
# T0 alignment status

- ❖ Optical survey – decision in Oct. 2006
  - ❖ T0-A and T0-C: fiducial marks

- ❖ Residual misalignments
  - ❖ max shift in cm w.r.t. Global RS:  
**Double\_t sigmatr = 0.05**
  - ❖ max rot in degrees w.r.t. Global RS:  
**Double\_t sigmarot = 0.3**

# Laser Survey

- survey during installation
- reference
  - global RS
  - C-side  $\rightarrow$  muon
  - A-side ?





# T0 outlook

## Alignment

### - Laser Survey

- Provide symbolic volume names
- AddAlignableVolumes



# Calibration DB – current status

T0 Calibration procedure

Calibration class (AliSTARTCalibData)

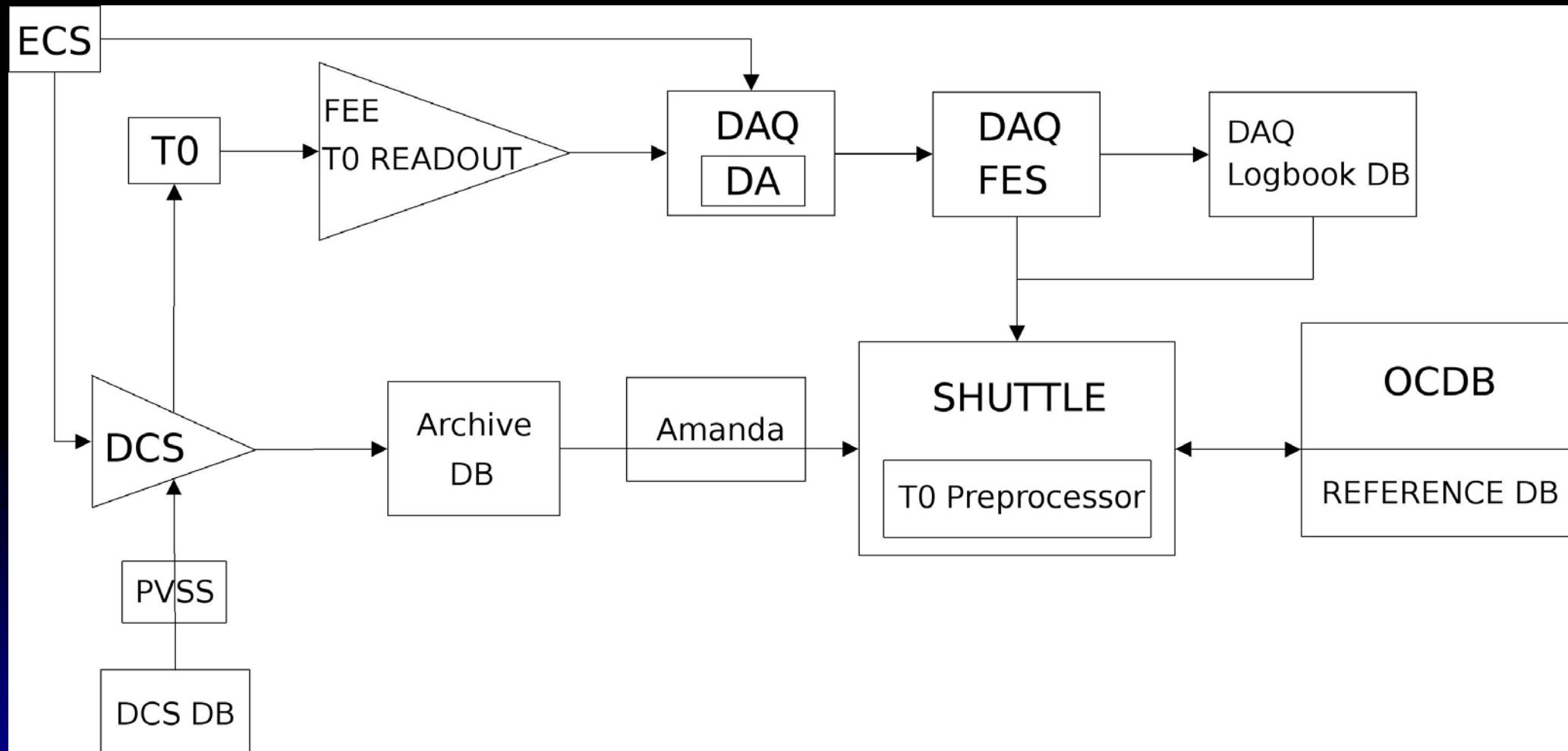
adding new methods:

SetTime(Float\_t \*signal, Float\_t \*delay)

T0 Preprocessor class



# Calibration procedure





# T0 Preprocessor

AliSTARTPreprocessor

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```
UInt_t AliSTARTPreprocessor::Process(TMap* dcsAliasMap )
//DCS
TString aliasName =Form("T0HV%d", j);
aliasArr = dynamic_cast<TObjArray*> (dcsAliasMap->GetValue(aliasName.Data()));

//DAQ
const char* TimefileName = GetFile(kDAQ, "TIME", "LDC0");

//Calculate time
calibdata->SetTime(numbers, hv_time);

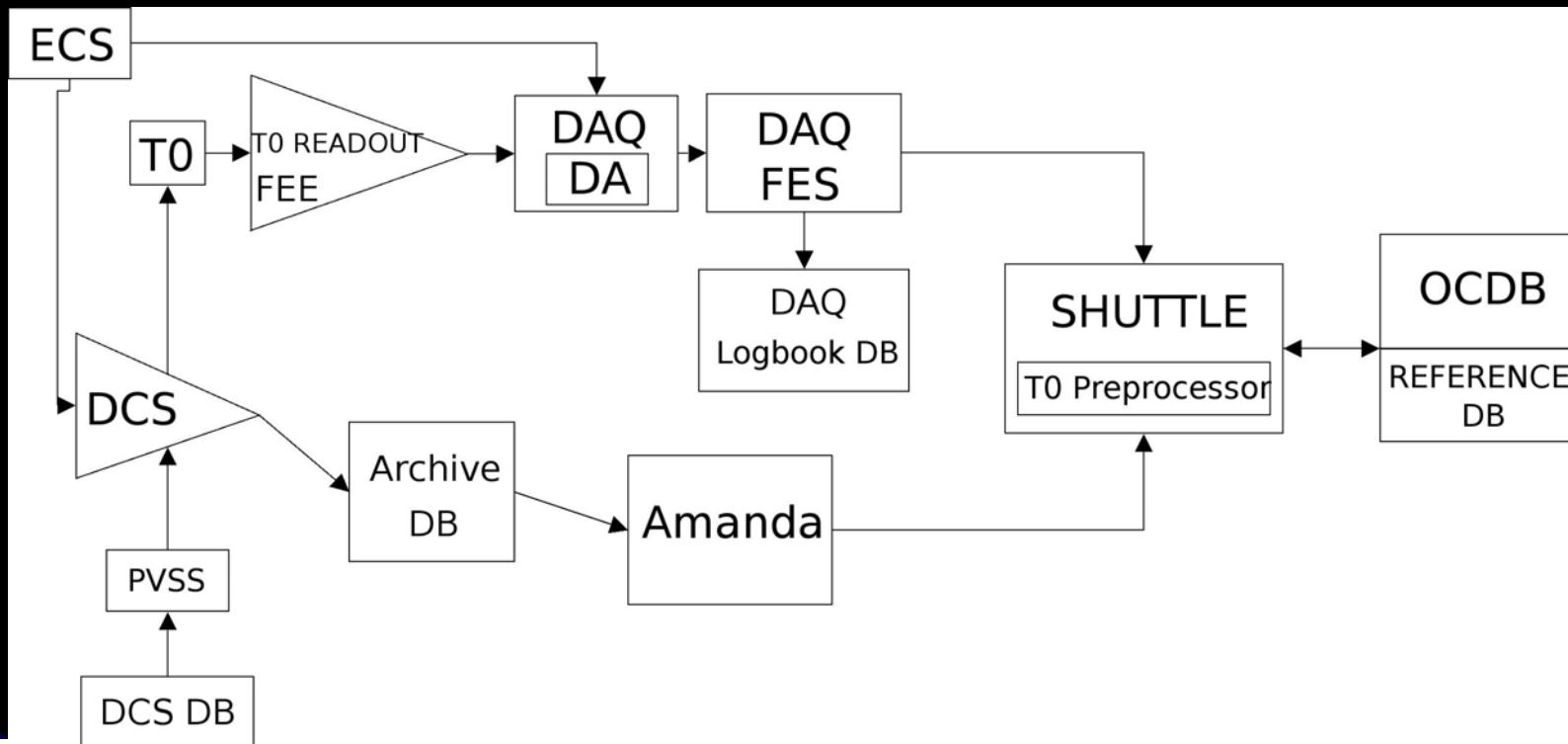
// Put time to OCDB
UInt_t result = Store("Calib","Data", calibdata, &metaData);
```

AliSTARTCalibData

```
void SetTime(Float_t* time, Float_t* delay);
void SetTime(Int_t channel, Float_t val)
void SetAmplitude(Int_t channel, Float_t val)
```



# T0 outlook Calibration



- AliSTARTPreprocessor
- AliSTARTCalibData
- Use case (1 and 4 ?) to be confirmed

Thank you for your attention!